# On the topology of $\mathcal{H}(2)$ 

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## Translation surface

## Definition

Translation surface is a flat surface with conical singularities such that the holonomy of any closed curve (which does not pass through the singularities) is a translation of $\mathbb{R}^{2}$.

## Basic properties

- Cone angles at singularities must belong to $2 \pi \mathbb{N}$,
- A tangent vector at a regular point can be extended to a parallel vector field,
- Correspondence between a translation surface with a unitary parallel vector field and a holomorphic 1 -form on a Riemann surface, zero of order $k \longleftrightarrow$ singularity with cone angle $(k+1) 2 \pi$.


## Examples

- Flat tori (without singularities)

- Surfaces obtained from polygons by identifying sides which are parallel, and have the same length



## Notations and terminologies

$\mathcal{H}(2)$ is the moduli space of pairs $(M, \omega)$ where $M$ is a Riemann surface of genus 2 and $\omega$ is a holomorphic 1 -form on $M$ having only one zero which is of order 2. Equivalently, $\mathcal{H}(2)$ is the moduli space of translation surfaces of genus 2 having only one singularity with cone angle $6 \pi$.

## Remark

- The unique zero of $\omega$ must be a Weierstrass point of $M$.
- Every Riemann surface of gennus 2 is hyper-elliptic, and therefore has exactly 6 Weierstrass points.


## Notations and terminologies

We denote by $\mathcal{M}(2)$ the quotient $\mathcal{H}(2) / \mathbb{C}^{*}$ which is the set of pairs ( $M, W$ ), where $M$ is a Riemmann surface of genus 2 , and $W$ is a marked Weierstrass point of $M$.

A saddle connection on a translation surface is a geodesic segment joining two singularities, which may coincide. In the case of $\mathcal{H}(2)$, every saddle connection is a geodesic joining the unique singularity to itself.

## Construction from parallelograms

We represent a parallelogram in $\mathbb{R}^{2}$ up to translation by a pair of complex numbers $\left(z_{1}, z_{2}\right)$ such that $\operatorname{Im}\left(z_{1} \bar{z}_{2}\right)>0$.
Given three parallelograms $\mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}$ represented by the pairs $\left(z_{1}, z_{2}\right),\left(z_{2}, z_{3}\right)$, and $\left(z_{3}, z_{4}\right)$ respectively, we can construct a surface in $\mathcal{H}(2)$ by the following gluing:


## Construction from parallelograms

## Proposition

Every surface in $\mathcal{H}(2)$ can be obtained from the previous construction.

Consequently, on every surface in $\mathcal{H}(2)$, there always exist a family of 6 saddle connections which decompose the surface into 3 parallelograms. We will call such families parallelogram decompositions of the surface.

## Construction from parallelograms

## Question

- Which triples of parallelograms give the same surface in $\mathcal{H}(2)$ ?
- Given a surface in $\mathcal{H}(2)$, describe the set of parallelogram decompositions of this surface.


## Elementary moves

$T$-move: changing $P_{1}$


## Elementary moves

S-move: permuting $\left(\mathrm{P}_{1}, \mathrm{P}_{2}, \mathrm{P}_{3}\right)$


## Elementary moves

$R$-move: changing $\mathrm{P}_{2}$ and $\mathrm{P}_{3}$


## Elementary moves

## Theorem

Two triples of parallelograms give rise to the same surface in $\mathcal{H}(2)$ if and only if one can be transformed to the other by a sequence of elementary moves.

## Parallelogram decompositions

Given a surface $\Sigma$ in $\mathcal{H}(2)$, we have elementary moves corresponding to $T, S, R$ in the set of parallelogram decompositions. Those moves can be realized by homeomorphisms of the surface.

One can associate to each parallelogram decomposition of $\Sigma$ a unique canonical basis of of $H_{1}(\Sigma, \mathbb{Z})$, then the actions of the corresponding homeomorphisms on $H_{1}(\Sigma, \mathbb{Z})$ in this basis given by the matrices $T, S$, and $R$.

Let $\Gamma$ denote the group generated by $T, S$ and $R$.

## The matrices $T, S, R$

$$
\begin{aligned}
T & =\left(\begin{array}{cccc}
1 & 1 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 0 \\
0 & 0 & 0 & 1
\end{array}\right) \\
S & =\left(\begin{array}{cccc}
0 & 1 & 0 & 1 \\
0 & 0 & -1 & 0 \\
0 & 1 & 0 & 0 \\
-1 & 0 & 1 & 0
\end{array}\right) \\
R & =\left(\begin{array}{cccc}
1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 \\
0 & 0 & 1 & 1 \\
0 & 0 & 0 & 1
\end{array}\right)
\end{aligned}
$$

## Properties of $\Gamma$

- $T$ and $R$ commute, $S^{2}=-\mathrm{Id}$,
- $\Gamma \subsetneq \operatorname{Sp}(4, \mathbb{Z})$, the action of $\Gamma$ on $(\mathbb{Z} / \mathbb{Z})^{4} \backslash\{0\}$ has two orbits, but the action of $\operatorname{Sp}(4, \mathbb{Z})$ is transitive.
- $\Gamma$ is not normal in $\mathrm{Sp}(4, \mathbb{Z})$.
- $\lceil$ contains $\operatorname{SL}(2, \mathbb{Z})$ as a proper subgroup.


## Jacobian locus

For $g \geqslant 1$, the Siegel upper half space $\mathfrak{H}_{g}$ is the set of $g \times g$ complex symmetric matrices whose imaginary part is positive definite.

The Jacobian locus $\mathfrak{J}_{g}$ is the subset of $\mathfrak{H}_{g}$ consisting of period matrices associated to canonical homology bases of Riemann surfaces of genus $g$.

The moduli space $\mathfrak{M}_{g}$ of Riemann surfaces of genus $g$ can be identified with $\mathfrak{J}_{g} / \operatorname{Sp}(2 g, \mathbb{Z})$.

## Jacobian locus

- Case $g=1$ : $\mathfrak{J}_{1}=\mathfrak{H}_{1}=\mathbb{H}$ the hyperbolic upper half plan.
- Case $g=2: \mathfrak{J}_{2} \subsetneq \mathfrak{H}_{2}$, the complement is a countable union of copies of $\mathfrak{H}_{1} \times \mathfrak{H}_{1}$.


## Main result

## Theorem

The space $\mathcal{M}(2)$, that is the set of pairs (Riemann surface of genus 2, distinguished Weierstrass point), can be identified with the quotient $\mathfrak{J}_{2} / \Gamma$.

## Main result

Main ideas:

- Generalizing the notion of "parallelogram decomposition" by taking into account the action of the hyperelliptic involution on $\pi_{1}(M, W)$.
- A connectivity result on a subset of the set of simple closed curves on $M$.
- Hyperellipticity of Riemann surfaces of genus 2 , and $\Theta$ function.


## Corollary

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We have $[\mathrm{Sp}(4, \mathbb{Z}): \Gamma]=6$.
Idea: there exists a map $\rho: \mathcal{M}(2) \longrightarrow \mathfrak{M}_{2}$ which is generically six to one.

## Remark

Let $\operatorname{Mod}_{0,6}$ denote the mapping class group of the sphere with 6 punctures. The fundamental group of $\mathcal{M}(2)$ is the subgroup of $\operatorname{Mod}_{0,6}$ fixing a distinguished puncture.

The universal cover map factors through $\mathfrak{J}_{2}$, therefore we have a surjective homomorphism from $\pi_{1}(\mathcal{M}(2))$ onto $\Gamma$ (more precisely $\Gamma /\{ \pm \mathrm{Id}\})$.

