

# Optimality Conditions and Finite Convergence of Lasserre's Hierarchy

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November 21, 2012

## Multivariate Polynomial Optimization

Given polynomials  $f(x), h_i(x), g_j(x)$ , we want to solve

$$\begin{aligned} \min_{x \in \mathbb{R}^n} \quad & f(x) \\ \text{s.t.} \quad & h_1(x) = \cdots = h_{m_1}(x) = 0, \\ & g_1(x) \geq 0, \cdots, g_{m_2}(x) \geq 0. \end{aligned}$$

Lasserre's hierarchy is a sequence of sum of squares (SOS) relaxations for solving the problem globally. He proved asymptotic convergence under a condition on  $(h, g)$ .

Question: How often does finite convergence occur?

Answer: **Almost always!** (The goal of this talk.)

## Outline of the Talk

- Introduction of Lasserre's Hierarchy
- Optimality Conditions and Finite Convergence
- Genericity of Optimality Conditions
- Certifying Finite Convergence

## SOS polynomials

A polynomial  $p$  is sum of squares (SOS) if  $p = \sum q_i^2(x)$ .

$$\begin{aligned} \text{Example: } & 3 \cdot (x_1^4 + x_2^4 + x_3^4 + x_4^4 - 4x_1x_2x_3x_4) \\ & = (x_1^2 - x_2^2 - x_4^2 + x_3^2)^2 + (x_1^2 + x_2^2 - x_4^2 - x_3^2)^2 + \\ & \quad (x_1^2 - x_2^2 - x_3^2 + x_4^2)^2 + 2(x_1x_4 - x_2x_3)^2 + \\ & \quad 2(x_1x_2 - x_3x_4)^2 + 2(x_1x_3 - x_2x_4)^2 \end{aligned}$$

SOS implies nonnegativity, but not conversely.

**Theorem** (Hilbert, 1888) Every nonnegative poly is SOS iff

$$(\# \text{ var}, \text{ degree}) = (1, 2d), (*, 2), \text{ or } (2, 4).$$

**Hilbert'1 17th Problem:** Is every nonnegative poly is a sum of squares of **rational** functions? (Yes, by Artin).

## Testing SOS Membership

A polynomial  $p$  is SOS if and only if (Lasserre, Parrilo, ...)

$$\exists X : \quad p = [x]_d^T X [x]_d, \quad X = X^T \succeq 0.$$

The  $X$  is called a Gram matrix.

$$\begin{aligned} & 2x_1^4 + 2x_1^3x_2 - x_1^2x_2^2 + 5x_2^4 \\ &= \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \end{bmatrix}^T \begin{bmatrix} 2 & 0 & 1 \\ 0 & 5 & 0 \\ 1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \end{bmatrix} \\ &= \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \end{bmatrix}^T \begin{bmatrix} 2 & -\alpha & 1 \\ -\alpha & 5 & 0 \\ 1 & 0 & -1 + 2\alpha \end{bmatrix} \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \end{bmatrix} \end{aligned}$$

When  $\alpha = 3$ , the Gram matrix is positive semidefinite.

## Truncated ideals and quadratic modules.

Let  $h = (h_1, \dots, h_{m_1})$  and  $g = (g_1, \dots, g_{m_2})$ .

The  $2k$ -th truncated ideal generated by  $h$  is

$$\langle h \rangle_{2k} := \left\{ \sum_{i=1}^{m_1} \phi_i h_i \mid \begin{array}{l} \text{each } \phi_i \in \mathbb{R}[x] \\ \text{and } \deg(\phi_i h_i) \leq 2k \end{array} \right\}.$$

The  $k$ -th truncated quadratic module generated by  $g$  is ( $g_0 = 1$ )

$$Q_k(g) := \left\{ \sum_{j=0}^{m_2} \sigma_j g_j \mid \begin{array}{l} \text{each } \sigma_j \in \mathbb{R}[x] \text{ is SOS} \\ \text{and } \deg(\sigma_j g_j) \leq 2k \end{array} \right\}.$$

The set  $\langle h \rangle_{2k}$  is a subspace and  $Q_k(g)$  is an SDP set.

## Lasserre's Hierarchy

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0. \end{aligned}$$

For a relaxation order  $k$ , solve the SOS program (by SDP)

$$\begin{aligned} f_k := \max \quad & \gamma \\ \text{s.t.} \quad & f - \gamma = \phi + \sigma, \phi \in \langle h \rangle_{2k}, \sigma \in Q_k(g). \end{aligned}$$

For  $k = 1, 2, \dots$ , we get a sequence of lower bounds:

$$f_1 \leq f_2 \leq f_3 \leq \dots \leq f_{min}.$$

Lasserre's hierarchy is the sequence  $\{f_k\}$  of lower bounds.

Lasserre's hierarchy has **finite convergence** if

$$f_k = f_{min} \quad \text{for all } k \text{ big enough.}$$

## Lasserre's Relax.: Example 1

$$\begin{aligned} \min_{x_1, x_2} \quad & -(x_1 - 1)^2 - (x_1 - x_2)^2 - (x_2 - 3)^2 \\ \text{s.t.} \quad & 1 - (x_1 - 1)^2 \geq 0, 1 - (x_1 - x_2)^2 \geq 0, 1 - (x_2 - 3)^2 \geq 0 \end{aligned}$$

Applying Lasserre's relax., we get

order $k$	lower bound $f_k$	minimum $f_{min}$	minimizer
1	-3	-2	not found
2	-2	-2	(1,2)

Lasserre's hierarchy converges at  $k = 2$ .



## Lasserre's Relax.: Example 2

$$\begin{aligned}
 \min_{x_1, x_2} \quad & -x_1 - x_2 \\
 \text{s.t.} \quad & x_2 \leq 2x_1^4 - 8x_1^3 + 8x_1^2 + 2 \\
 & x_2 \leq 4x_1^4 - 32x_1^3 + 88x_1^2 - 96x_1 + 36 \\
 & 0 \leq x_1 \leq 3, \quad 0 \leq x_2 \leq 4
 \end{aligned}$$

Applying Lasserre's relax., we get

order $k$	lower bound $f_k$	minimum $f_{min}$	minimizer
2	-7	-5.5080	not found
3	-6.667	-5.5080	not found
4	-5.5080	-5.5080	(2.3295, 3.1785)

Lasserre's hierarchy converges at  $k = 4$ .

## Convergence of Lasserre's Hierarchy

Poly Optim. Prob.	$k$ -th Lasserre's relax.
$f_{min} := \min f(x)$	$f_k := \max \gamma$
s.t. $(h_1, \dots, h_{m_1}) _x = 0$	s.t. $f - \gamma = \phi + \sigma,$
$(g_1, \dots, g_{m_2}) _x \geq 0$	$\phi \in \langle h \rangle_{2k}, \sigma \in Q_k(g).$

Archimedean condition (AC):  $\exists R > 0, t \in \mathbb{N}$  such that

$$R - \|x\|_2^2 \in \langle h \rangle_{2t} + Q_t(g).$$

AC is almost equivalent to compactness of the feasible set.

**Theorem** (Lasserre, 2001) If AC holds, then

$$\lim_{k \rightarrow \infty} f_k = f_{min} \quad (\text{asymptotic convergence}).$$

## Known Results about Finite Convergence

Lasserre hierarchy has finite convergence (i.e.,  $f_k = f_{min}$  for all  $k$  big enough) in the following cases:

- $V_{\mathbb{C}}(h)$  is finite (Laurent, 2007). If only  $V_{\mathbb{R}}(h)$  is finite, the dual (moment) version has finite convergence (Laurent, 2009).
- $V_{\mathbb{R}}(h)$  is a finite set (N., 2012).
- The objective and constraints are strictly convex on the feasible set (Lasserre, 2009)
- The objective and constraints are convex on the feasible set and strictly convex at global minimizers (Laurent-de Klerk, 2011)
- Generic cases ( this talk )

## Finite versus Asymptotic Convergence

**Bad news (Scheiderer):** If the feasible set has dimension  $\geq 3$ , there always exists a “bad”  $f$  such that

$$\lim_{k \rightarrow \infty} f_k = f_{min}, \quad \text{but} \quad f_k < f_{min} \quad \forall k.$$

**Good news:** If  $f$  is not specially chosen (e.g., randomly generated), we *almost always* have (numerically demonstrated)

$$f_k = f_{min} \quad \text{if } k \text{ is big enough.}$$

**Question:** Why does Lasserre’s hierarchy work so well in practice?

**Goal of this talk:** Give an interpretation for the performance!

## Outline of the Talk

- Introduction of Lasserre's Hierarchy
- Optimality Conditions and Finite Convergence
- Genericity of Optimality Conditions
- Certifying Finite Convergence

## First order optimality condition (FOOC)

Let  $u$  be a local minimizer of

$$\begin{aligned} \min & f(x) \\ \text{s.t.} & (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0. \end{aligned}$$

Let  $J(u) = \{j_1, \dots, j_r\}$  be the active set at  $u$ . If the *constraint qualification condition (CQC)* holds at  $u$ , i.e.,

$$\nabla h_1(u), \dots, \nabla h_{m_1}(u), \nabla g_{m_1}(u), \dots, \nabla g_{j_r}(u)$$

are linearly independent, then there exist Lagrange multipliers  $\lambda_1, \dots, \lambda_{m_1}$  and  $\mu_1, \dots, \mu_{m_2}$  satisfying

$$\nabla f(u) = \sum_{i=1}^{m_1} \lambda_i \nabla h_i(u) + \sum_{j=1}^{m_2} \mu_j \nabla g_j(u).$$

## Complementarity Conditions

Let  $u$  be a local minimizer of

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0. \end{aligned}$$

Let  $J(u) = \{j_1, \dots, j_r\}$  be the active set at  $u$ .

The Lagrange multipliers  $\lambda_1, \dots, \lambda_{m_1}$  and  $\mu_1, \dots, \mu_{m_2}$  in FIOC further satisfies the complementarity condition

$$\mu_1 g_1(u) = \dots = \mu_{m_2} g_{m_2}(u) = 0, \quad \mu_1 \geq 0, \dots, \mu_{m_2} \geq 0.$$

The strict complementarity condition (SCC) holds at  $u$  if

$$\mu_1 + g_1(u) > 0, \dots, \mu_{m_2} + g_{m_2}(u) > 0$$

which is equivalent to

$$\mu_j > 0 \quad \forall j \in J(u).$$

## Second Order Necessity Condition (SONC)

Let  $L(x)$  be the Lagrange function

$$L(x) := f(x) - \sum_{i=1}^{m_1} \lambda_i h_i(x) - \sum_{j=1}^{m_2} \mu_j g_j(x)$$

where  $\lambda_i$  and  $\mu_j$  are Lagrange multipliers.

SONC at a local minimizer  $u$  states that

$$v^T \nabla_x^2 L(u) v \geq 0 \quad \text{for all } v \in G(u)^\perp,$$

$$G(x) := \left[ \nabla h_1(x) \quad \cdots \quad \nabla h_{m_1}(x) \quad \nabla g_1(x) \quad \cdots \quad \nabla g_{m_2}(x) \right]^T.$$

$\nabla_x^2 L(u)$  is positive semidefinite in the tangent space  $G(u)^\perp$ .



## Second Order Sufficiency Condition (SOSC)

Let  $L(x)$  be the Lagrange function

$$L(x) := f(x) - \sum_{i=1}^{m_1} \lambda_i h_i(x) - \sum_{j \in J(u)} \mu_j g_j(x)$$

where  $\lambda_i$  and  $\mu_j$  are Lagrange multipliers.

SOSC at a local minimizer  $u$  requires that

$$v^T \nabla_x^2 L(u) v > 0 \quad \text{for all } 0 \neq v \in G(u)^\perp.$$

$\nabla_x^2 L(u)$  is positive definite in the tangent space  $G(u)^\perp$ .

## Theory of Optimality Conditions in NLP

### Necessity:

$CQC + \text{local optimality} \Rightarrow FOOC + CC + SONC.$

### Sufficiency:

$FOOC + SCC + SOSC \Rightarrow \text{strict local optimality.}$

## Optimality Conditions implies Finite Convergence

**Theorem** (N.,2012): Under archimedean condition (AC), if CQC, SCC and SOSC hold at every global minimizer of  $f$  on  $K$ , then

$$f_k = f_{min} \quad \text{for all } k \text{ big enough.}$$

(Lasserre's hierarchy has finite convergence.)

Counterexamples exist if one of AC, CQC, SCC, SOSC fails.

$$\begin{aligned} \min \quad & x_1^6 + x_2^6 + x_3^6 + 3x_1^2x_2^2x_3^2 - x_1^4(x_2^2 + x_3^2) - x_2^4(x_3^2 + x_1^2) - x_3^4(x_1^2 + x_2^2) \\ \text{s.t.} \quad & x_1^2 + x_2^2 + x_3^2 = 1. \end{aligned}$$

The global minimizers are

$$\frac{1}{\sqrt{3}}(\pm 1, \pm 1, \pm 1), \frac{1}{\sqrt{2}}(\pm 1, \pm 1, 0), \frac{1}{\sqrt{2}}(\pm 1, 0, \pm 1), \frac{1}{\sqrt{2}}(0, \pm 1, \pm 1).$$

CQC, SCC, SOSOC are satisfied, e.g., at  $u = \frac{1}{\sqrt{3}}(1, 1, 1)$ ,

$$\nabla_x^2 L(u) = \frac{4}{9} \left( 3 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}^T \right), \quad G(u)^\perp = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}^\perp.$$

The Lasserre's hierarchy has finite convergence:

$$f_k = f_{min} = 0 \quad \forall k \geq 5 \quad (\text{by GloptiPoly 3}).$$

## Sketchy Proof of the main Theorem

**Theorem** (N.,2012): Under archimedean condition (AC), if CQC, SCC and SOSC hold at every global minimizer of  $f$  on  $K$ , then

$$f_k = f_{min} \quad \text{for all } k \text{ big enough.}$$

(i.e., Lasserre's hierarchy has finite convergence.)

Proof. The CQC, SCC,SOSC imply that the boundary Hessian condition (BHC) holds at every global minimizer of  $f$  on  $K$ , and then apply the BHC theorem of Murray Marshall.  $\square$

## Local Parameterization Condition (LPC)

Let  $V := V_{\mathbb{R}}(h_1, \dots, h_{m_1})$  be a real algebraic variety and

$$K = \{x \in V : g_1(x) \geq 0, \dots, g_{m_2}(x) \geq 0\}.$$

(**Marshall, 2006**) Local Parameterization Condition at  $u$ :

- i) The point  $u \in V$  is nonsingular;
- ii)  $\exists$  a neighborhood  $\mathcal{O}$  of  $u$  such that  $V \cap \mathcal{O}$  is parameterized by free parameters  $t_1, \dots, t_\ell$ ;
- iii)  $\exists 1 \leq \nu_1 < \dots < \nu_r \leq m_2$  such that

$$t_1 = g_{\nu_1}, \dots, t_r = g_{\nu_r} \text{ on } V \cap \mathcal{O};$$

- iv)  $K \cap \mathcal{O}$  is defined by  $t_1 \geq 0, \dots, t_r \geq 0$  in  $(t_1, \dots, t_r)$ -coordinates.

In brief, LPC requires that a subset of  $\{g_1, \dots, g_{m_2}\}$ , plus other parameters, can parameterize  $K$  locally at  $u$ .

## Boundary Hessian Condition (BHC)

Let  $V := V_{\mathbb{R}}(h_1, \dots, h_{m_1})$  be a real algebraic variety and

$$K = \{x \in V : g_1(x) \geq 0, \dots, g_{m_2}(x) \geq 0\}.$$

**(Marshall)** Boundary Hessian Condition (BHC) at  $u$ :

i) LPC holds at  $u$ ; let  $(t_1, \dots, t_\ell)$  be local parameters for  $K$  s.t.

$$t_1 = g_{\nu_1}, \dots, t_r = g_{\nu_r}, \quad r \leq \ell.$$

Expand  $f$  locally around  $u$  as  $f = f_0 + f_1 + f_2 + \dots$  where each  $f_i$  is homogeneous of degree  $i$  in  $(t_1, \dots, t_\ell)$ ;

ii) The linear form  $f_1 = a_1 t_1 + \dots + a_r t_r$  and has positive coeffs.

$$a_1 > 0, \dots, a_r > 0;$$

iii) The quadratic form  $f_2(0, \dots, 0, t_{r+1}, \dots, t_\ell)$  is positive definite in  $(t_{r+1}, \dots, t_\ell)$ .

## BHC Theorem

Let  $V := V_{\mathbb{R}}(h_1, \dots, h_{m_1})$  be a real algebraic variety and

$$K = \{x \in V : g_1(x) \geq 0, \dots, g_{m_2}(x) \geq 0\}.$$

**Theorem** (Marshall, 2006) Let  $f$  be a polynomial. Assume:

- i) The archimedean condition holds for  $(h, g)$ ;
- ii) The BHC holds at every global minimizer of  $f$  on  $K$ .

Then,  $\exists \sigma \in Q(g)$ , such that

$$f - f_{min} \equiv \sigma \quad \text{mod} \quad I(V) := \{p \in \mathbb{R}[x] : p|_V \equiv 0\}.$$



## Optimality conditions $\Rightarrow$ BHC

Let  $V := V_{\mathbb{R}}(h_1, \dots, h_{m_1})$  be a real algebraic variety and

$$K = \{x \in V : g_1(x) \geq 0, \dots, g_{m_2}(x) \geq 0\}.$$

**Theorem** (N.,2012) Let  $u$  be a global minimizer of  $f$  on  $K$ .

i) CQC  $\Rightarrow$  LPC holds at  $u$ .

Expand  $f$  locally as  $f = f_0 + f_1 + f_2 + \dots$  in  $(t_1, \dots, t_\ell)$ .

ii) FOOC and SCC imply that  $f_1 = a_1 t_1 + \dots + a_r t_r$  and

$$a_1 > 0, \dots, a_r > 0;$$

iii) SOSOC implies that  $f_2(0, \dots, 0, t_{r+1}, \dots, t_\ell)$  is positive definite in  $(t_{r+1}, \dots, t_\ell)$ .

In brief, CQC+SCC+SOSOC  $\Rightarrow$  BHC.

## Outline of the Talk

- Introduction of Lasserre's Hierarchy
- Optimality Conditions and Finite Convergence
- **Genericity of Optimality Conditions**
- Certifying Finite Convergence

## Genericity of Optimality conditions.

**Theorem** (N.,2012) There exist polynomials

$$\varphi_1, \dots, \varphi_L$$

in the coefficients of  $f, h_i, g_j$ , such that if

$$\varphi_1(f, h_i, g_j) \neq 0, \dots, \varphi_L(f, h_i, g_j) \neq 0,$$

then CQC, SCC, and SOSC hold at every local minimizer.

In brief, the optimality conditions hold in a Zariski open set.

## Constraint Qualification Condition is generic

Let  $K = \{x \in \mathbb{R}^n : (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0\}$ .

Let  $\{j_1, \dots, j_r\}$  be the active set at  $u$ . If

$$\Delta(h_1, \dots, h_{m_1}, g_{j_1}, \dots, g_{j_r}) \neq 0,$$

(  $\Delta(\dots)$  is a polynomial in the coef. of  $h_i, g_j$ ), then the constraint qualification condition holds at  $u$ . This is because

$$h_1 = \dots = h_{m_1} = g_{j_1} = \dots = g_{j_r} = 0$$

has no singular solutions if  $\Delta(h_1, \dots, g_{j_1}, \dots) \neq 0$ .

## Strict Complementarity Condition is generic

Consider the optimization problem

$$\min f(x) \quad s.t. \quad h(x) = 0, g(x) \geq 0.$$

The KKT condition at a local minimizer  $u$  (with  $g(u) = 0$ ) is

$$\nabla f(u) = \lambda \nabla h(u) + \mu \nabla g(u), h(u) = 0, \mu \geq 0.$$

SCC requires  $\mu > 0$ . If  $\mu = 0$ , then  $u$  is a solution of

$$\nabla f(x) = \lambda \nabla h(x), h(x) = 0, g(x) = 0.$$

If  $f, h$  has generic coef., then the polynomial system

$$\nabla f(x) = \lambda \nabla h(x), h(x) = 0$$

has finitely many solutions, which do not intersect  $g(x) = 0$  if  $g$  is generic.

## Second Order Sufficiency Condition is generic

$$\min_{x \in \mathbb{R}^n} f(x).$$

The first order optimality condition is

$$f_{x_1}(x) = \cdots = f_{x_n}(x) = 0.$$

If  $u$  is a local minimizer,  $SOSC \Leftrightarrow \nabla^2 f(u) \succ 0$ .  
( $\nabla^2 f$  is the Jacobian of  $\nabla f$ .)

By definition of discriminants, if

$$\Delta(f_{x_1}, \dots, f_{x_n}) \neq 0,$$

then  $\nabla f(x) = 0$  has no solution  $u$  with  $\nabla^2 f(u)$  singular:

$$\Delta(f_{x_1}, \dots, f_{x_n}) \neq 0 \Rightarrow SOSC.$$

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## How to Certify Exactness?

Lasserre's hierarchy is a sequence of lower bounds

$$f_1 \leq \cdots \leq f_k \leq \cdots \leq f_{min}$$

for the polynomial optimization

$$\begin{aligned} \min & f(x) \\ \text{s.t.} & (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0. \end{aligned}$$

The equality  $f_k = f_{min}$  is certified if a feasible  $x^*$  satisfies

$$f(x^*) = f_k.$$

Can we always find such  $x^*$  if finite convergence occurs?

**This is almost always possible!**



## Duality in Lasserre's Relaxations

For the polynomial optimization problem

$$\begin{aligned} \min \quad & f(x) \\ \text{s.t.} \quad & (h_1, \dots, h_{m_1})|_x = 0, (g_1, \dots, g_{m_2})|_x \geq 0. \end{aligned}$$

the  $k$ -th Lasserre's relaxation (**SOS version**) is:

$$\max \quad \gamma \quad \text{s.t.} \quad f - \gamma = \phi + \sigma g, \phi \in \langle h \rangle_{2k}, \sigma \in Q_k(g).$$

Its dual problem (**moment version**) is:

$$\begin{aligned} \min \quad & f^T y \quad \text{s.t.} \quad L_h^{(k)}(y) = 0 \quad (1 \leq i \leq m_1), y_0 = 1, \\ & L_{g_j}^{(k)}(y) \succeq 0 \quad (0 \leq j \leq m_2). \end{aligned}$$

where  $L_p^{(k)}(y)$  denotes the  $k$ -th **localizing matrix** of a poly  $p$  and a moment vector  $y$ .

## Flat Truncation (FT)

Suppose  $y^*$  is a minimizer of the dual optimization problem:

$$\min f^T y \quad s.t. \quad \begin{aligned} L_h^{(k)}(y) &= 0 \quad (1 \leq i \leq m_1), \quad y_0 = 1, \\ L_{g_j}^{(k)}(y) &\succeq 0 \quad (0 \leq j \leq m_2). \end{aligned}$$

We say  $y^*$  has a **flat truncation (FT)** or FT holds at  $y^*$  if

$$\text{rank } M_t(y^*) = \text{rank } M_{t-d}(y^*) \quad \text{for some } t \in [d, k]$$

where  $d = \max\{1, \lceil \deg(h)/2 \rceil, \lceil \deg(g)/2 \rceil\}$ .

FT  $\Rightarrow y^*|_{2t}$  admits a finite measure (Curto-Fialkow).

FT  $\Rightarrow$  global minimizers can be found (Henrion-Lasserre).

## FT Holds Generally

Suppose  $y^*$  is a minimizer of the  $k$ -th Lasserre's relax.:

$$\min \quad \sum f^T y \quad s.t. \quad L_h^{(k)}(y) = 0 \quad (1 \leq i \leq m_1), \quad y_0 = 1, \\ L_{g_j}^{(k)}(y) \succeq 0 \quad (0 \leq j \leq m_2).$$

**Theorem** (N. 2011) If the optimization problem

$$\min \quad f(x) \\ s.t. \quad (h_1, \dots, h_{m_1})|_x = 0, \quad (g_1, \dots, g_{m_2})|_x \geq 0.$$

has **finitely** many global KKT points, then **FT holds for every** minimizer  $y^*$  for some order  $k$ .

Generically, FT can be used as a certificate to check finite convergence of Lasserre's hierarchy.

## The main conclusion of this talk

For generic cases, Lasserre's hierarchy has finite convergence.

## What can we do for nongeneric cases?

Apply **Jacobian SDP relaxation**! It **always** has finite convergence if only the feasible sets are smooth, no matter what the objectives are.

**Thank you very much for attention!**