



Computing rare event properties by discretization and optimal control

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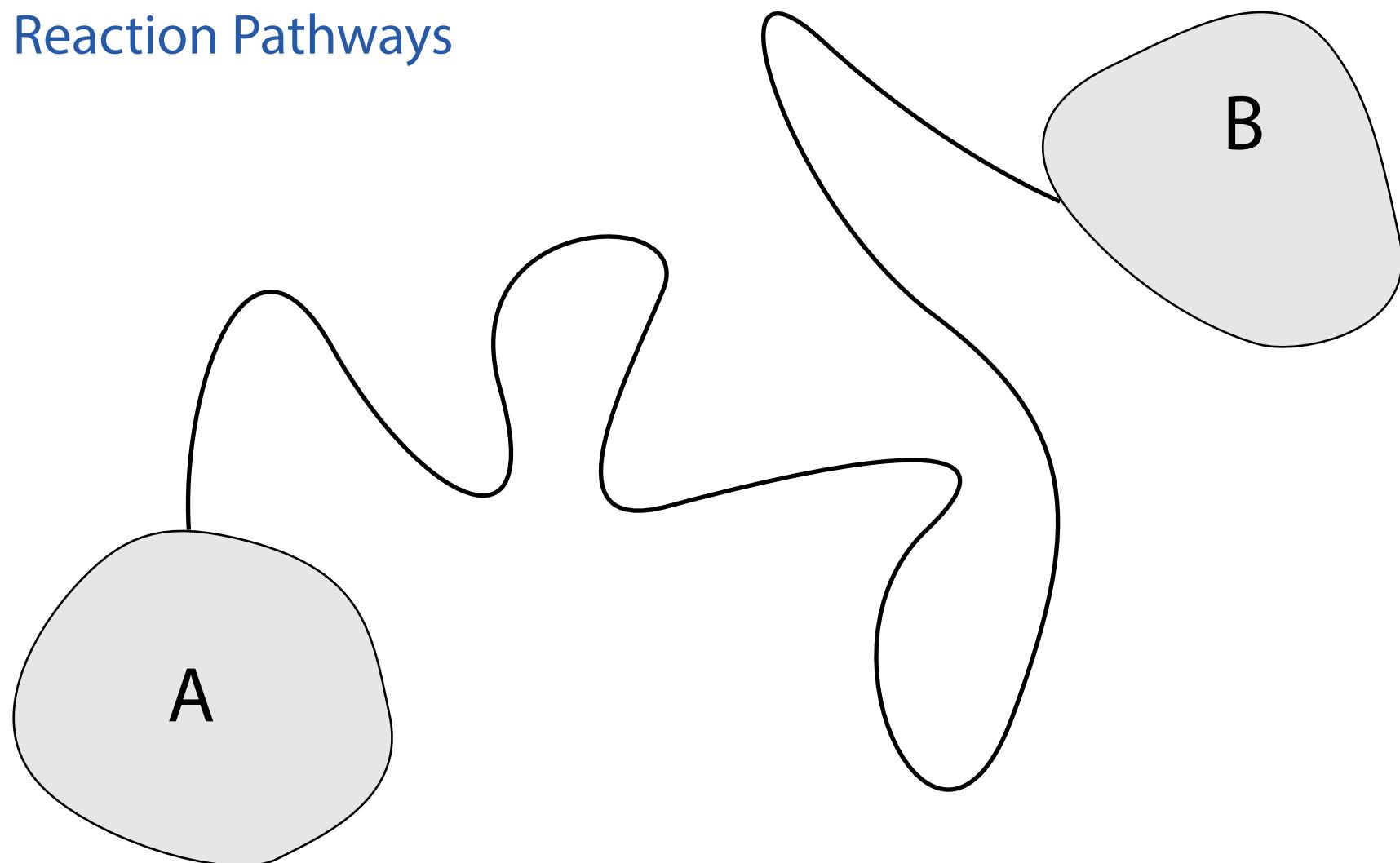
Freie Universität Berlin

DFG Research Center MATHEON
Mathematics for key technologies



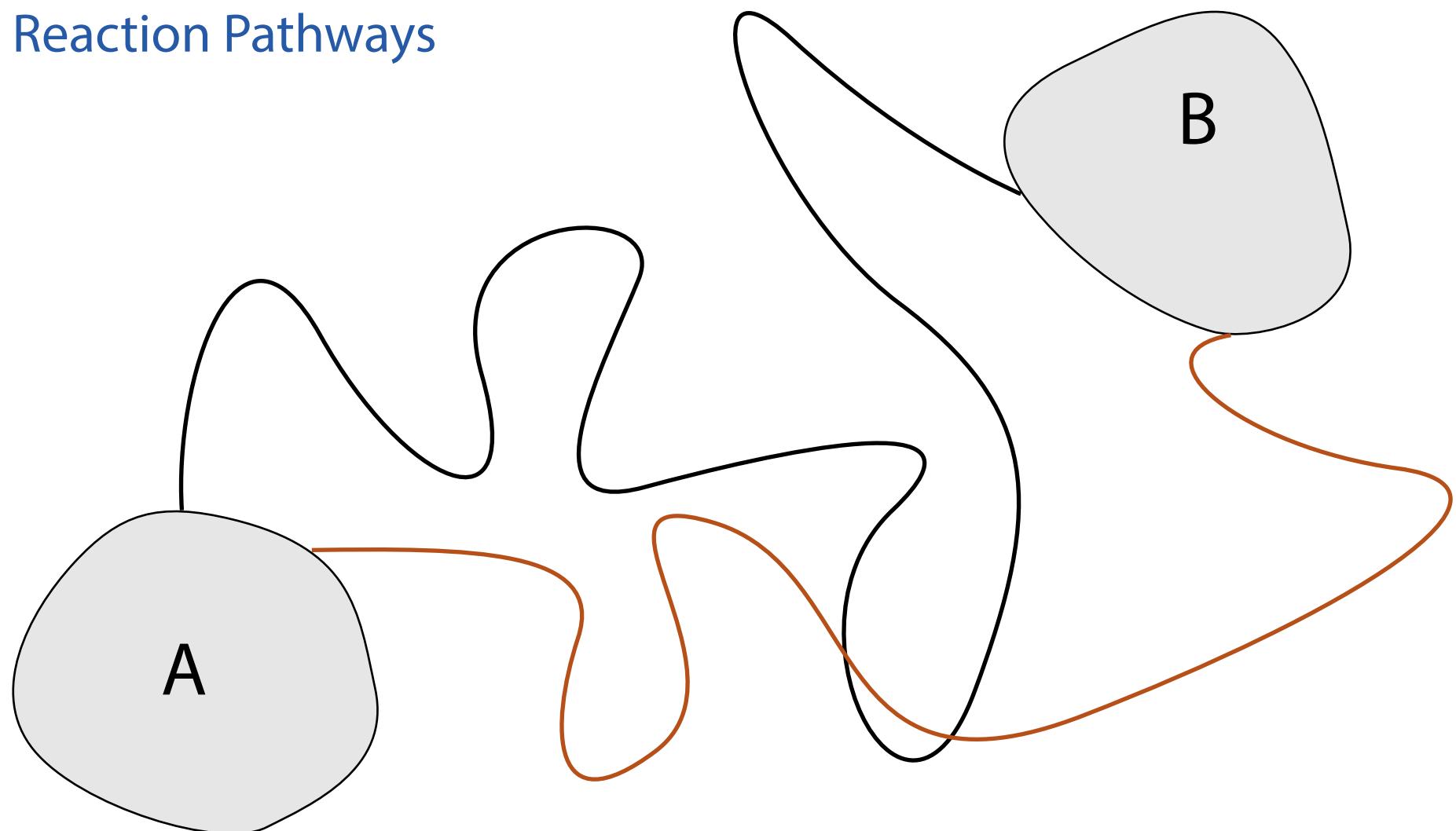


Reaction Pathways





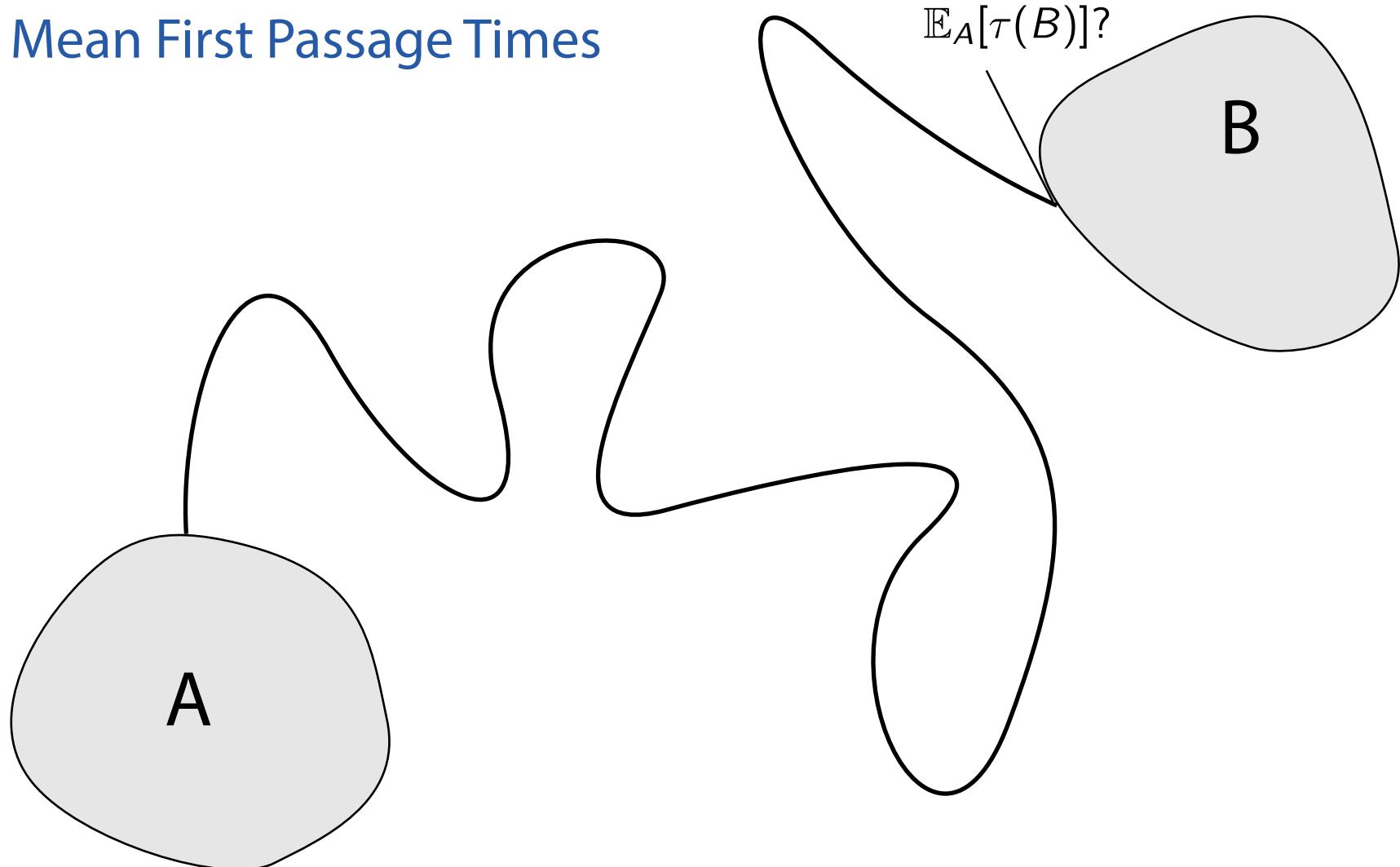
Reaction Pathways



What are the dominant reaction pathways from set *A* to set *B*?



Mean First Passage Times

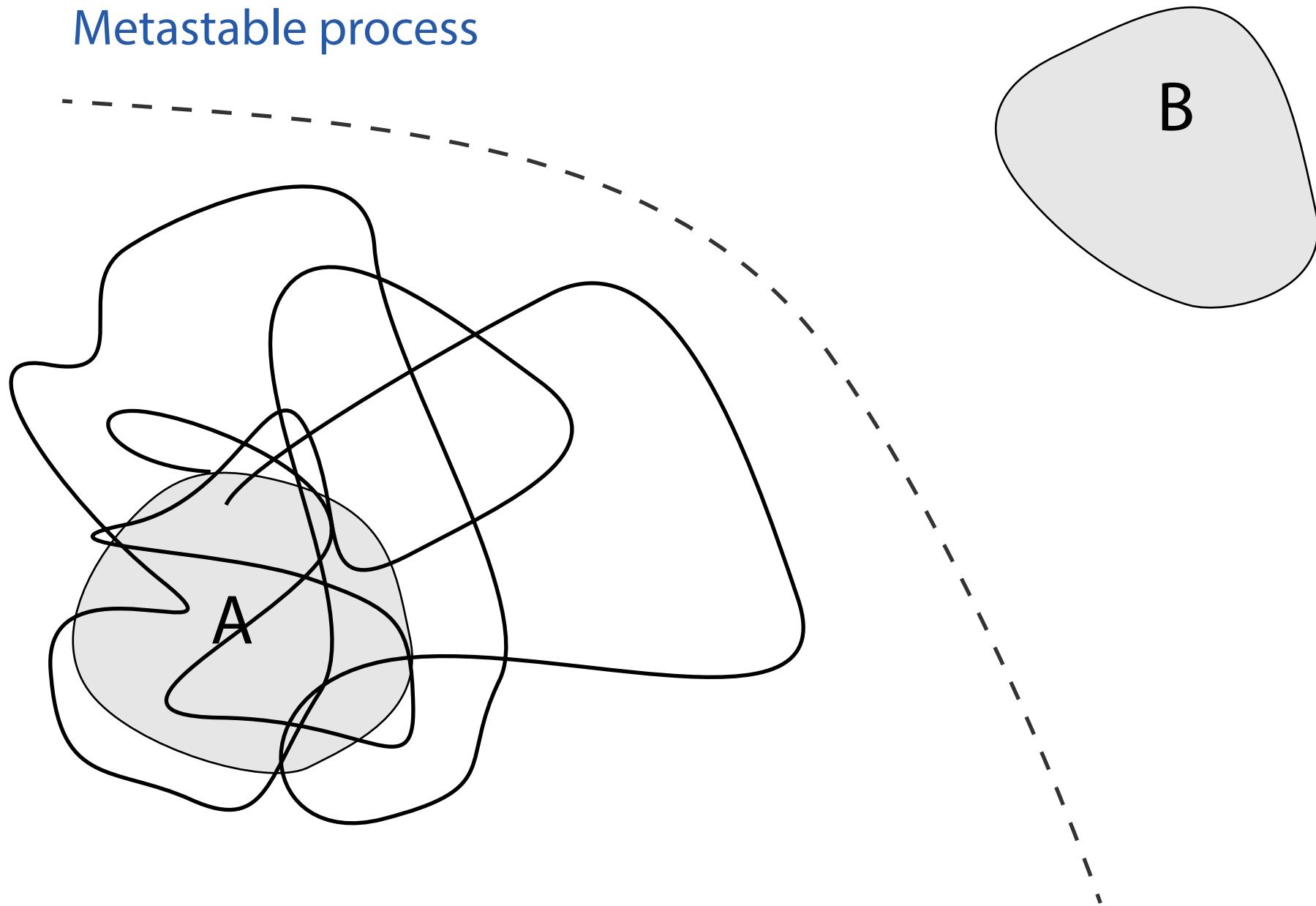


$$\tau(B) = \inf\{t \geq 0, X_t \in B\}$$



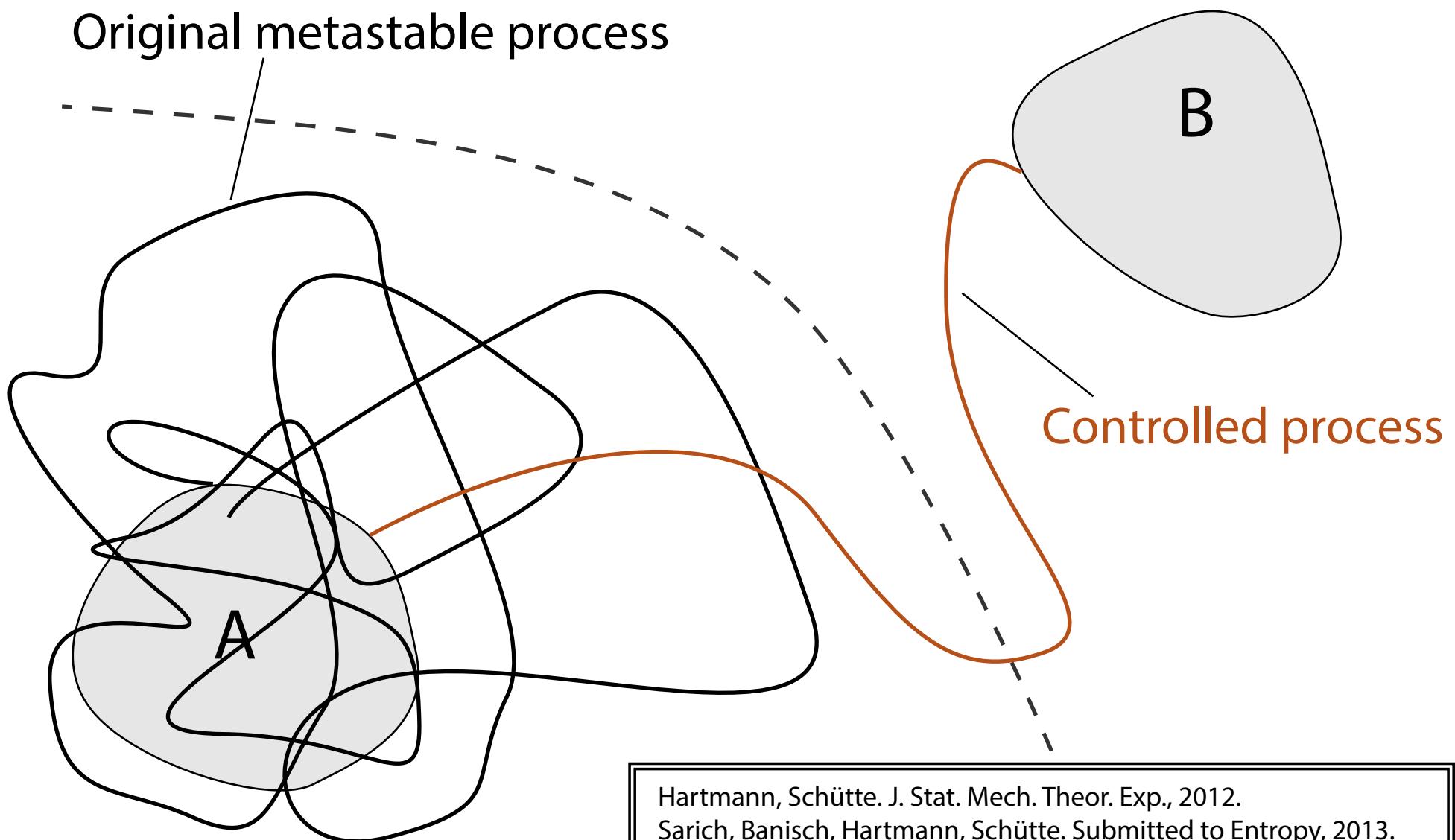
Sampling problem: Metastability leads to rare events

Metastable process



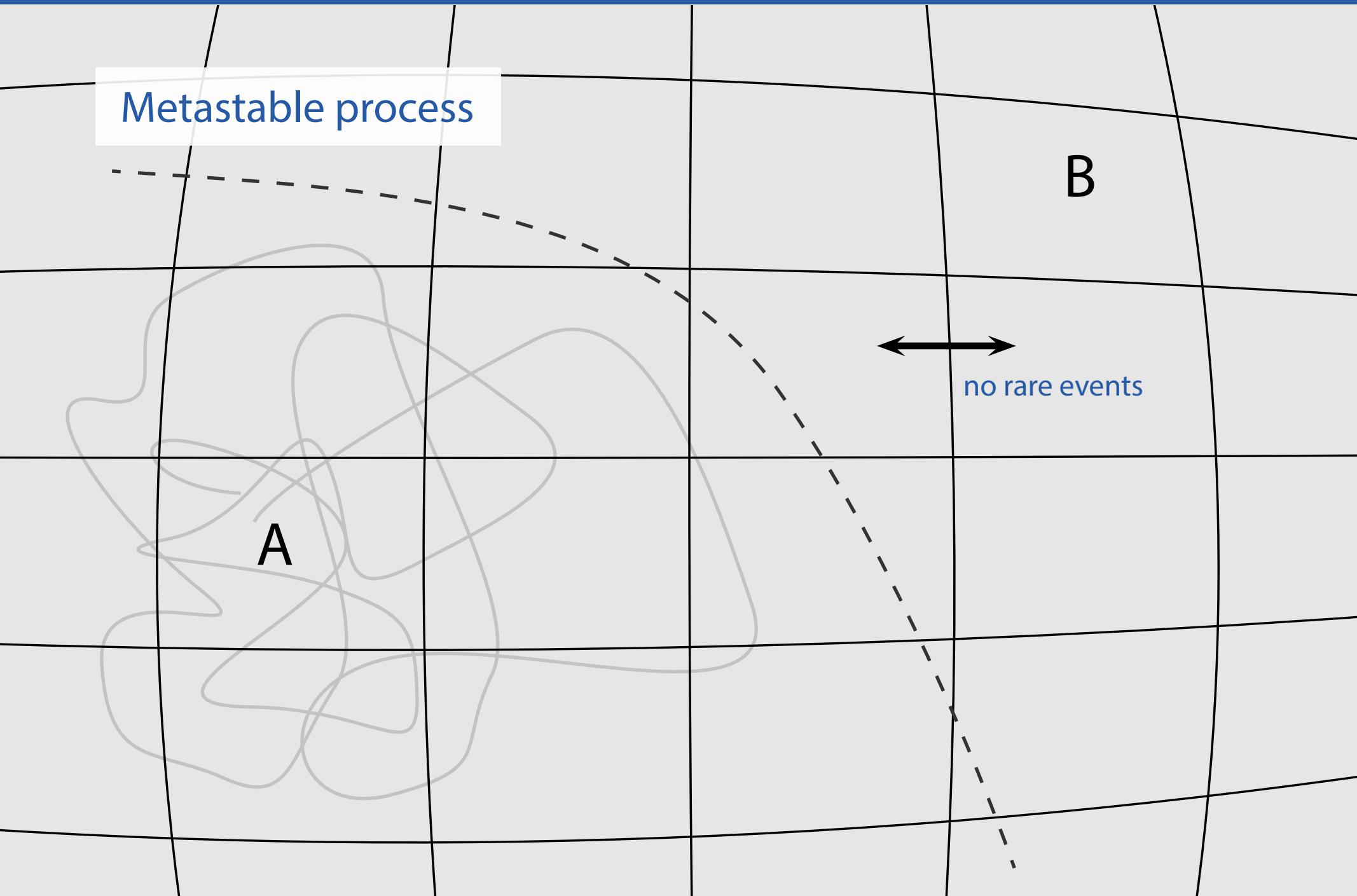


The optimal control approach





The discretization approach





For a Markov chain (\hat{X}_n) with transition matrix P :

The mean first passage times

$$m(i) = \mathbb{E}[\tau(B) \mid X_0 = i]$$

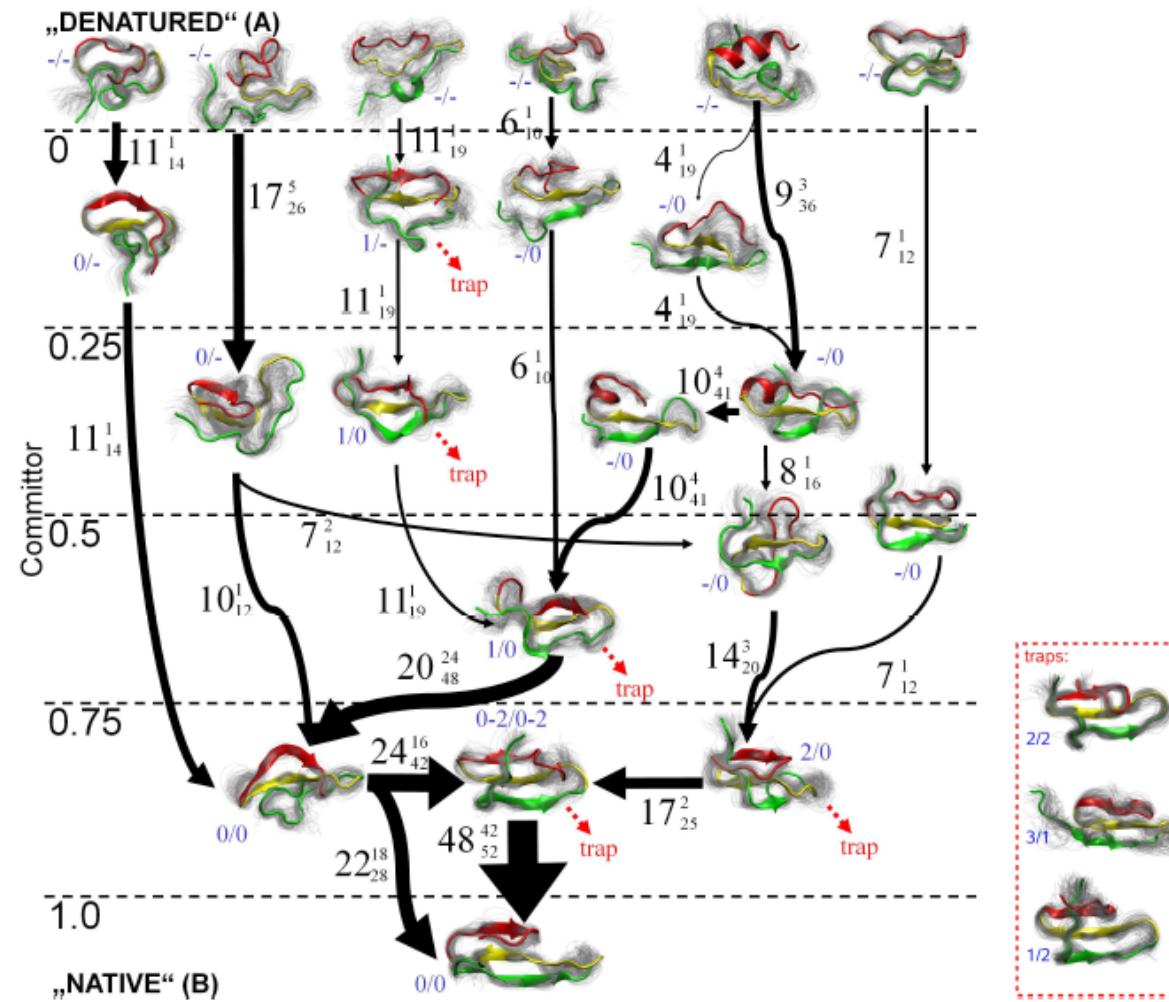
can be computed without sampling

$$\begin{aligned}(P - I)m &= -\mathbb{1}, && \text{on } B^c, \\ m &= 0, && \text{on } B.\end{aligned}$$



Tools for finite state space Markov chains

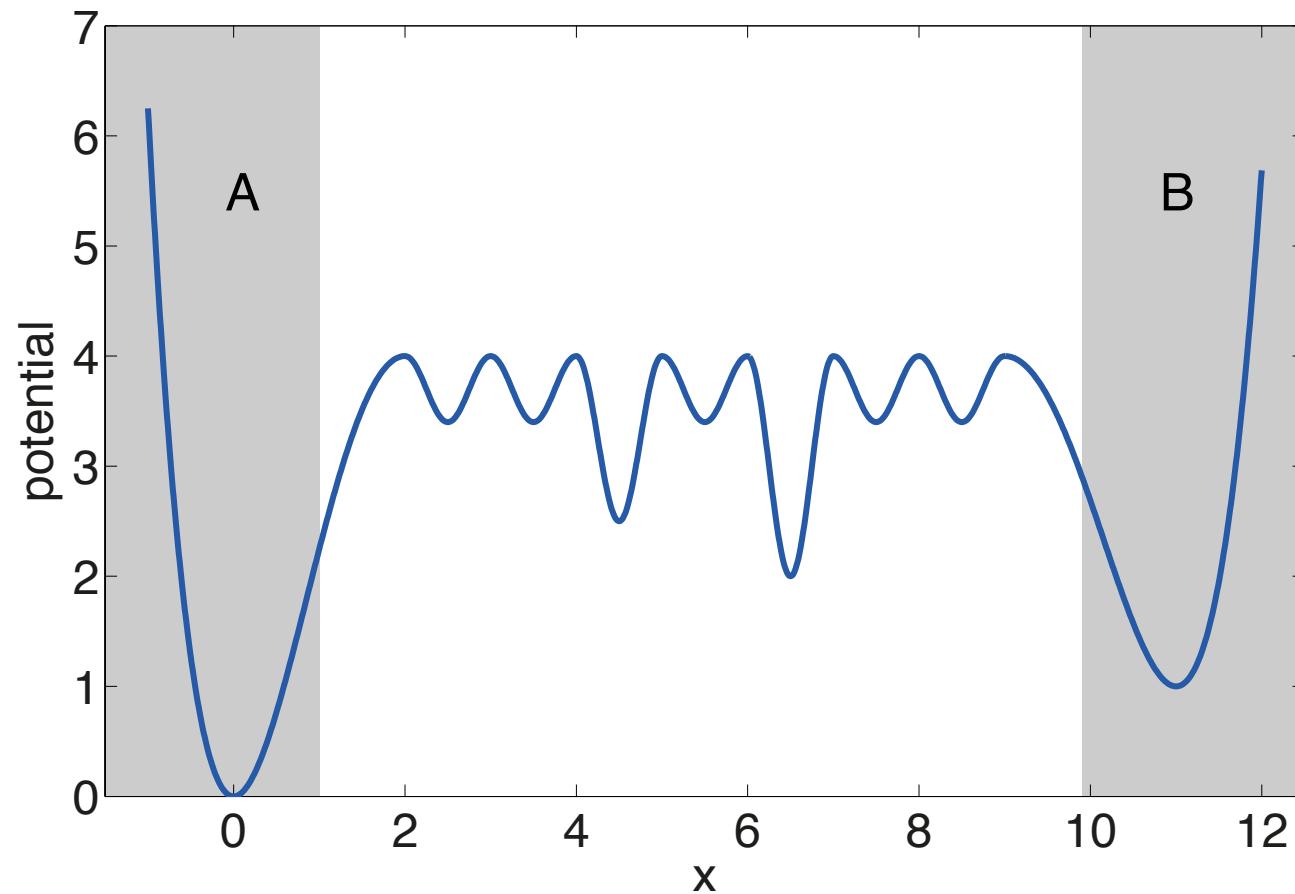
Also the statistics of transition pathways can be computed without sampling by using transition path theory (TPT).



Noé, Schütte, Vanden-Eijnden, Reich, Weikl, PNAS, 2009.

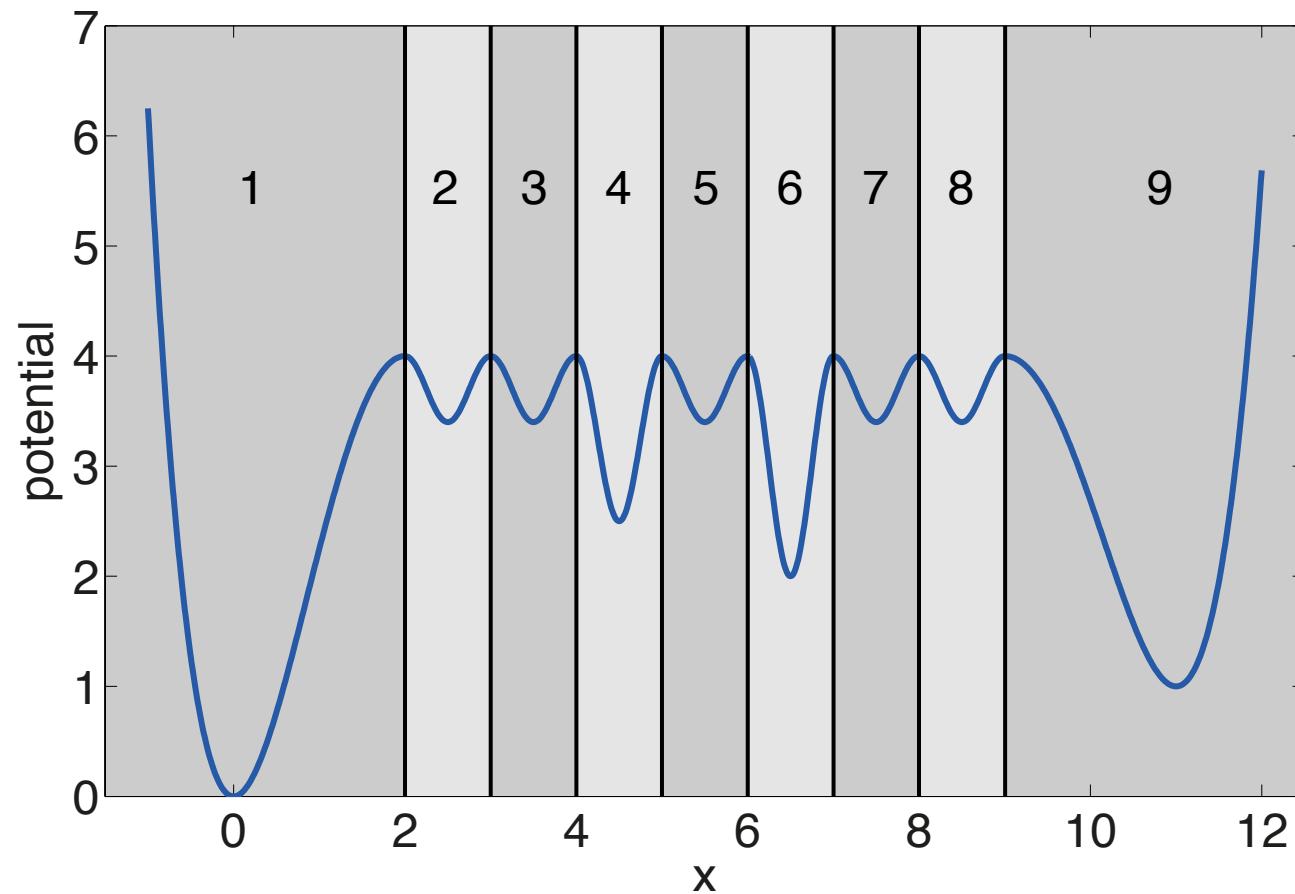


$$dX_t = -\nabla V(X_t)dt + \sigma dB_t$$





Cluster state space into sets A_1, \dots, A_n and consider
 $P_{ij} = \mathbb{P}_\mu[X_\tau \in A_j | X_0 \in A_i]$.





$$D = \text{span}\{\mathbb{1}_{A_1}, \dots, \mathbb{1}_{A_n}\}$$

Q - orthogonal projection onto D

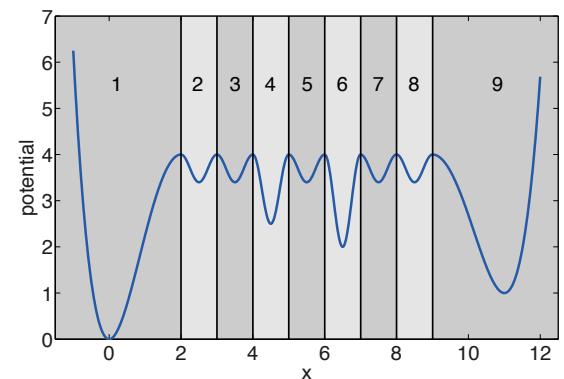
P can be considered as projection of the original **transfer operator** of the system

$$QT : D \rightarrow D,$$

$$T := T_\tau = e^{L\tau}, \quad (Lv)(x) = \frac{1}{2}\sigma^2 \Delta v(x) - \nabla V(x) \cdot \nabla v(x).$$



Example: Implied timescales



$$\eta_i = -\frac{\tau}{\log \lambda_i}$$

λ_i - largest eigenvalues of transfer operator or its projection

	η_1	η_2	η_3	η_4
original	17.5267	3.1701	0.9804	0.4524
full partition	16.5478	2.9073	0.8941	0.4006



Theorem

Let T be a self-adjoint transfer operator and Q the orthogonal projection to a subspace D with $\mathbb{1} \in D$. Let λ be an eigenvalue of T , u a corresponding normalized eigenvector, and set $\delta = \|u - Qu\|$. Then there exists an eigenvalue $\hat{\lambda}$ of the projected transfer operator QT with

$$|\lambda - \hat{\lambda}| \leq \lambda_1 \delta (1 - \delta^2)^{-\frac{1}{2}},$$

where $\lambda_1 < 1$ is the largest non-trivial eigenvalue of T .

In particular, for $\delta \leq \frac{3}{4}$ one can simplify the equation to

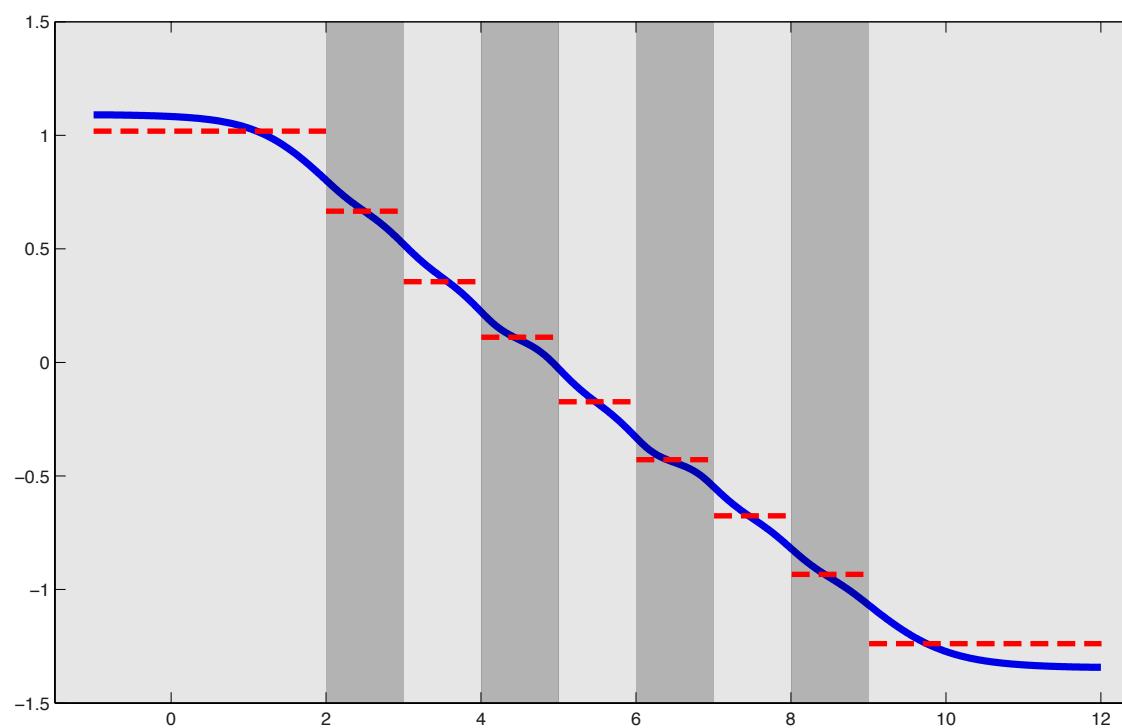
$$|\lambda - \hat{\lambda}| \leq 2\lambda_1 \delta.$$

Sarich, Schütte. Comm. Math. Sci., 2012.



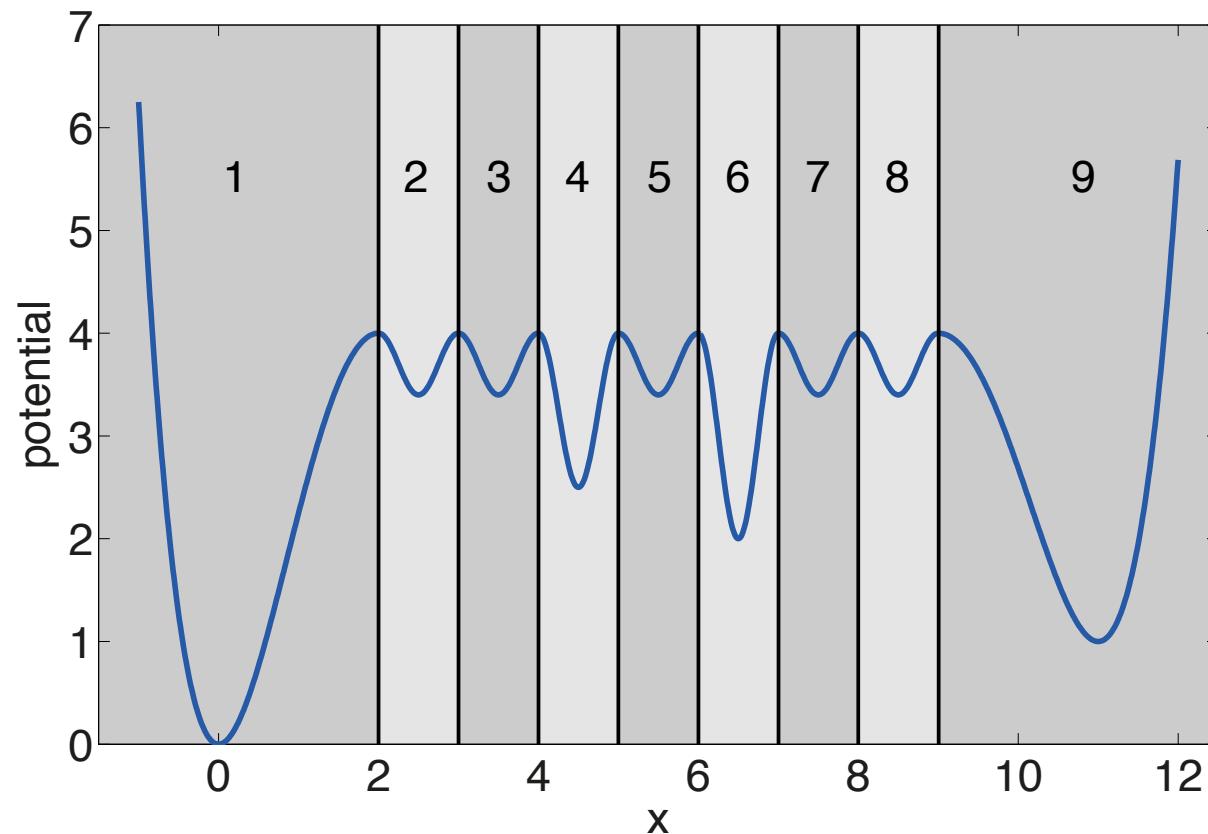
Projection error for the example

	η_1	η_2	η_3	η_4
original	17.5267	3.1701	0.9804	0.4524
full partition	16.5478	2.9073	0.8941	0.4006



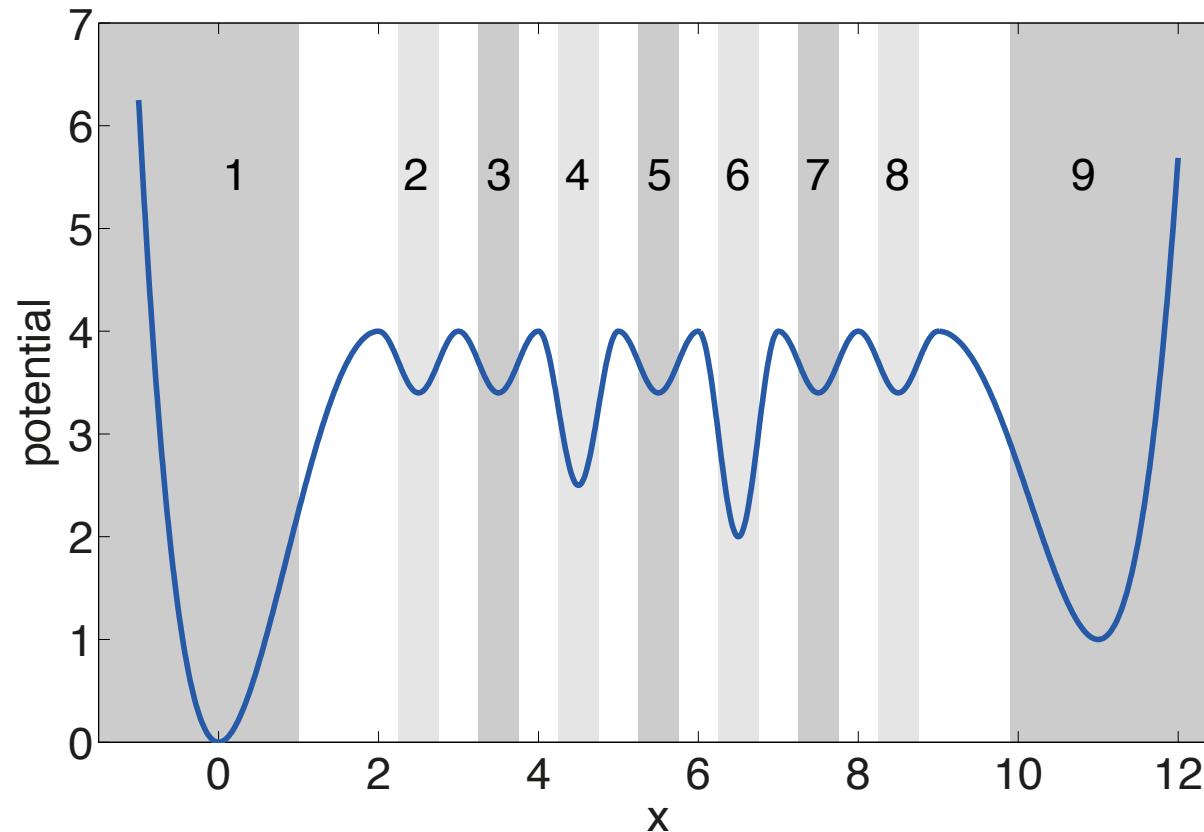


Use instead of a full partition....



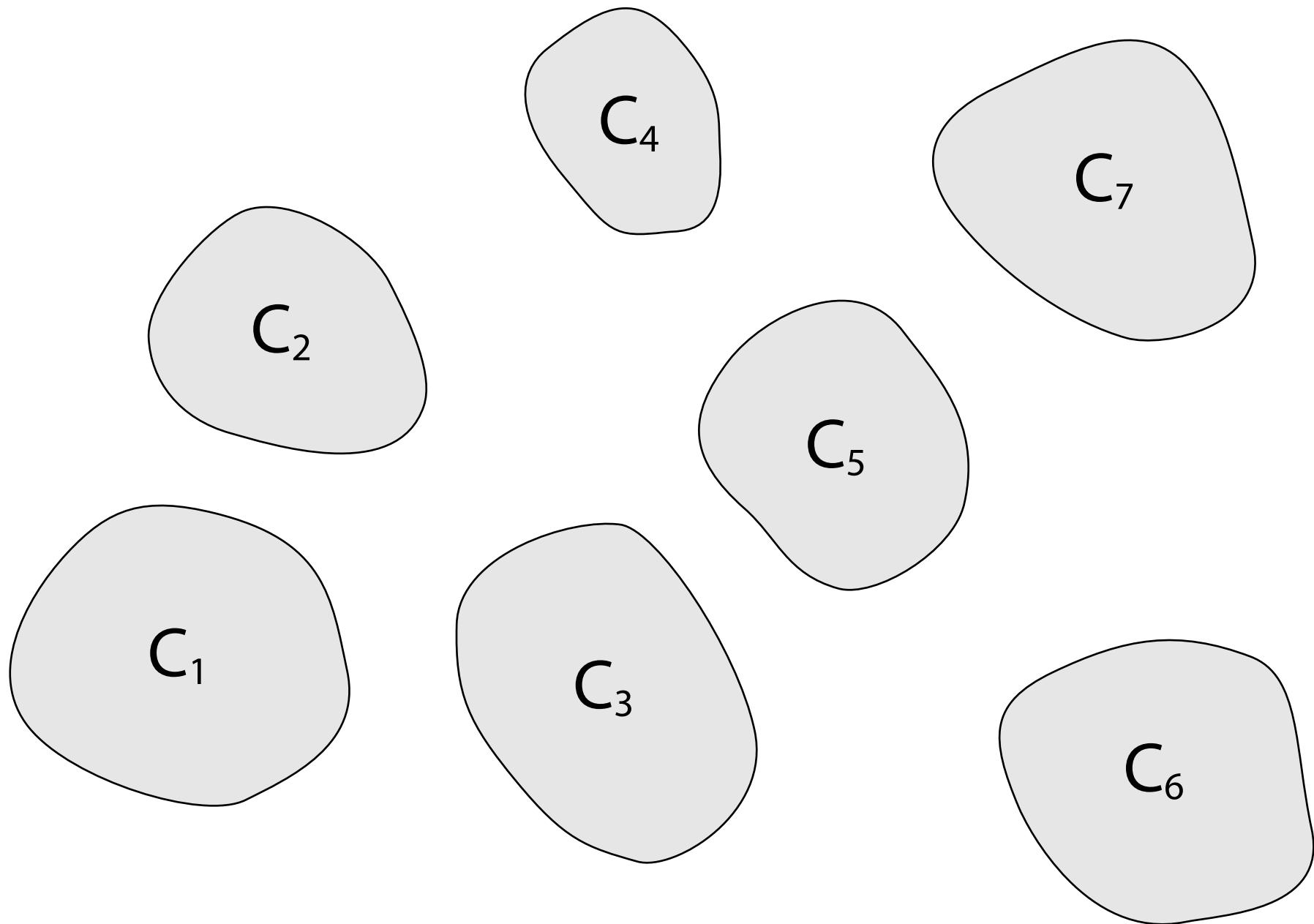


...so called **core sets** by cutting out a transition region.





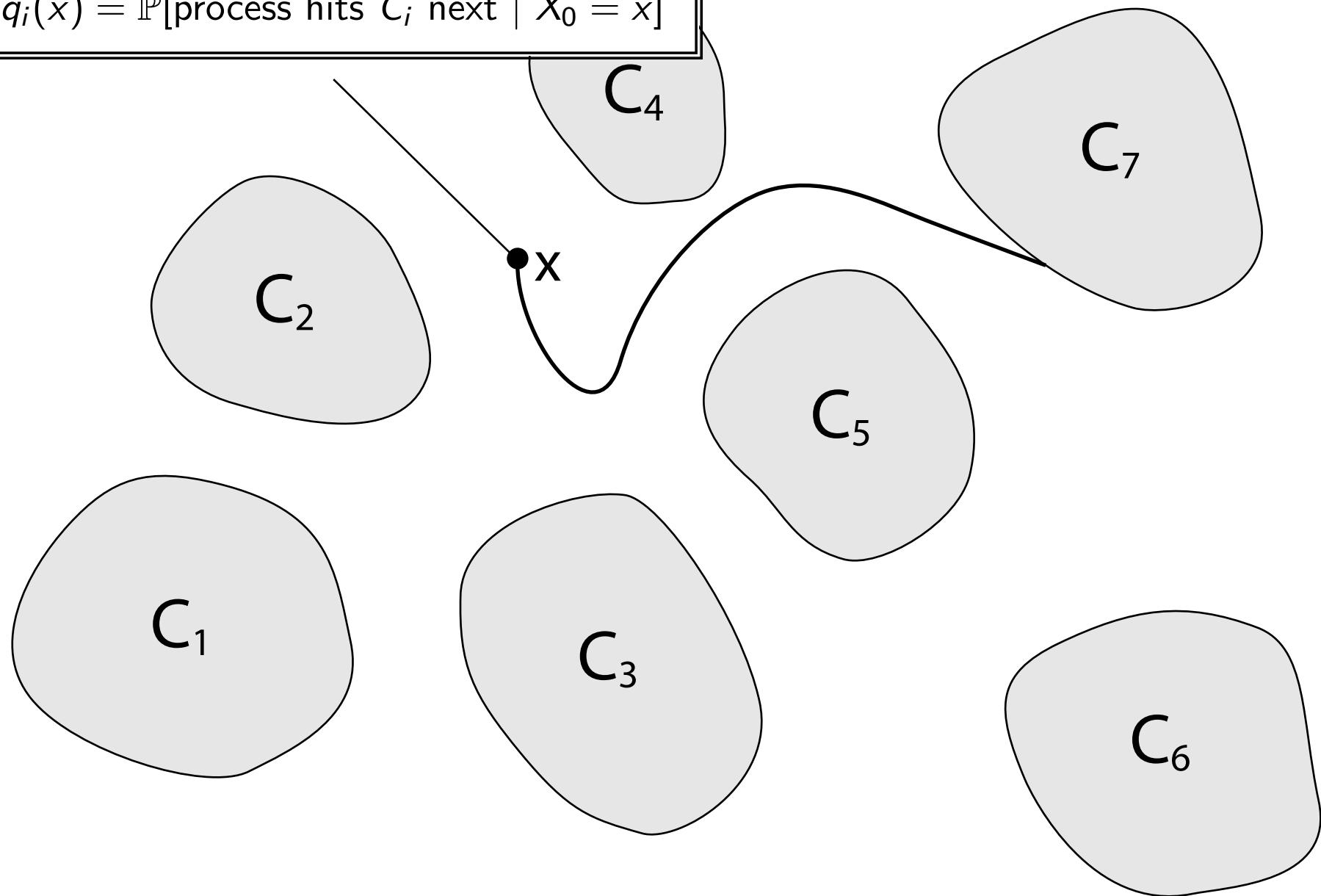
The core set approach





The core set approach and committors

$$q_i(x) = \mathbb{P}[\text{process hits } C_i \text{ next} \mid X_0 = x]$$



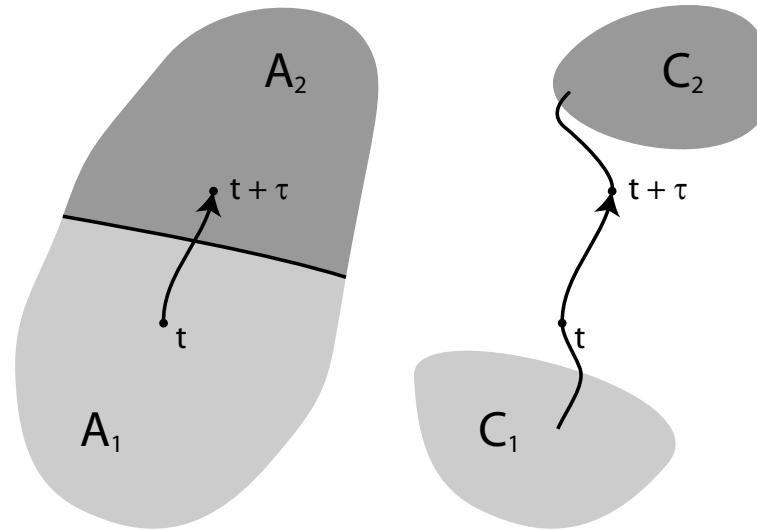


Projection of transfer operator QT onto $D = \text{span}\{q_1, \dots q_n\}$ leads to matrix $P = \hat{T}M^{-1}$ with

$M_{ij} = \mathbb{P}[\text{after time } t \text{ process will hit next } C_j \mid \text{at time } t \text{ process came last from } C_i]$

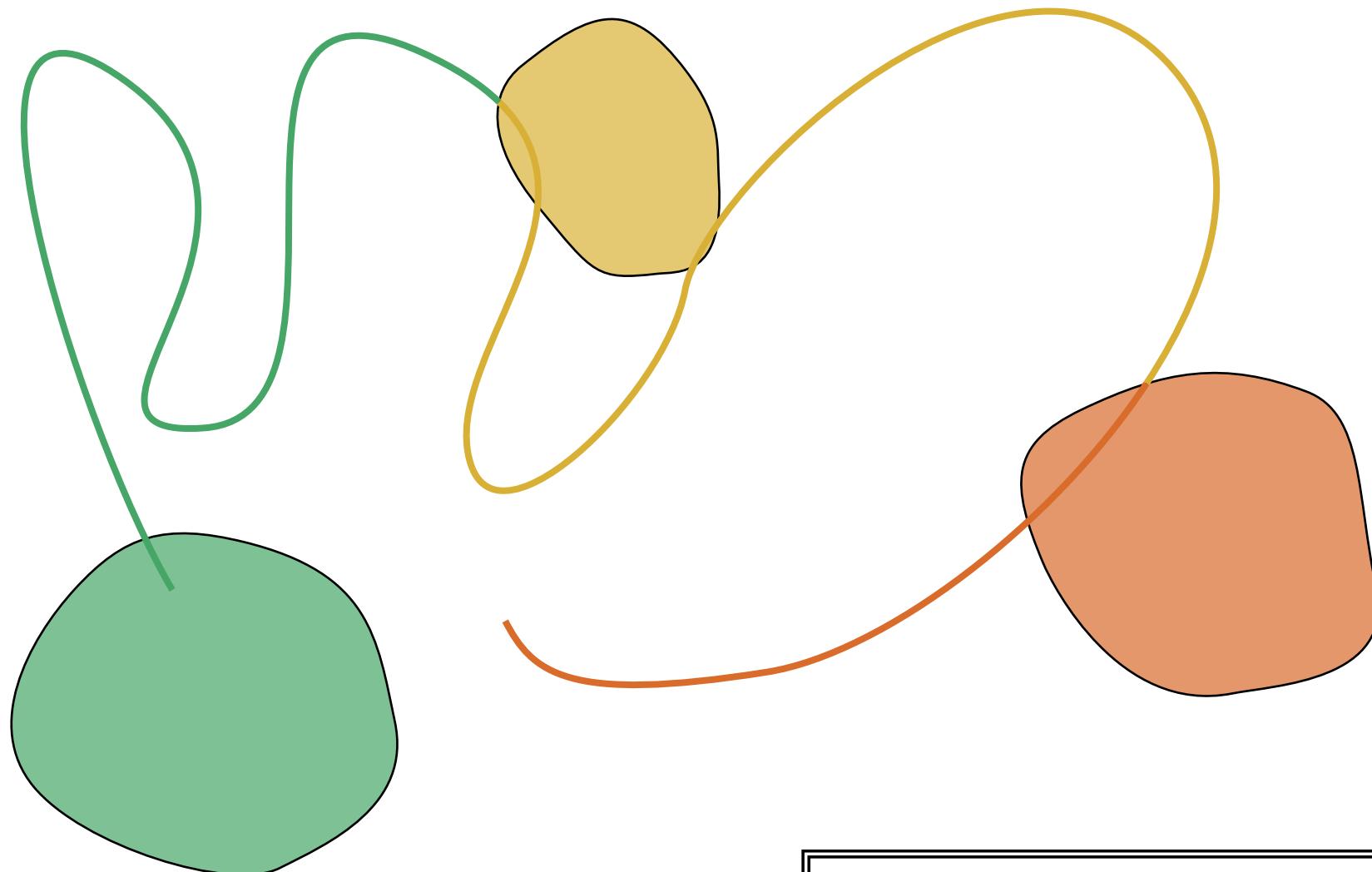
and

$\hat{T}_{ij} = \mathbb{P}[\text{after time } t + \tau \text{ process will hit next } C_j \mid \text{at time } t \text{ process came last from } C_i].$





Transition behaviour in terms of milestoning



Ch. Schütte, F. Noé, J. Lu, M. Sarich, and E. Vanden-Eijnden.
Markov State Models Based on Milestoning. *J. Chem. Phys.*,
134 (20). 204105, 2011.



...and it can be proven to be more accurate!

$$\|u - Q_{cores} u\| \leq \|u - Q_{full} u\| - \|(u - Q_{full} u)|_C\| + \frac{\rho}{\eta},$$

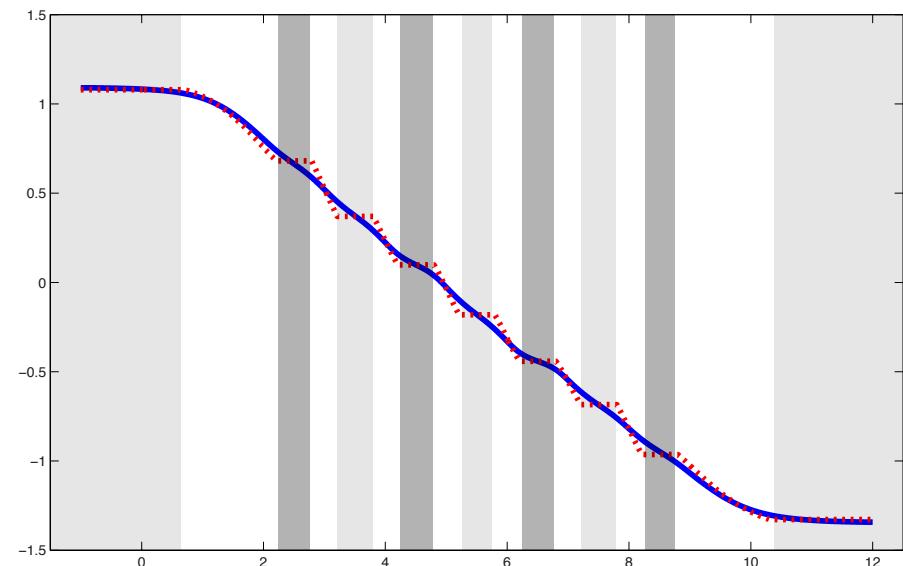
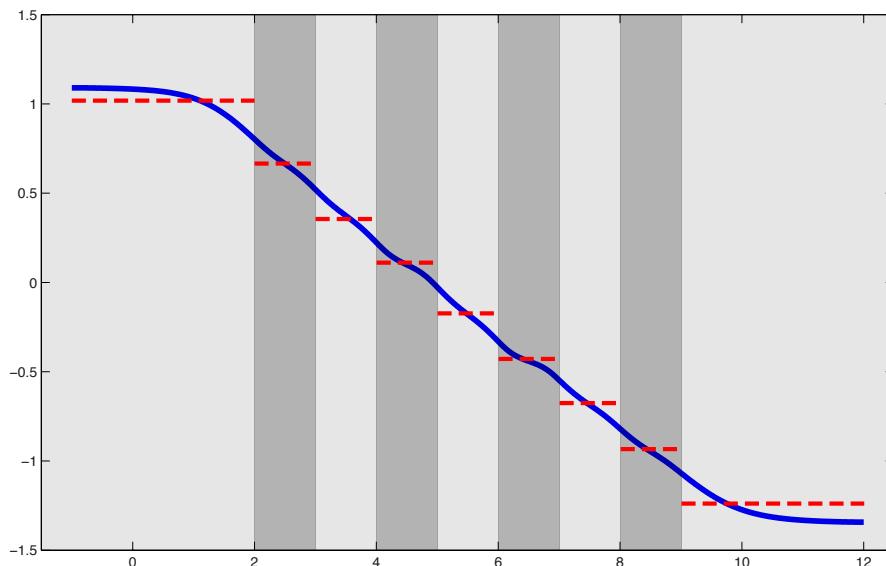
- ▶ $\rho \leq \max_{x \in C} \mathbb{E}_x[\tau(C^c)]$
- ▶ η implied timescale belonging to u
- ▶ C region that is cut out

Sarich, Schütte. Comm. Math. Sci., 2012.



Example

	η_1	η_2	η_3	η_4
original	17.5267	3.1701	0.9804	0.4524
core sets	17.3298	3.1332	0.9690	0.4430
full partition	16.5478	2.9073	0.8941	0.4006

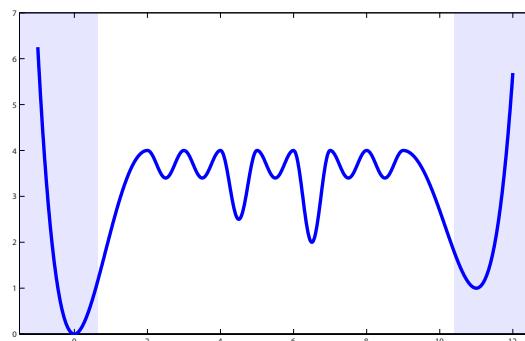




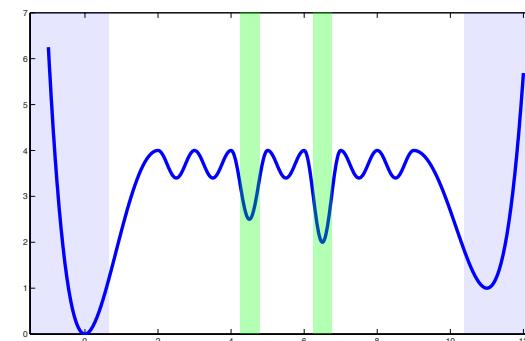
Using a multigrid

Let $\mathcal{C}_j = \{C_1^j, \dots, C_{n_j}^j\}$ be an increasing sequence of core set discretizations, i.e.

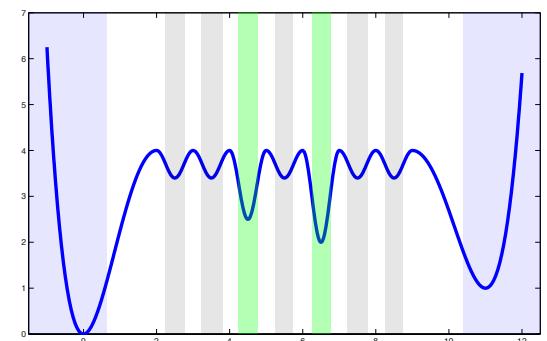
$$\mathcal{C}_i \subset \mathcal{C}_j \text{ for all } j \geq i.$$



Level 1



Level 2



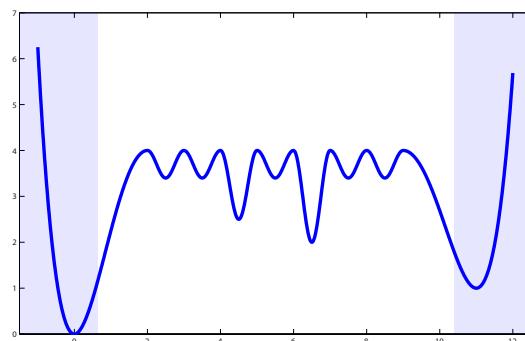
Level 3



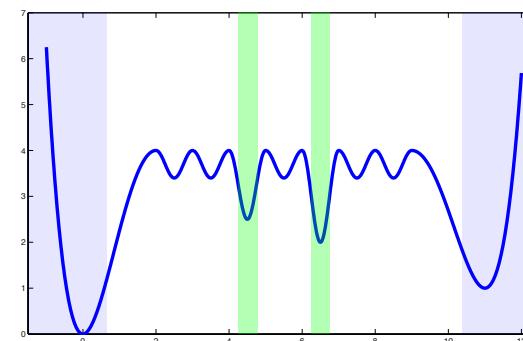
Using a multigrid

Let $\mathcal{C}_j = \{C_1^j, \dots, C_{n_j}^j\}$ be an increasing sequence of core set discretizations, i.e.

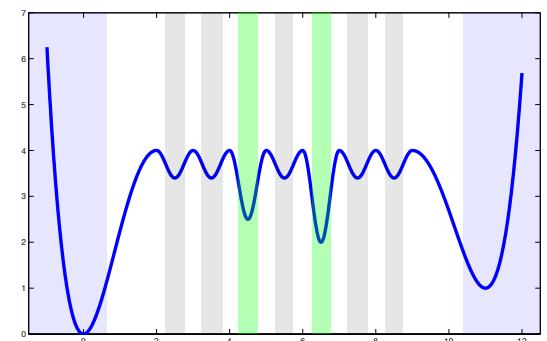
$$\mathcal{C}_i \subset \mathcal{C}_j \text{ for all } j \geq i.$$



Level 1



Level 2



Level 3

Iterative Space Construction

Level 1: $D_1 = \text{span}\{q_1, \dots, q_n\}$, q_i usual committors.

Level $k + 1$: $D_{k+1} = \hat{D}_{k+1} \cap D_k^\perp$, where \hat{D}_{k+1} is the usual committor space for the cores on level $k + 1$.

Total space for projection with m levels: $D = D_1 + \dots + D_m$



Computing the model

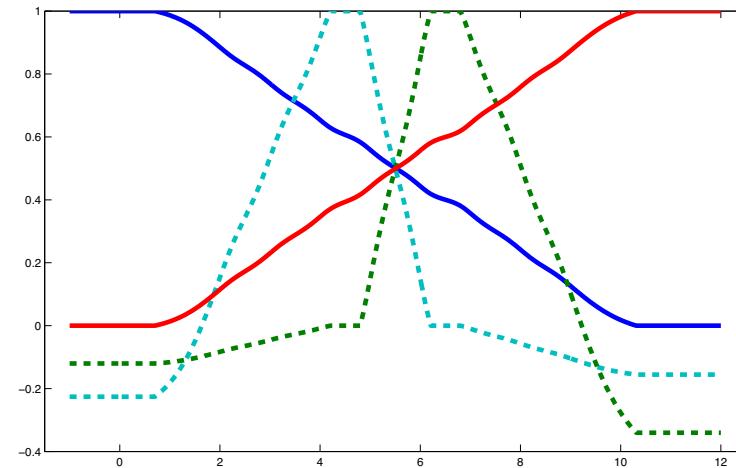
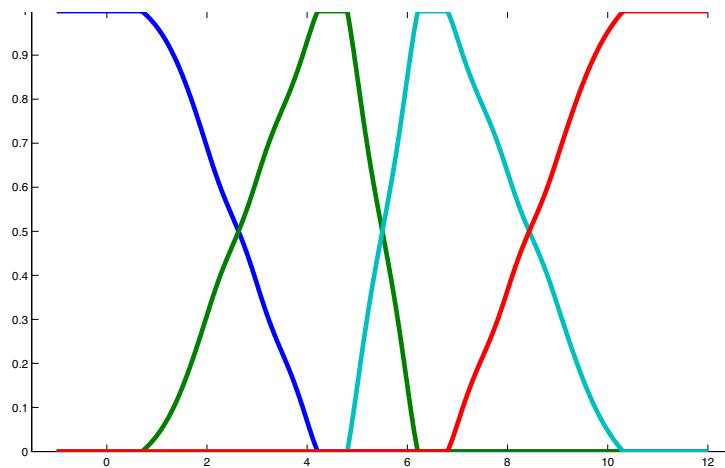
A matrix representation $P = \hat{T}M^{-1}$ can again be computed from stochastic quantities.

Assume C_i was first introduced on level k and C_j was first introduced on level l , then

$$M_{ij} = \mathbb{P}[\text{hit } C_j \text{ next on level } l \mid \text{came from } C_i \text{ on level } k].$$



Good approximation along multiple timescales



Mutilevel committors for 4 sets
and 2 levels.

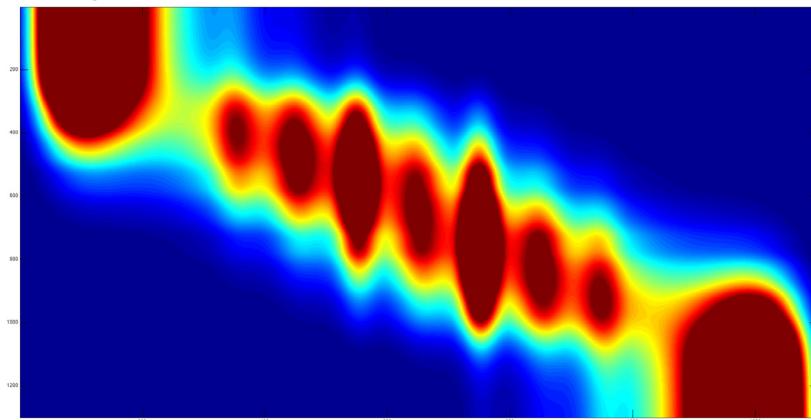
Example

	T_1	T_2	T_3	T_4
original	17.5267	3.1701	0.9804	0.4524
9 cores multigrid	17.5043	3.1579	0.9703	0.4441
9 core sets	17.3298	3.1332	0.9690	0.4430
full partition	16.5478	2.9073	0.8941	0.4006
2 core sets	17.5043	-	-	-

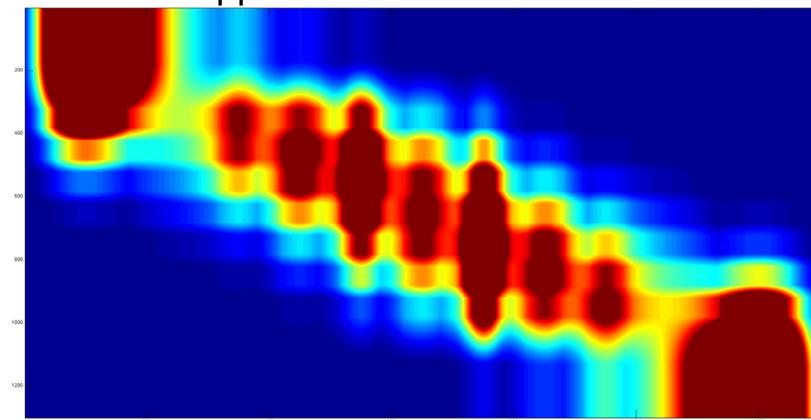


Smoother approximation of the transfer operator

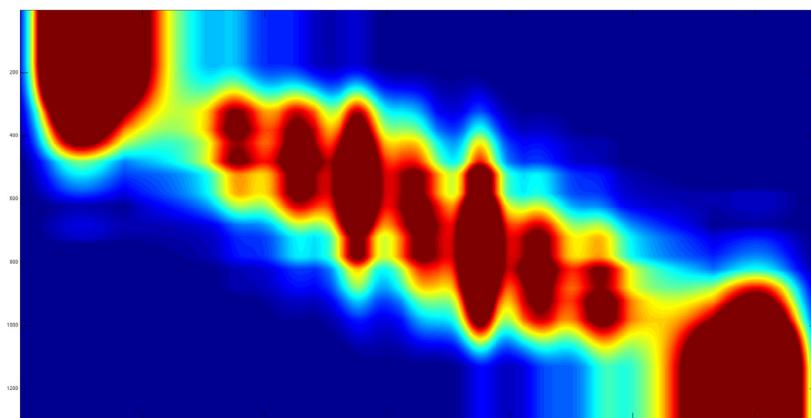
Original transfer operator



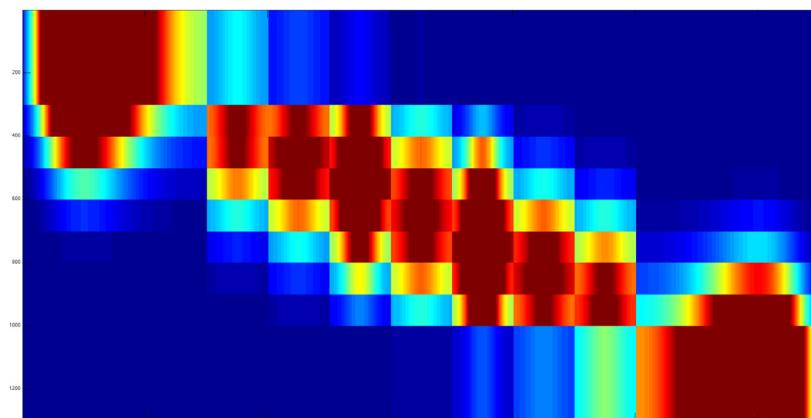
Core set approximation

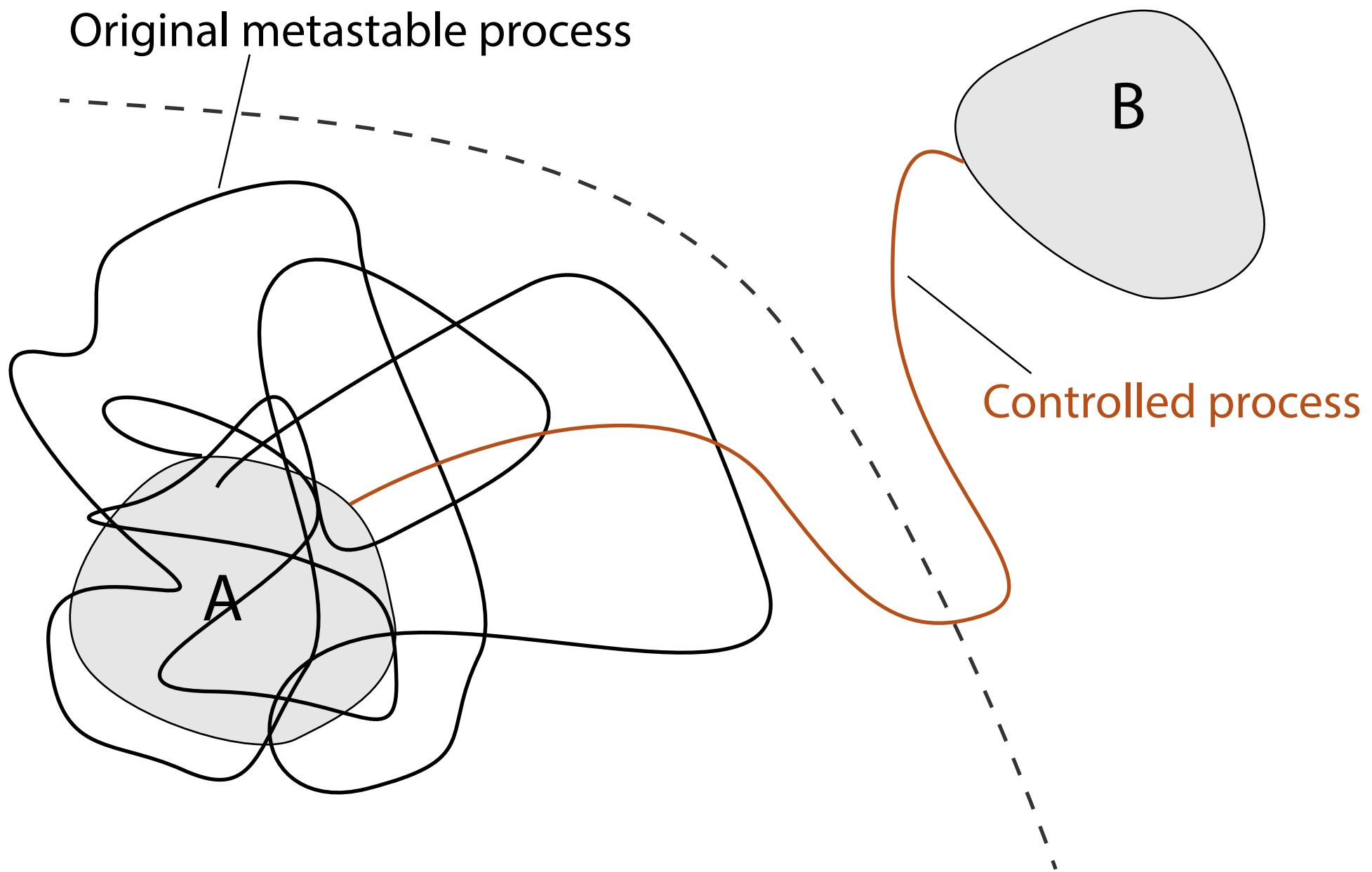


Multigrid approximation



Full partition approximation







$$dX_t = -\nabla V(X_t)dt + \sqrt{2\epsilon}dB_t$$

Cumulant generating function

$$J(x) = -\epsilon \log \mathbb{E}_x[\exp(-\tau(B)/\epsilon)] = \mathbb{E}_x[\tau(B)] + \epsilon$$



$$dX_t = -\nabla V(X_t)dt + \sqrt{2\epsilon}dB_t$$

Cumulant generating function

$$\begin{aligned} J(x) &= -\epsilon \log \mathbb{E}_x[\exp(-\tau(B)/\epsilon)] = \mathbb{E}_x[\tau(B)] + \epsilon \\ &= \min_{u \in U} \mathbb{E}_x^{\mathbb{P}_u} \left[\tau(B) + \int_0^{\tau(B)} \frac{1}{2} \|u_s\|^2 ds \right], \end{aligned}$$

where \mathbb{P}_u is the path measure belonging to

$$dX_t = (\sqrt{2}u_t - \nabla V(X_t))dt + \sqrt{2\epsilon}dB_t.$$



If J is smooth enough, $u_t = -\sqrt{2}\nabla J(X_t)$ is the unique minimizer.

$$J(x) = \mathbb{E}_x^{\mathbb{P}_u} \left[\tau(B) + \int_0^{\tau(B)} \|\nabla J(X_s)\|^2 ds \right]$$

where \mathbb{P}_u is the path measure belonging to

$$dX_t = -\nabla U(X_t)dt + \sqrt{2\epsilon}dB_t, \quad U(x) = V(x) + 2J(x).$$



$$J(x) = \mathbb{E}_x^{\mathbb{P}_u} \left[\tau(B) + \int_0^{\tau(B)} \|\nabla J(X_s)\|^2 ds \right] =: (\mathcal{A}J)(x).$$

Idea

Fixed point iteration for the function \mathcal{A} on a finite dimensional ansatz space, i.e. assuming

$$J(x) = \sum_{i=1}^n a_i \phi_i(x).$$



Another option

Writing

$$J(x) = -\epsilon \log \psi(x).$$

Then, ψ solves the linear system

$$(L - \epsilon^{-1} \mathbb{1}_B) \psi = 0$$

$$\psi|_B = 1.$$



Optimal control via Markov State Model

Another option

Writing

$$J(x) = -\epsilon \log \psi(x).$$

Then, ψ solves the linear system

$$(L - \epsilon^{-1} \mathbb{1}_B) \psi = 0$$

$$\psi|_B = 1.$$

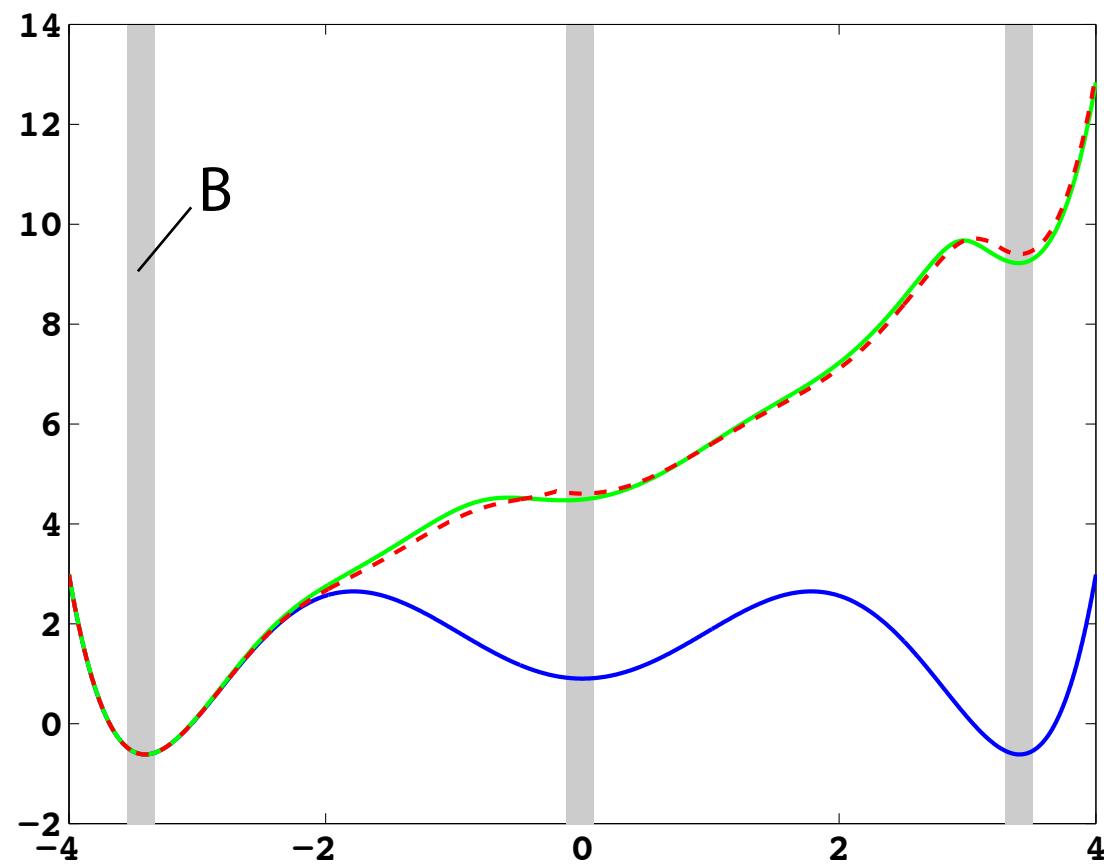


Approximation by a
Markov State Model
possible!

Hartmann, Schütte. J. Stat. Mech. Theor. Exp., 2012.
Sarich, Banisch, Hartmann, Schütte. Submitted to Entropy, 2013.



Optimal control example



optimal control as lifted potential



computed via core set MSM using three core sets (grey)



Ch. Schütte and M. Sarich. Metastability and Markov State Models in Molecular Dynamics: Modeling, Analysis, Algorithmic Approaches. Courant Lecture Notes 24, AMS, CIMS, 2013.

M. Sarich, R. Banisch, C. Hartmann, Ch. Schütte. Markov State Models for Rare Events in Molecular Dynamics. Entropy Special Issue „Molecular Dynamics Simulation”, 2013.

C. Hartmann, R. Banisch, M. Sarich, T. Badowski, and Ch. Schütte. Characterization of Rare Events in Molecular Dynamics. Entropy Special Issue „Molecular Dynamics Simulation”, 2013.

M. Sarich and Ch. Schütte. Approximating Selected Non-dominant Timescales by Markov State Models. Comm. Math. Sci., 10 (3). pp. 1001-1013, 2012.

Ch. Schütte, F. Noé, J. Lu, M. Sarich, and E. Vanden-Eijnden. Markov State Models Based on Milestoning. J. Chem. Phys., 134 (20). 204105, 2011.

J.-H. Prinz, H. Wu, M. Sarich, B. Keller, M. Fischbach, M. Held, J. D. Chodera, Ch. Schütte, and F. Noé. Markov models of molecular kinetics: Generation and Validation. J. Chem. Phys., 134 . p. 174105, 2011.