Moments and positive polynomials for optimization IV: Another look at nonnegativity and optimization

Jean B. Lasserre

LAAS-CNRS and Institute of Mathematics, Toulouse, France

Tutorial, IMS, Singapore, November 2012

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \ \rightarrow \ inner \ approximations \ of the \ cone \ of \ polynomials nonnegative \ on \ K$
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

▲ 御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ …

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

(個) (日) (日) 日

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

・ 何 と く き と く き と … き

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

▲冊▶▲≣▶▲≣▶ ≣ のQ@

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

▲□ ▶ ▲ 三 ▶ ▲ 三 ▶ ● 三 ● ● ● ●

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

▲□ ▶ ▲ 三 ▶ ▲ 三 ▶ ● 三 ● ● ● ●

- Positivstellensatze for semi-algebraic sets K ⊂ ℝⁿ from the knowledge of defining polynomials
- $\bullet \rightarrow inner \mbox{ approximations}$ of the cone of polynomials nonnegative on K
- Optimization: Semidefinite relaxations yield lower bounds
- Another look at nonnegativity from knowledge of a measure supported on K.
- $\bullet \rightarrow outer approximations of the cone of polynomials nonnegative on K$
- Optimization: Semidefinite approximations yield upper bounds

▲□ ▶ ▲ ■ ▶ ▲ ■ ▶ ■ ● ● ● ●

Let $\subseteq \mathbb{R}^n$ be closed



A basic question is:

Characterize the continuous functions $f : \mathbb{R}^n \to \mathbb{R}$ that are nonnegative on **K**

・ 同 ト ・ ヨ ト ・ ヨ ト

э





if one obtains ...

a characterization amenable to practical computation!

ヘロン 人間 とくほ とくほ とう

3

Let $\mathbf{K} := \{\mathbf{x} \in \mathbb{R}^n : g_j(\mathbf{x}) \ge 0, \quad j = 1, \dots, m\}$, for some polynomials $(g_j) \subset \mathbb{R}[\mathbf{x}]$.

Here, knowledge on **K** is through its defining polynomials $(g_j) \subset \mathbb{R}[\mathbf{x}]$.

Let $\mathcal{C}(\mathbf{K})_d$ be the CONVEX cone of polynomials of degree at most d, nonnegative on \mathbf{K} , and \mathcal{C}_d the CONVEX cone of polynomials of degree at most d, nonnegative on \mathbb{R}^n .

(四) (日) (日)

Let
$$g_0(x) = 1$$
 for all x.

The quadratic module associated with (g_i) is the set

$$\mathcal{Q}(\boldsymbol{g}) \, := \, \left\{ \, \sum_{j=0}^m \sigma_j \, \boldsymbol{g}_j \, : \, \sigma_j \in \Sigma[\mathbf{x}] \,
ight\}$$

Of course every element of Q(g) is nonnegative on K, and the (σ_j) provide certificates of nonnegativity on K.

▲御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ 二 臣

The *k*-truncated quadratic module
associated with the
$$(g_j)$$
 is the set
 $Q_k(g) := \left\{ \sum_{j=0}^m \sigma_j g_j : \sigma_j \in \Sigma[\mathbf{x}], \quad \deg \sigma_j g_j \le 2k \right\}$

And as one is interested in the cone of polynomials of degree at most d, nonnegative on K,

 \dots consider the d-truncated convex cone: $Q_k^d(g) \, := \, Q_k(g) \, \cap \, \mathbb{R}[\mathbf{x}]_d$

< 回 > < 回 > < 回 > -

ъ

Observe that

$$Q_k^d(g) \subset \mathcal{C}(\mathsf{K})_d, \quad \forall k,$$

and so, the convex cones $(Q_k^d(g)), k \in \mathbb{N}$, provide nested inner approximations of $\mathcal{C}(\mathsf{K})_d$.

... and ... TESTING whether $f \in Q_k^d(g)$ reduces to SOLVING a SEMIDEFINITE PROGRAM (a convex optimization problem that can be solved efficiently)

... which provides the basis of

moment-sos relaxations for polynomial programming!

ヘロト ヘワト ヘビト ヘビト

Observe that

$$Q_k^d(g) \subset \mathcal{C}(\mathbf{K})_d, \quad \forall k,$$

and so, the convex cones $(Q_k^d(g)), k \in \mathbb{N}$, provide nested inner approximations of $\mathcal{C}(\mathsf{K})_d$.

... and ... **TESTING** whether $f \in Q_k^d(g)$

reduces to SOLVING a SEMIDEFINITE PROGRAM

(a convex optimization problem that can be solved efficiently)

... which provides the basis of

moment-sos relaxations for polynomial programming!

・ロン ・四 と ・ ヨ と ・ ヨ と …

Observe that

$$Q_k^d(g) \subset \mathcal{C}(\mathbf{K})_d, \quad \forall k,$$

and so, the convex cones $(Q_k^d(g)), k \in \mathbb{N}$, provide nested inner approximations of $\mathcal{C}(\mathsf{K})_d$.

... and ... **TESTING** whether $f \in Q_k^d(g)$

reduces to SOLVING a SEMIDEFINITE PROGRAM

(a convex optimization problem that can be solved efficiently)

... which provides the basis of

moment-sos relaxations for polynomial programming!

・ 同 ト ・ ヨ ト ・ ヨ ト

Recall the fundamental and powerful representation result:

Putinar-Prestel-Jacobi Positivstellensatz

Assume that for some M > 0, the quadratic polynomial $\mathbf{x} \mapsto M - \|\mathbf{x}\|^2$ is in Q(g) and let $f \in \mathbb{R}[X]_d$. Then:

 $[\mathsf{K} \text{ compact and } f > 0 \text{ on } \mathsf{K}] \quad \Rightarrow \quad f \in Q^d_k(g)$

for some integer *k*.

・ 同 ト ・ ヨ ト ・ ヨ ト

Recall the fundamental and powerful representation result:

Putinar-Prestel-Jacobi Positivstellensatz

Assume that for some M > 0, the quadratic polynomial $\mathbf{x} \mapsto M - \|\mathbf{x}\|^2$ is in Q(g) and let $f \in \mathbb{R}[X]_d$. Then:

 $[\mathsf{K} \text{ compact and } \mathbf{f} > 0 \text{ on } \mathsf{K}] \quad \Rightarrow \quad \mathbf{f} \in Q_k^d(\mathbf{g})$

for some integer k.

通 とくほ とくほ とう

Recall the fundamental and powerful representation result:

Putinar-Prestel-Jacobi Positivstellensatz

Assume that for some M > 0, the quadratic polynomial $\mathbf{x} \mapsto M - \|\mathbf{x}\|^2$ is in Q(g) and let $f \in \mathbb{R}[X]_d$. Then:

 $[\mathsf{K} \text{ compact and } \mathbf{f} > 0 \text{ on } \mathsf{K}] \quad \Rightarrow \quad \mathbf{f} \in Q_k^d(\mathbf{g})$

for some integer k.

通 とくほ とくほ とう

In fact, Putinar's Positivstellensatz can be re-stated as:

$$\overline{\left(\bigcup_{k=0}^{\infty} Q_k^d(g)\right)} = \mathcal{C}(\mathbf{K})_d$$

(if $\mathbf{x}\mapsto M-\|\mathbf{x}\|^2$ is in Q(g))

◆□ → ◆ 三 → ◆ 三 → ◆ ○ ◆

Optimization: Hierarchy of semidefinite relaxations

Consider the global optimization problem

 $\mathbf{f}^* = \min\{\mathbf{f}(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$

and with $2k_0 \ge \deg f$, consider the semidefinite programs:

$$\rho_k := \max_{\lambda} \{ \lambda : f - \lambda \in Q_k(g) \}, \quad k \ge k_0$$

We have already seen:

Theorem

Let **K** be compact and assume that the polynomial $M - ||\mathbf{x}||^2$ belongs to Q(g). Then $\rho_k \uparrow f^* := \min \{f(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$.

イロン 不良 とくほう 不良 とうほ

Optimization: Hierarchy of semidefinite relaxations

Consider the global optimization problem

$$f^* = \min\{f(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$$

and with $2k_0 \ge \deg f$, consider the semidefinite programs:

$$\rho_{k} := \max_{\lambda} \{ \lambda : f - \lambda \in Q_{k}(g) \}, \quad k \geq k_{0}$$

We have already seen:

Theorem

Let **K** be compact and assume that the polynomial $M - ||\mathbf{x}||^2$ belongs to Q(g). Then $\rho_k \uparrow f^* := \min \{f(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$.

イロト イポト イヨト イヨト 三日

Optimization: Hierarchy of semidefinite relaxations

Consider the global optimization problem

 $\mathbf{f}^* = \min\{\mathbf{f}(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$

and with $2k_0 \ge \deg f$, consider the semidefinite programs:

$$\rho_k := \max_{\lambda} \{ \lambda : f - \lambda \in Q_k(g) \}, \quad k \ge k_0$$

We have already seen:

Theorem

Let **K** be compact and assume that the polynomial $M - ||\mathbf{x}||^2$ belongs to Q(g). Then $\rho_k \uparrow f^* := \min \{f(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}$.

イロト イポト イヨト イヨト 三日

Another look at of nonnegativity



표 🗼 🗉 표

Let $\mathbf{K} \subseteq \mathbb{R}^n$ be an arbitrary closed set, and let $f : \mathbb{R}^n \to \mathbb{R}$ be a continuous function.

Support of a measure

On a separable metric space X, the support $\sup \mu$ of a Borel measure μ is the (unique) smallest closed set such that $\mu(X \setminus \mathsf{K}) = 0$.

Here the knowledge on **K** is through a measure μ with supp $\mu = \mathbf{K}$, and is independent of the representation of **K**.

Lemma (Let μ be such that $\mathrm{supp}\,\mu=1$

A continuous function $f : X \to \mathbb{R}$ is nonnegative on \mathbb{K} if and only if the signed Borel measure $\nu(B) = \int_{\mathbb{K} \cap B} f \, d\mu$, $B \in \mathcal{B}$, is a positive measure.

イロン 不良 とくほう 不良 とうほ

Let $\mathbf{K} \subseteq \mathbb{R}^n$ be an arbitrary closed set, and let $f : \mathbb{R}^n \to \mathbb{R}$ be a continuous function.

Support of a measure

On a separable metric space *X*, the support $\sup \mu$ of a Borel measure μ is the (unique) smallest closed set such that $\mu(X \setminus \mathbf{K}) = 0$.

Here the knowledge on **K** is through a measure μ with supp $\mu = \mathbf{K}$, and is independent of the representation of **K**.

Lemma (Let μ be such that supp $\mu = K$)

A continuous function $f : X \to \mathbb{R}$ is nonnegative on K if and only if the signed Borel measure $\nu(B) = \int_{K \cap B} f \, d\mu$, $B \in \mathcal{B}$, is a positive measure.

・ロト ・ 同 ト ・ ヨ ト ・ ヨ ト

proof

The *only if part* is straightforward. For the *if part*, if ν is a positive measure then $f(\mathbf{x}) \ge 0$ for μ -almost all $\mathbf{x} \in \mathbf{K}$. That is, there is a Borel set $G \subset \mathbf{K}$ such that $\mu(G) = 0$ and $f(\mathbf{x}) \ge 0$ on $\mathbf{K} \setminus G$.

Next, observe that $\overline{\mathbf{K} \setminus G} \subset \mathbf{K}$ and $\mu(\overline{\mathbf{K} \setminus G}) = \mu(\mathbf{K})$. Therefore $\overline{\mathbf{K} \setminus G} = \mathbf{K}$ by minimality of \mathbf{K} .

Hence, let $\mathbf{x} \in \mathbf{K}$ be fixed, arbitrary. As $\mathbf{K} = \overline{\mathbf{K} \setminus G}$, there is a sequence $(\mathbf{x}_k) \subset \mathbf{K} \setminus G$, $k \in \mathbb{N}$, with $\mathbf{x}_k \to \mathbf{x}$ as $k \to \infty$. But since *f* is continuous and $f(\mathbf{x}_k) \ge 0$ for every $k \in \mathbb{N}$, we obtain the desired result $f(\mathbf{x}) \ge 0$. \Box

▲圖 > ▲ ヨ > ▲ ヨ > …

proof

The only if part is straightforward. For the *if part*, if ν is a positive measure then $f(\mathbf{x}) \ge 0$ for μ -almost all $\mathbf{x} \in \mathbf{K}$. That is, there is a Borel set $G \subset \mathbf{K}$ such that $\mu(G) = 0$ and $f(\mathbf{x}) \ge 0$ on $\mathbf{K} \setminus G$.

Next, observe that $\overline{\mathsf{K} \setminus G} \subset \mathsf{K}$ and $\mu(\overline{\mathsf{K} \setminus G}) = \mu(\mathsf{K})$. Therefore $\overline{\mathsf{K} \setminus G} = \mathsf{K}$ by minimality of K .

Hence, let $\mathbf{x} \in \mathbf{K}$ be fixed, arbitrary. As $\mathbf{K} = \overline{\mathbf{K} \setminus G}$, there is a sequence $(\mathbf{x}_k) \subset \mathbf{K} \setminus G$, $k \in \mathbb{N}$, with $\mathbf{x}_k \to \mathbf{x}$ as $k \to \infty$. But since *f* is continuous and $f(\mathbf{x}_k) \ge 0$ for every $k \in \mathbb{N}$, we obtain the desired result $f(\mathbf{x}) \ge 0$. \Box

・ 同 ト ・ ヨ ト ・ ヨ ト …

The only if part is straightforward. For the *if part*, if ν is a positive measure then $f(\mathbf{x}) \ge 0$ for μ -almost all $\mathbf{x} \in \mathbf{K}$. That is, there is a Borel set $G \subset \mathbf{K}$ such that $\mu(G) = 0$ and $f(\mathbf{x}) \ge 0$ on $\mathbf{K} \setminus G$.

Next, observe that $\overline{\mathsf{K} \setminus G} \subset \mathsf{K}$ and $\mu(\overline{\mathsf{K} \setminus G}) = \mu(\mathsf{K})$. Therefore $\overline{\mathsf{K} \setminus G} = \mathsf{K}$ by minimality of K .

Hence, let $\mathbf{x} \in \mathbf{K}$ be fixed, arbitrary. As $\mathbf{K} = \overline{\mathbf{K} \setminus G}$, there is a sequence $(\mathbf{x}_k) \subset \mathbf{K} \setminus G$, $k \in \mathbb{N}$, with $\mathbf{x}_k \to \mathbf{x}$ as $k \to \infty$. But since *f* is continuous and $f(\mathbf{x}_k) \ge 0$ for every $k \in \mathbb{N}$, we obtain the desired result $f(\mathbf{x}) \ge 0$. \Box

▲圖 ▶ ▲ 国 ▶ ▲ 国 ▶ ……

Moment and localizing matrix

Let $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^{n}$, be the moment of a finite Borel measure μ on \mathbb{R}^{n} , i.e.,

$$\mathbf{y}_{\alpha} = \int_{\mathbb{R}^n} \mathbf{x}^{\alpha} \, \mathbf{d}\mu \quad \left(= \int_{\mathbb{R}^n} \mathbf{x}_1^{\alpha_1} \cdots \mathbf{x}_n^{\alpha_n} \, \mathbf{d}\mu \right), \quad \forall \alpha \in \mathbb{N}^n.$$

The "Moment matrix" $M_d(y)$ has its rows and columns indexed in the basis $\{X^{\alpha}\}$ of $\mathbb{R}[X]_d$, and with entries:

$$\begin{aligned} M_d(\mathbf{y})(\alpha,\beta) &= \int_{\mathbb{R}^n} X^{\alpha+\beta} \, d\mu \\ &= \mathbf{y}_{\alpha+\beta} \quad \forall \, \alpha,\beta \in \mathbb{N}^n, \quad |\alpha|, |\beta| \leq d. \end{aligned}$$

(四) (日) (日)

ъ

For instance in
$$\mathbb{R}^2$$
: $M_1(y) = \begin{bmatrix} 1 & X_1 & X_2 \\ y_{00} & | & y_{10} & y_{01} \\ - & - & - \\ y_{10} & | & y_{20} & y_{11} \\ y_{01} & | & y_{11} & y_{02} \end{bmatrix}$

Importantly ... $M_d(\mathbf{y}) \succeq 0 \iff \int_{\mathbb{R}^n} h^2 \, d\mu \ge 0, \quad \forall h \in \mathbb{R}[X]_d$

◆□ > ◆□ > ◆臣 > ◆臣 > ─臣 ─のへで

The "Localizing matrix" $M_d(\theta y)$ w.r.t. a polynomial $\theta \in \mathbb{R}[X]$

with $X \mapsto \theta(X) = \sum_{\gamma} \theta_{\gamma} X^{\gamma}$, has its rows and columns also indexed in the basis $\{X^{\alpha}\}$ of $\mathbb{R}[X]_d$, and with entries:

$$\begin{split} M_{d}(\theta \, \mathbf{y})(\alpha, \beta) &= \int_{\mathbb{R}^{n}} \theta(X) \, X^{\alpha+\beta} \, \mathbf{d}\mu \\ &= \sum_{\gamma \in \mathbb{N}^{n}} \theta_{\gamma} \, \mathbf{y}_{\alpha+\beta+\gamma}, \qquad \left\{ \begin{array}{l} \alpha, \beta \in \mathbb{N}^{n} \\ |\alpha|, |\beta| \leq \mathbf{d}. \end{array} \right. \end{split}$$

▲□ ▶ ▲ ■ ▶ ▲ ■ ▶ ■ ● ● ●

For instance, in \mathbb{R}^2 , and with $X \mapsto \theta(X) := 1 - X_1^2 - X_2^2$,

$$M_{1}(\theta y) = \begin{bmatrix} 1 & X_{1} & X_{2} \\ y_{00} - y_{20} - y_{02}, & y_{10} - y_{30} - y_{12}, & y_{01} - y_{21} - y_{03} \\ y_{10} - y_{30} - y_{12}, & y_{20} - y_{40} - y_{22}, & y_{11} - y_{21} - y_{12} \\ y_{01} - y_{21} - y_{03}, & y_{11} - y_{21} - y_{12}, & y_{02} - y_{22} - y_{04} \end{bmatrix}$$

Importantly ...

$$M_d(heta \, oldsymbol{y}) \succeq 0 \quad \Longleftrightarrow \quad \int_{\mathbb{R}^n} h^2 \, heta \, oldsymbol{d} \mu \geq 0, \qquad orall h \in \mathbb{R}[X]_d$$

◆□ > ◆□ > ◆臣 > ◆臣 > ─臣 ─のへで

Theorem

Let $\mathbf{K} \subseteq [-1, 1]^n$ be compact and let μ be an arbitrary, fixed, finite Borel measure on \mathbf{K} with supp $\mu = \mathbf{K}$ and with moments $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^n$.

(a) $\mathbf{f} \in \mathbb{R}[\mathbf{x}]$ is nonnegative on **K** if and only if

 $M_d(\mathbf{f} \mathbf{y}) \succeq 0, \qquad d = 0, 1, \dots$

(b) If in addition, f is also concave on K, then one may replace K with co(K).

Theorem

Let $\mathbf{K} \subseteq [-1, 1]^n$ be compact and let μ be an arbitrary, fixed, finite Borel measure on \mathbf{K} with supp $\mu = \mathbf{K}$ and with moments $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^n$.

(a) $f \in \mathbb{R}[\mathbf{x}]$ is nonnegative on **K** if and only if

$$M_d(\mathbf{f} \mathbf{y}) \succeq \mathbf{0}, \qquad d = \mathbf{0}, \mathbf{1}, \dots$$

(b) If in addition, f is also concave on K, then one may replace K with co(K).

◆□ → ◆ 三 → ◆ 三 → ◆ ○ ◆

Consider the signed measure $d\nu = f d\mu$. As $\mathbf{K} \subseteq [-1, 1]^n$,

$$|\mathbf{Z}_{\alpha}| = \left| \int_{\mathbf{K}} \mathbf{x}^{\alpha} \mathbf{f} d\mu \right| \le \int_{\mathbf{K}} |\mathbf{f}| d\mu = \|\mathbf{f}\|_{1}, \qquad \forall \alpha \in \mathbb{N}^{n}.$$

and so *z* is the moment sequence of a finite (positive) Borel measure ψ on $[-1, 1]^n$.

As **K** is compact this implies $\nu = \psi$, and so, ν is a positive Borel measure, and with support equal to **K**.

By the Lemma that we have seen, $f \ge 0$ on **K**.

▲圖 > ▲ ヨ > ▲ ヨ > …

Consider the signed measure $d\nu = f d\mu$. As $\mathbf{K} \subseteq [-1, 1]^n$,

$$|\mathbf{Z}_{\alpha}| = \left| \int_{\mathbf{K}} \mathbf{x}^{\alpha} \mathbf{f} d\mu \right| \leq \int_{\mathbf{K}} |\mathbf{f}| d\mu = \|\mathbf{f}\|_{1}, \qquad \forall \alpha \in \mathbb{N}^{n}.$$

and so *z* is the moment sequence of a finite (positive) Borel measure ψ on $[-1, 1]^n$.

As **K** is compact this implies $\nu = \psi$, and so, ν is a positive Borel measure, and with support equal to **K**.

By the Lemma that we have seen, $f \ge 0$ on **K**.

▲圖 ▶ ▲ 臣 ▶ ▲ 臣 ▶ 二 臣

Consider the signed measure $d\nu = f d\mu$. As $\mathbf{K} \subseteq [-1, 1]^n$,

$$|\mathbf{Z}_{\alpha}| = \left| \int_{\mathbf{K}} \mathbf{x}^{\alpha} \mathbf{f} d\mu \right| \le \int_{\mathbf{K}} |\mathbf{f}| d\mu = \|\mathbf{f}\|_{1}, \qquad \forall \alpha \in \mathbb{N}^{n}.$$

and so *z* is the moment sequence of a finite (positive) Borel measure ψ on $[-1, 1]^n$.

As **K** is compact this implies $\nu = \psi$, and so, ν is a positive Borel measure, and with support equal to **K**.

By the Lemma that we have seen, $f \ge 0$ on K.

< 回 > < 回 > < 回 > … 回

Let identify $f \in \mathbb{R}[\mathbf{x}]_d$ with its vector of coefficient $f \in \mathbb{R}^{s(d)}$, with $s(d) = \binom{n+d}{n}$.

Observe that, for every k = 1, ..., the set

$$\Delta_k := \{ \mathbf{f} \in \mathbb{R}^{s(d)} : M_k(\mathbf{f} \mathbf{y}) \succeq \mathbf{0} \},\$$

is the feasible set associated with a Linear Matrix Inequality, and so a CONVEX SET (and in fact, here, a CONVEX CONE).

Indeed the entry (α, β) of $M_k(f \mathbf{y})$ is just

 $\sum_{\gamma \in \mathbb{N}^n} f_{\gamma} \, \mathbf{y}_{\alpha+\beta+\gamma}$

and so $M_k(f \mathbf{y}) \succeq 0$ is a Linear Matrix Inequality (LMI) on the vector of coefficients of f.

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ - □ - つへの

Let identify $f \in \mathbb{R}[\mathbf{x}]_d$ with its vector of coefficient $f \in \mathbb{R}^{s(d)}$, with $s(d) = \binom{n+d}{n}$.

Observe that, for every k = 1, ..., the set

$$\Delta_k := \{ \mathbf{f} \in \mathbb{R}^{s(d)} : M_k(\mathbf{f} \mathbf{y}) \succeq \mathbf{0} \},\$$

is the feasible set associated with a Linear Matrix Inequality, and so a CONVEX SET (and in fact, here, a CONVEX CONE).

Indeed the entry (α, β) of $M_k(f \mathbf{y})$ is just

$$\sum_{\gamma \in \mathbb{N}^n} f_{\gamma} \, \mathbf{y}_{\alpha+eta+\gamma}$$

and so $M_k(f \mathbf{y}) \succeq 0$ is a Linear Matrix Inequality (LMI) on the vector of coefficients of f.

・ロト ・ 同ト ・ ヨト ・ ヨト … ヨ

Example: Let $f \in \mathbb{R}[\mathbf{x}]$ be the polynomial:

$$\mathbf{x} \mapsto f(\mathbf{x}) := \mathbf{a} + \mathbf{b} x_1 x_2.$$

 $M_1(f\mathbf{y}) = \begin{bmatrix} ay_{00} + by_{11}, & ay_{10} + by_{21}, & ay_{01} + by_{12} \\ ay_{10} + by_{21}, & ay_{20} + by_{31}, & ay_{11} + by_{22} \\ ay_{01} + by_{12}, & ay_{11} + by_{22}, & ay_{02} + by_{13} \end{bmatrix} \succeq \mathbf{0}.$

Equivalently,

$$a\begin{bmatrix} y_{00}, y_{10}, y_{01} \\ y_{10}, y_{20}, y_{11} \\ y_{01}, y_{11}, y_{02} \end{bmatrix} + b\begin{bmatrix} y_{11}, y_{21}, y_{12} \\ y_{21}, y_{31}, y_{22} \\ y_{12}, y_{22}, y_{13} \end{bmatrix} \succeq 0$$

which defines a CONVEX CONE in \mathbb{R}^2 for the coefficients (a, b) of polynomials of the form $a + bx_1x_2$.

◎ ▶ ▲ 臣 ▶ ▲ 臣 ▶ ○ 臣 ● の Q ()

and so ...

one obtains a nested hierarchy of spectrahedra

$$\Delta_0 \supset \Delta_1 \cdots \supset \Delta_k \cdots \supset \mathcal{C}(\mathsf{K})_d,$$

with no lifting, which provide

tighter and tighter outer approximations of $\mathcal{C}(\mathbf{K})_d$.

◆□▶ ◆□▶ ◆三▶ ◆三▶ ● ○ ○ ○

So we get the sandwich $Q_k^d(g) \subset \mathcal{C}(\mathbb{K})_d \subset \Delta_k$ for all k, and

$$\overline{\left(\bigcup_{k=0}^{\infty} Q_{k}^{d}(g)\right)} = \mathcal{C}(\mathbf{K})_{d} = \left(\bigcap_{k=0}^{\infty} \Delta_{k}\right)$$

$$\downarrow \qquad \downarrow$$
Inner approximations
representation dependent
independent of representation

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Theorem (A hierarchy of upper bounds)

Let $f \in \mathbb{R}[\mathbf{x}]_d$ be fixed and $\mathbf{K} \subset \mathbb{R}^n$ be closed. Let μ be such that $\sup \mu = \mathbf{K}$ and with moment sequence $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^n$. Consider the hierarchy of semidefinite programs:

$$u_{k} = \min_{\sigma} \left\{ \int_{\mathbf{K}} \mathbf{f} \underbrace{\sigma \, d\mu}_{d\nu} : \int_{\mathbf{K}} \underbrace{\sigma \, d\mu}_{d\nu} = 1; \ \sigma \in \Sigma[\mathbf{x}]_{d} \right\},$$

with dual:

$$u_k^* = \max_{\lambda} \{ \lambda : M_k(f - \lambda, \mathbf{y}) \succeq \mathbf{0} \}$$

=
$$\max_{\lambda} \{ \lambda : \lambda M_k(\mathbf{y}) \preceq M_k(f, \mathbf{y}) \}$$

Then $u_k^*, u_k \downarrow f^* = \min_{\mathbf{x}} \{f(\mathbf{x}) : \mathbf{x} \in \mathbf{K}\}.$

ヘロア 人間 アメヨア 人口 ア

ъ

- Computing u_k^* is a generalized eigenvalue problem!
- Next, recall that

$$f^* = \min_{\psi} \{ \int_{\mathbf{K}} f \, d\psi : \psi(\mathbf{K}) = 1, \, \psi(\mathbb{R}^n \setminus \mathbf{K}) = 0 \}$$

whereas
$$u_k = \min_{\nu} \{ \int_{\mathbf{K}} f \, \underbrace{\sigma d\mu}_{d\nu} : \nu(\mathbf{K}) = 1, \, \nu(\mathbb{R}^n \setminus \mathbf{K}) = 0; \, \sigma \in \Sigma[\mathbf{x}]_k \}$$

that is, one optimizes over the subspace of Borel probability measures absolutely continuous with respect to μ , and with density $\sigma \in \Sigma[\mathbf{x}]_k$.

Ideally, when k is large, $\sigma(\mathbf{x}) > 0$ in a neighborhood of a global minimizer $\mathbf{x}^* \in \mathbf{K}$.

- Computing u_k^* is a generalized eigenvalue problem!
- Next, recall that

$$f^* = \min_{\psi} \{ \int_{\mathbf{K}} f \, d\psi : \psi(\mathbf{K}) = 1, \, \psi(\mathbb{R}^n \setminus \mathbf{K}) = 0 \}$$

whereas
$$u_k = \min_{\nu} \{ \int_{\mathbf{K}} f \, \underbrace{\sigma d\mu}_{d\nu} : \nu(\mathbf{K}) = 1, \, \nu(\mathbb{R}^n \setminus \mathbf{K}) = 0; \, \sigma \in \Sigma[\mathbf{x}]_k \}$$

that is, one optimizes over the subspace of Borel probability measures absolutely continuous with respect to μ , and with density $\sigma \in \Sigma[\mathbf{x}]_k$.

Ideally, when k is large, $\sigma(\mathbf{x}) > 0$ in a neighborhood of a global minimizer $\mathbf{x}^* \in \mathbf{K}$.

▲ 御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ …

- Computing u_k^* is a generalized eigenvalue problem!
- Next, recall that

$$f^{*} = \min_{\psi} \{ \int_{\mathbf{K}} f \, d\psi : \psi(\mathbf{K}) = 1, \, \psi(\mathbb{R}^{n} \setminus \mathbf{K}) = 0 \}$$

whereas
$$u_{k} = \min_{\nu} \{ \int_{\mathbf{K}} f \, \underbrace{\sigma d\mu}_{d\nu} : \nu(\mathbf{K}) = 1, \, \nu(\mathbb{R}^{n} \setminus \mathbf{K}) = 0; \, \sigma \in \Sigma[\mathbf{x}]_{k} \}$$

that is, one optimizes over the subspace of Borel probability measures absolutely continuous with respect to μ , and with density $\sigma \in \Sigma[\mathbf{x}]_k$.

Ideally, when k is large, $\sigma(\mathbf{x}) > 0$ in a neighborhood of a global minimizer $\mathbf{x}^* \in \mathbf{K}$.

▲ 御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ …

- Computing u_k^* is a generalized eigenvalue problem!
- Next, recall that

$$f^{*} = \min_{\psi} \{ \int_{\mathbf{K}} f \, d\psi : \psi(\mathbf{K}) = 1, \, \psi(\mathbb{R}^{n} \setminus \mathbf{K}) = 0 \}$$

whereas
$$u_{k} = \min_{\nu} \{ \int_{\mathbf{K}} f \underbrace{\sigma d\mu}_{d\nu} : \nu(\mathbf{K}) = 1, \, \nu(\mathbb{R}^{n} \setminus \mathbf{K}) = 0; \, \sigma \in \Sigma[\mathbf{x}]_{k} \}$$

that is, one optimizes over the subspace of Borel probability measures absolutely continuous with respect to μ , and with density $\sigma \in \Sigma[\mathbf{x}]_k$.

Ideally, when k is large, $\sigma(\mathbf{x}) > 0$ in a neighborhood of a global minimizer $\mathbf{x}^* \in \mathbf{K}$.

▲御♪ ▲臣♪ ▲臣♪ 二臣

- Computing u_k^* is a generalized eigenvalue problem!
- Next, recall that

$$f^{*} = \min_{\psi} \{ \int_{\mathbf{K}} f \, d\psi : \psi(\mathbf{K}) = 1, \, \psi(\mathbb{R}^{n} \setminus \mathbf{K}) = 0 \}$$

whereas
$$u_{k} = \min_{\nu} \{ \int_{\mathbf{K}} f \underbrace{\sigma d\mu}_{d\nu} : \nu(\mathbf{K}) = 1, \, \nu(\mathbb{R}^{n} \setminus \mathbf{K}) = 0; \, \sigma \in \Sigma[\mathbf{x}]_{k} \}$$

that is, one optimizes over the subspace of Borel probability measures absolutely continuous with respect to μ , and with density $\sigma \in \Sigma[\mathbf{x}]_k$.

Ideally, when k is large, $\sigma(\mathbf{x}) > 0$ in a neighborhood of a global minimizer $\mathbf{x}^* \in \mathbf{K}$.

(四) (日) (日) 日

• Also works for non-compact closed sets but then μ has to satisfy a Carleman-type sufficient condition which limits the growth of the moments. For example, take

$$\boldsymbol{d}\mu = \mathrm{e}^{-\|\mathbf{x}\|^2/2} \, \boldsymbol{d}\nu$$

where ν is an arbitrary finite Borel measure with support K. • The sequences of upper bounds (u_k, u_k^*) complement the sequences of lower bounds (ρ_k, ρ_k^*) obtained from SDP-relaxations.

• Of course, for practical computation, the previous semidefinite relaxations require knowledge of the moment sequence $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^{n}$.

(個) (日) (日) 日

• Also works for non-compact closed sets but then μ has to satisfy a Carleman-type sufficient condition which limits the growth of the moments. For example, take

$$\mathbf{d}\mu = \mathrm{e}^{-\|\mathbf{x}\|^2/2} \, \mathbf{d}\nu$$

where ν is an arbitrary finite Borel measure with support K. • The sequences of upper bounds (u_k, u_k^*) complement the sequences of lower bounds (ρ_k, ρ_k^*) obtained from SDP-relaxations.

• Of course, for practical computation, the previous semidefinite relaxations require knowledge of the moment sequence $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^{n}$.

(個) (日) (日) 日

• Also works for non-compact closed sets but then μ has to satisfy a Carleman-type sufficient condition which limits the growth of the moments. For example, take

$$\mathbf{d}\mu = \mathrm{e}^{-\|\mathbf{x}\|^2/2} \, \mathbf{d}\nu$$

where ν is an arbitrary finite Borel measure with support K. • The sequences of upper bounds (u_k, u_k^*) complement the sequences of lower bounds (ρ_k, ρ_k^*) obtained from SDP-relaxations.

• Of course, for practical computation, the previous semidefinite relaxations require knowledge of the moment sequence $\mathbf{y} = (\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^{n}$.

(個) (ヨ) (ヨ) (ヨ)

This is possible for relatively simple sets **K** like a box, a simplex, the discrete set, an ellipsoid, etc., where one can compute all moments of a measure μ whose support is **K**. For instance take μ to be uniformly distributed, or $\mathbf{K} = \mathbb{R}^n$ (or $\mathbf{K} = \mathbb{R}^n_+$) with

 $d\mu = e^{-\|\mathbf{x}\|^2/2} d\mathbf{x}, \quad \mathbf{K} = \mathbb{R}^n$ $d\mu = e^{-\sum_i x_i} d\mathbf{x}, \quad \mathbf{K} = \mathbb{R}^n_+$ $d\mu = d\mathbf{x}, \begin{cases} \mathbf{K} = [\mathbf{a}_1, \mathbf{b}_1] \times \cdots \times [\mathbf{a}_n, \mathbf{b}_n] \\ \mathbf{K} = \{\mathbf{x} \in \mathbb{R}^n_+ : \sum_{i=1}^n x_i \le 1\} \end{cases}$

For $\mathbf{K} = \{-1, 1\}^n$ or $\mathbf{K} = \{0, 1\}^n$ take μ to be uniformly distributed.

(個) (日) (日) (日)

Practical calculation

If instead of the usual canonical basis of monomials (X^{α}) , $\alpha \in \mathbb{N}^{n}$, one now uses the basis of polynomials (P_{α}) , $\alpha \in \mathbb{N}^{n}$, that are ORTHONORMAL with respect to the known measure μ , then the moments matrix $M_{k}(\mathbf{y})$ expressed in that basis is the IDENTITY matrix! Indeed,

$$M_k(\mathbf{y})(\alpha,\beta) = \int_{\mathbb{R}^n} P_\alpha P_\beta d\mu = \delta_{\alpha=\beta}.$$

Then . . .

$$u_k^* = \max_{\lambda} \{ \lambda : \lambda M_k(\mathbf{y}) \leq M_k(f, \mathbf{y}),$$

i.e., u_k^* is the smallest eigenvalue of the matrix $M_k(f, \mathbf{y})$

・ 同 ト ・ ヨ ト ・ ヨ ト

Practical calculation

If instead of the usual canonical basis of monomials (X^{α}) , $\alpha \in \mathbb{N}^{n}$, one now uses the basis of polynomials (P_{α}) , $\alpha \in \mathbb{N}^{n}$, that are ORTHONORMAL with respect to the known measure μ , then the moments matrix $M_{k}(\mathbf{y})$ expressed in that basis is the IDENTITY matrix! Indeed,

$$M_k(\mathbf{y})(\alpha,\beta) = \int_{\mathbb{R}^n} P_\alpha P_\beta d\mu = \delta_{\alpha=\beta}.$$

Then ...

$$u_k^* = \max_{\lambda} \{ \lambda : \lambda M_k(\mathbf{y}) \leq M_k(\mathbf{f}, \mathbf{y}),$$

i.e., u_k^* is the smallest eigenvalue of the matrix $M_k(f, \mathbf{y})!$

・ 一 ・ ・ ・ ・ ・

Computing a basis of polynomials

 $(P_{\alpha}), \alpha \in \mathbb{N}^{n}$, orthonormal with respect to μ is easy if one knows the moments of μ !

For instance: $P_0 = 1$, and

$$P_{10} = \det\left(\left[\begin{array}{cc} y_0 & y_{10} \\ 1 & X_1 \end{array}\right]\right); \qquad P_{01} = \det\left(\left[\begin{array}{cc} y_0 & y_{10} & y_{01} \\ y_{10} & y_{20} & y_{11} \\ 1 & X_1 & X_2 \end{array}\right]\right);$$

etc., plus scaling so as to have $\int P_{\alpha}^2 d\mu = 1$.

▲御 ▶ ▲ 臣 ▶ ▲ 臣 ▶ 二 臣

Computing a basis of polynomials

 $(P_{\alpha}), \alpha \in \mathbb{N}^{n}$, orthonormal with respect to μ is easy if one knows the moments of μ !

For instance: $P_0 = 1$, and

$$P_{10} = \det\left(\left[\begin{array}{cc} y_0 & y_{10} \\ 1 & X_1 \end{array}\right]\right); \qquad P_{01} = \det\left(\left[\begin{array}{cc} y_0 & y_{10} & y_{01} \\ y_{10} & y_{20} & y_{11} \\ 1 & X_1 & X_2 \end{array}\right]\right);$$

etc., plus scaling so as to have $\int P_{\alpha}^2 d\mu = 1$.

通 とくほ とくほ とう

ъ

Ex 1: With $\mathbf{K} = \mathbb{R}^n_+$ and $\mathbf{x} \mapsto f_{\mathbf{A}}(\mathbf{x}) := \mathbf{x}^T \cdot \mathbf{x}$

for real symmetric matrices $\mathbf{A} \in \mathbb{R}^{n \times n}$, one may thus provide outer approximations of the convex cone of COPOSITIVE matrices, that is, matrices **A** such that

$$\mathbf{x}^T \mathbf{A} \mathbf{x} \ge \mathbf{0}, \qquad \forall \mathbf{x} \in \mathbb{R}^n_+,$$

an important tool for 0/1 combinatorial optimization problems. These outer approximations complement the inner approximations already obtained by Parrilo, and DeKlerk and Pasechnik.

Ex 2: With $\mathbf{K} = \{-1, 1\}^n$ and $\mathbf{x} \mapsto f_{\mathbf{A}}(\mathbf{x}) := \mathbf{x}^T \wedge \mathbf{x}$

for real symmetric matrices $\mathbf{A} \in \mathbb{R}^{n \times n}$, one may thus provide a hierarchy of upper bounds for MAXCUT problem with matrix \mathbf{A} .

ヘロン ヘアン ヘビン ヘビン

Some experiments

•
$$\mathbf{K} = \mathbb{R}^2_+$$
 with $d\mu = e^{-\sum_i x_i} d\mathbf{x}$ so that
 $\mathbf{y}_{ij} = i! j!, \quad \forall i, j = 0, 1, ...$
 $\mathbf{x} \mapsto f(\mathbf{x}) := x_1^2 x_2^2 (x_1^2 + x_2^2 - 1)$ with $f^* = -1/27 \approx -0.037$.
 $u_0 = 92; \quad u_1 = 1.51; \quad u_{14} = -0.011$.
• The same problem on the box $\mathbf{K} = [0, 1]$ now yields

 $u_0 = 0.222;$ $u_1 = -0.055;$ $u_{14} = -0.0311.$

and some numerical problems occur.

◆□ > ◆□ > ◆臣 > ◆臣 > ─臣 ─のへで

Some experiments

•
$$\mathbf{K} = \mathbb{R}^2_+$$
 with $d\mu = e^{-\sum_i x_i} d\mathbf{x}$ so that
 $\mathbf{y}_{ij} = i! j!, \quad \forall i, j = 0, 1, ...$
 $\mathbf{x} \mapsto \mathbf{f}(\mathbf{x}) := x_1^2 x_2^2 (x_1^2 + x_2^2 - 1)$ with $\mathbf{f}^* = -1/27 \approx -0.037$.
 $u_0 = 92; \quad u_1 = 1.51; \quad u_{14} = -0.011$.

• The same problem on the box $\mathbf{K} = [0, 1]$ now yields

$$u_0 = 0.222;$$
 $u_1 = -0.055;$ $u_{14} = -0.0311,$

and some numerical problems occur.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Some experiments

•
$$\mathbf{K} = \mathbb{R}^2_+$$
 with $d\mu = e^{-\sum_i x_i} d\mathbf{x}$ so that
 $\mathbf{y}_{ij} = i! j!, \quad \forall i, j = 0, 1, ...$
 $\mathbf{x} \mapsto \mathbf{f}(\mathbf{x}) := x_1^2 x_2^2 (x_1^2 + x_2^2 - 1)$ with $\mathbf{f}^* = -1/27 \approx -0.037$.
 $u_0 = 92; \quad u_1 = 1.51; \quad u_{14} = -0.011$.

• The same problem on the box $\mathbf{K} = [0, 1]$ now yields

$$u_0 = 0.222;$$
 $u_1 = -0.055;$ $u_{14} = -0.0311,$

and some numerical problems occur.

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Some randomly generated MAXCUT problems

$$f^* = \min_{x} \{ \mathbf{x} Q \mathbf{x} : x \in \{-1, 1\}^n \}$$

with n = 11 variables.

d	<i>u</i> ₀	<i>u</i> ₁	U ₂	U ₃	U ₄	f *
Ex1	0	-1.928	-3.748	-5.22	-6.37	-7.946
Ex2	0	-1.56	-3.103	-4.314	-5.282	-6.863
Ex3	0	-1.910	-3.694	-5.078	-6.161	-8.032
Ex4	0	-2.164	-4.1664	-5.7971	-7.06	-9.198
Ex5	0	-1.825	-3.560	-4.945	-5.924	-7.467

Table: MAXCUT: n = 11; Q random.

▲冊 ▶ ▲ 臣 ▶ ▲ 臣 ▶ ● ○ ○ ○ ○ ○

Illustrating duality



Figure: $f(x) = 0.375 - 5x + 21x^2 - 32x^3 + 16x^4$ on [0, 1]

|▲ 国 → | ▲ 国 → |

æ

Solving the dual yields the SOS polynomial density σ_k with

$$u_k = \int f(\mathbf{x}) \underbrace{\sigma_k(\mathbf{x}) \, d\mathbf{x}}_{d\nu_k(\mathbf{x})}$$



Figure: The probability density $\sigma_{10}(x)dx$ on [0, 1]

通 とく ヨ とく ヨ とう

ъ

- Rapid decrease in first steps, but convergence is slow
- Numerical stability problems to be expected.
- Use bases different from the monomial basis.
- Rather see this technique as a complement to lower bounds obtained from semidefinite relaxations

- Rapid decrease in first steps, but convergence is slow
- Numerical stability problems to be expected.
- Use bases different from the monomial basis.
- Rather see this technique as a complement to lower bounds obtained from semidefinite relaxations

- Rapid decrease in first steps, but convergence is slow
- Numerical stability problems to be expected.
- Use bases different from the monomial basis.

• Rather see this technique as a complement to lower bounds obtained from semidefinite relaxations

★ 문 ► ★ 문 ►

- Rapid decrease in first steps, but convergence is slow
- Numerical stability problems to be expected.
- Use bases different from the monomial basis.
- Rather see this technique as a complement to lower bounds obtained from semidefinite relaxations

ト < 臣 > < 臣 >