Recovering an homogeneous polynomial from moments of its level set

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Motivation

- An important property of Positively Homogeneous Functions (PHF)
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing K
- Exact reconstruction from moments

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Reconstruction of a shape $\mathbf{K} \subset \mathbb{R}^n$ (convex or not)

from knowledge of finitely many moments

$$\mathbf{y}_{\alpha} = \int_{\mathbf{K}} x_1^{\alpha_1} \cdots x_n^{\alpha_n} \, dx, \qquad \alpha \in \mathbb{N}_d^n,$$

for some integer *d*, is a difficult and challenging problem!

EXACT recovery of K

from $y = (y_{\alpha}), \alpha \in \mathbb{N}^{n}_{d}$, is even more difficult and challenging!

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Examples of exact recovery:

- Quadrature (planar) Domains in (ℝ²) (Gustafsson, He, Milanfar and Putinar (Inverse Problems, 2000))
 via an exponential transform
- Convex Polytopes (in ℝⁿ) (Gravin, Lasserre, Pasechnik and Robins (Discrete & Comput. Geometry (2012))
 Use Brion-Barvinok-Khovanski-Lawrence-Pukhlikov moment formula for projections ∫_P ⟨c, x⟩^j dx combined with a Prony-type method to recover the vertices of *P*.
- and extension to Non convex poyhedra by Pasechnik et al.
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Approximate recovery can de done in multi-dimensions

(Cuyt, Golub, Milanfar and Verdonk, 2005) via :

- (multi-dimensional versions of) homogeneous Padé approximants applied to the Stieltjes transform.
- cubature formula at each point of grid
- solving a linear system of equations to retrieve the indicator function of K

Exact recovery.

- $\mathbf{K} = \{ x \in \mathbb{R}^n : g(\mathbf{x}) \le 1 \}$ compact.
- g is a nonnegative homogeneous polynomial
- Data are finitely many moments:

$$\mathbf{y}_{lpha} \,=\, \int_{\mathbf{K}} \mathbf{x}^{lpha} \, d\mathbf{x}, \quad lpha \in \mathbb{N}_{d}^{n}.$$

Also works for Quasi-homogeneous polynomials, i.e., when

$$g(\lambda^{u_1}x_1,\ldots,\lambda^{u_n}x_n) = \lambda g(x), \qquad x \in \mathbb{R}^n,$$

for some vector $\boldsymbol{u} \in \mathbb{Q}^n$.

(*d*-Homogeneous =u-quasi homogeneous with $u_i = \frac{1}{d}$ for all *i*).

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Positively Homogeneous functions (PHF) form a wide class of functions encountered in many applications. As a consequence of homogeneity, they enjoy very particular properties, and among them the celebrated and very useful Euler's identity which allows to deduce additional properties of PHFs in various contexts.

Another (apparently not well-known) property of PHFs yields surprising and unexpected results, some of them already known in particular cases.

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So we are now concerned with PHFs, their sublevel sets and in particular, the integral

$$\mathbf{y} \mapsto \mathbf{I}_{g,h}(\mathbf{y}) := \int_{\{\mathbf{x} : \mathbf{g}(\mathbf{x}) \leq \mathbf{y}\}} h(\mathbf{x}) d\mathbf{x},$$

as a function $I_{g,h} : \mathbb{R}_+ \to \mathbb{R}$ when g, h are PHFs.

With y fixed, we are also interested in

 $\boldsymbol{g}\mapsto \boldsymbol{I_{g,h}(y)},$

now as a function of g, especially when g is a nonnegative homogeneous polynomial.

Nonnegative homogeneous polynomials are particularly interesting as they can be used to approximate norms; see e.g. Barvinok

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Interestingly, the latter integral is related in a simple and remarkable manner to the non-Gaussian integral $\int_{\mathbb{R}^n} h \exp(-g) dx$.

Functional integrals appear frequently in quantum Physics

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exact formulas for $\int \exp(-g) dx$, the most well-known being when deg g = 2,

$$d = 2 \Rightarrow \int \exp(-g) \, dx = \frac{\operatorname{Cte}}{\sqrt{\operatorname{det}(g)}}$$

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The key tools are discriminants and SL(n)-invariants.

An integral

$$J(g) := \int \exp(-g) \, dx$$

is called a discriminant integral.

Integral discriminants satisfy WARD Identities

$$\left(\frac{\partial}{\partial g_{a_1\cdots a_n}}\frac{\partial}{\partial g_{b_1\cdots b_n}}-\frac{\partial}{\partial g_{c_1\cdots c_n}}\frac{\partial}{\partial g_{d_1\cdots d_n}}\right)\cdot J(g) = 0,$$

where $a_i + b_i = c_i + d_i$ for all i .

which permits to obtain exact formulas in low-dimensional cases in terms of algebraic invariants of g. See e.g. Morosov and Shakirov¹

¹New and old results in Resultant theory, arXiv.0ອ11ເສັ278ສ1.ເຊັ່າ ຊິ ລາດຕ

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In particular, as a by-product in the important particular case when h = 1, they have proved that for all *forms g* of degree d,

$$\operatorname{Vol}\left(\{x : g(x) \le 1\}\right) = \int_{\{x : g(x) \le 1\}} dx$$
$$= \operatorname{cte}(d) \cdot \int_{\mathbb{R}^n} \exp(-g) d\mathbf{x},$$

where the constant depends only on *d* and *n*.

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In fact, a formula of exactly the same flavor was already known for convex sets, and was the initial motivation of our work. Namely, if $C \subset \mathbb{R}^n$ is convex, its support function

$$x \mapsto \sigma_{\mathcal{C}}(x) := \sup \{x^T y : y \in \mathcal{C}\},\$$

is a PHF of degree 1, and the polar $C^{\circ} \subset \mathbb{R}^n$ of *C* is the convex set $\{x : \sigma_C(x) \leq 1\}$.

Then ...

$$\operatorname{vol}(\mathcal{C}^{\circ}) = \frac{1}{n!} \int_{\mathbb{R}^n} \exp(-\sigma_{\mathcal{C}}(x)) \, dx, \qquad \forall \mathcal{C}.$$

Theorem

Let $\phi : \mathbb{R}_+ \to \mathbb{R}$ be a measurable mapping, and let $g \ge 0$ and h be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$ and such that $\int |h| \exp(-g) dx$ is finite,

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = C(\phi, d, p) \cdot \int_{\mathbb{R}^n} h \exp(-g) dx,$$

where the constant $C(\phi, d, p)$ depends only on ϕ, d, p . In particular, if the sublevel set $\{x : g(x) \le 1\}$ is bounded, then

$$\int_{\{x: g(x) \leq y\}} h \, dx = \frac{y^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx,$$

with Γ being the standard Gamma function

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Proof for nonnegative /

With $z = (z_1, ..., z_{n-1})$, do the change of variable $x_1 = t$, $x_2 = t z_1, ..., x_n = t z_{n-1}$) so that one may decompose $\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx$ into the sum

$$\int_{\mathbb{R}_{+} \times \mathbb{R}^{n-1}} t^{n+p-1} \phi(t^{d}g(1,z)) h(1,z) dt dz$$

+
$$\int_{\mathbb{R}_{+} \times \mathbb{R}^{n-1}} t^{n+p-1} \phi(t^{d}g(-1,-z)) h(-1,-z) dt dz,$$

=
$$\int_{\mathbb{R}^{n-1}} \left(\int_{0}^{\infty} t^{n+p-1} \phi(t^{d}g(1,z)) dt \right) h(1,z) dz$$

+
$$\int_{\mathbb{R}^{n-1}} \left(\int_{0}^{\infty} t^{n+p-1} \phi(t^{d}g(-1,-z)) dt \right) h(-1,-z) dz,$$

where the last two integrals are obtained from the sum of the previous two by using Tonelli's Theorem.

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Proof (continued)

Next, with the change of variable $u = t g(1, z)^{1/d}$ and $u = t g(-1, -z)^{1/d}$

$$\int_{\mathbb{R}^n} \phi(g(x)) h(x) dx = \underbrace{\left(\int_{\mathbb{R}_+} u^{n+p-1} \phi(u^d) du\right)}_{\operatorname{Cte}(\phi, p, d)} \cdot A(g, h),$$

with

 \square

$$A(g,h) = \int_{\mathbb{R}^{n-1}} \left(\frac{h(1,z)}{g(1,z)^{(n+p)/d}} + \frac{h(-1,-z)}{g(-1,-z)^{(n+p)/d}} \right) dz.$$

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Choosing $\phi(t) = \exp(-t)$ on $[0, +\infty)$ yields:

$$\int_{\mathbb{R}^n} \exp(-g(x)) h(x) dx = \frac{\Gamma(1+(n+p)/d)}{n+p} \cdot A(g,h),$$

whereas, choosing
$$\phi(I) = I_{[0,1]}(I)$$
 on $[0, +\infty)$ yields:
$$\int_{\{x : g(x) \le 1\}} h(x) dx = \frac{1}{n+p} \cdot A(g, h),$$

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And so in particular, whenever g is nonnegative and $\{x : g(x) \le 1\}$ is bounded:

Theorem

If g, h are PHFs of degree 0 < d and p respectively, then:

$$\int_{\{x:g(x)\leq y\}} h dx = \frac{y^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} \exp(-g) h dx$$

$$\operatorname{vol}\left(\{x : g(x) \leq y\}\right) = \frac{y^{n/d}}{\Gamma(1+n/d)} \int_{\mathbb{R}^n} \exp(-g) \, dx$$

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An alternative proof

Let g, h be nonnegative so that $I_{g,h}(y)$ vanishes on $(-\infty, 0]$. Its Laplace transform $\lambda \mapsto \mathcal{L}_{I_{g,h}}(\lambda) = \int_0^\infty \exp(-\lambda y) I_{g,h}(y) \, dy$

$$\mathcal{L}_{l_{g,h}}(\lambda) = \int_{0}^{\infty} \exp(-\lambda y) \left(\int_{\{x:g(x) \le y\}}^{\infty} h dx \right) dy$$

$$= \int_{\mathbb{R}^{n}} h(x) \left(\int_{g(x)}^{\infty} \exp(-\lambda y) dy \right) dx \quad [by Fubini]$$

$$= \frac{1}{\lambda} \int_{\mathbb{R}^{n}} h(x) \exp(-\lambda g(x)) dx$$

$$= \frac{1}{\lambda^{1+(n+p)/d}} \int_{\mathbb{R}^{n}} h(z) \exp(-g(z)) dz \quad [by homog]$$

$$= \frac{\int_{\mathbb{R}^{n}} h(z) \exp(-g(z)) dz}{\Gamma(1+(n+p)/d)} \mathcal{L}_{y^{(n+p)/d}}(\lambda).$$

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And so, by uniqueness of the Laplace transform,

$$I_{g,h}(\mathbf{y}) = \frac{\mathbf{y}^{(n+p)/d}}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} h(x) \exp(-g(x)) dx,$$

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II. Approximating a non gaussian integral

Hence computing the non Gaussian integral $\int \exp(-g) dx$

reduces to computing the volume of the level set $G := \{x : g(x) \le 1\},\$

... which is the same as solving the optimization problem:

 $\max_{\mu} \quad \mu(G)$ s.t. $\mu + \nu = \lambda$ $\mu(\mathbf{B} \setminus G) = 0$

where :

- **B** is a box $[-a, a]^n$ containing **G** and
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... and we know how to approximate $\mu(G)$ as closely as desired

Let $G \subseteq \mathbf{B} := [-1, 1]^n$ (possibly after scaling), and let $z = (z_\alpha)$, $\alpha \in \mathbb{N}^n_{2k}$, be the moments of the Lebesgue measure λ on B.

Solve the hierarchy of semidefinite programs:

$$\rho_{k} = \max \quad y_{0}$$

s.t.
$$\begin{aligned} \mathbf{M}_{k}(\mathbf{y}), \mathbf{M}_{k}(\mathbf{v}) \succeq \mathbf{0}, \\ \mathbf{M}_{k-\lceil (d)/2 \rceil}(\mathbf{g} \mathbf{y}) \succeq \mathbf{0} \\ \mathbf{M}_{k-1}((1-x_{i}^{2}) \mathbf{v}) \succeq \mathbf{0}, \quad i = 1, \dots, n \\ y_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}, \quad \alpha \in \mathbb{N}_{2k}^{n} \end{aligned}$$

for some moment and localizing matrices $\mathbf{M}_k(\mathbf{y})$ and $\mathbf{M}_k(\mathbf{g}, \mathbf{y})$. • The linear constraints $\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}$ for all $\alpha \in \mathbb{N}_{2k}^n$ "ensure" $\mu + \nu = \lambda$, while the " \succeq 0" constraints "ensure" supp $\mu = \mathbf{G}$ and supp $\nu = \mathbf{B}$.

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\mathbf{M}_{k-1}((1-x_{i}^{2}) \boldsymbol{v}) \succeq 0, \quad i = 1, \dots, n \\
\boldsymbol{y}_{\alpha} + \boldsymbol{v}_{\alpha} &= \boldsymbol{z}_{\alpha}, \quad \alpha \in \mathbb{N}_{2k}^{n}
\end{aligned}$$

for some moment and localizing matrices $\mathbf{M}_k(\mathbf{y})$ and $\mathbf{M}_k(\mathbf{g}, \mathbf{y})$. • The linear constraints $\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}$ for all $\alpha \in \mathbb{N}_{2k}^n$ "ensure" $\mu + \nu = \lambda$, while the " \succeq 0" constraints "ensure" supp $\mu = \mathbf{G}$ and supp $\nu = \mathbf{B}$.

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... and we know how to approximate $\mu(G)$ as closely as desired

Let $G \subseteq \mathbf{B} := [-1, 1]^n$ (possibly after scaling), and let $z = (z_\alpha)$, $\alpha \in \mathbb{N}^n_{2k}$, be the moments of the Lebesgue measure λ on B.

Solve the hierarchy of semidefinite programs:

$$p_{k} = \max \quad \mathbf{y}_{0}$$

s.t.
$$\mathbf{M}_{k}(\mathbf{y}), \mathbf{M}_{k}(\mathbf{v}) \succeq 0,$$
$$\mathbf{M}_{k-\lceil (d)/2 \rceil}(\mathbf{g} \mathbf{y}) \succeq 0$$
$$\mathbf{M}_{k-1}((1 - x_{i}^{2}) \mathbf{v}) \succeq 0, \quad i = 1, \dots, n$$
$$\mathbf{y}_{\alpha} + \mathbf{v}_{\alpha} = \mathbf{z}_{\alpha}, \quad \alpha \in \mathbb{N}_{2k}^{n}$$

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Lemma

 $\rho_{k} \rightarrow \lambda(G)$ as $k \rightarrow \infty$.

(see: Approximate volume and integration for basic semi algebraic sets, Henrion, Lasserre and Savorgnan, SIAM Review 51, 2009.)

However .

the resulting SDPs are numerically difficult to solve.

Solving the dual reduces to approximating the indicator function I(G) by polynomials of increasing degrees \rightarrow Gibbs effect, etc.

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Another identity

Corollary

If g has degree d and G is bounded then

$$\frac{\int_{\{x:g(x)\leq y\}} \exp(-g) dx}{\int_{\mathbb{R}^n} \exp(-g) dx} = \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\int_0^\infty t^{n/d-1} \exp(-t) dt}$$
$$= \frac{\int_0^y t^{n/d-1} \exp(-t) dt}{\Gamma(n/d)}$$

expresses how fast $\mu(\{x : g(x) \le y\})$ goes to $\mu(\mathbb{R}^n)$ as $y \to \infty$, for the Borel measure $d\mu = \exp(-g) dx$.

It is like for the Gamma function $\Gamma(n/d)$ when approximated by $\int_0^y t^{n/d-1} \exp(-t) dt$.

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III. Convexity

An interesting issue is to analyze how the Lebesgue volume vol $\{x \in \mathbb{R}^n : g(x) \leq 1\}$, (i.e. vol (*G*)) changes with *g*. Recall that $G = \{x : g(x) \leq 1\}$.

Corollary

Let *h* be a PHF of degree *p* and let $C_d \subset \mathbb{R}[x]_d$ be the convex cone of homogeneous polynomials of degree at most *d* such that **G** is bounded. Then the function $f_h : C_d \to \mathbb{R}$,

$$g\mapsto f_h(g):=\int_G h\,dx,\qquad g\in C_d,$$

- is a PHF of degree -(n + p)/d,
- convex whenever h is nonnegative and strictly convex if h > 0 on ℝⁿ \ {0}

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Corollary (continued)

Moreover, if **h** is continuous and $\int |\mathbf{h}| \exp(-\mathbf{g}) dx < \infty$ then:

$$\frac{\partial f_h(g)}{\partial g_\alpha} = \frac{-1}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} x^\alpha h \exp(-g) dx$$
$$= \frac{-\Gamma(2+(n+p)/d)}{\Gamma(1+(n+p)/d)} \int_G x^\alpha h dx$$
$$\frac{\partial^2 f_h(g)}{\partial g_\alpha \partial g_\beta} = \frac{-1}{\Gamma(1+(n+p)/d)} \int_{\mathbb{R}^n} x^{\alpha+\beta} h \exp(-g) dx$$

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PROOF: Just use

$$\int_{\{x: g(x) \le 1\}} h \, dx = \frac{1}{\Gamma(1 + (n + p)/d)} \int_{\mathbb{R}^n} h \exp(-g) \, dx$$

Notice that proving convexity directly would be non trivial but becomes easy when using the previous lemma!

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For a set $C \subset \mathbb{R}^n$, recall:

• The support function $x \mapsto \sigma_{C}(x) := \sup_{y \in C} \{x^{T}y : y \in C\}$

• The POLAR $C^{\circ} := \{x \in \mathbb{R}^n : \sigma_C(x) \leq 1\}$

• and for a PHF *g* of degree *d*, its Legendre-Fenchel conjugate $g^*(x) = \sup_{y} \{x^T y - g(y)\}$ is a PHF of degree *q* with $\frac{1}{d} + \frac{1}{q} = 1$.

Polarity (continued)

Lemma

Let g be a closed proper convex PHF of degree 1 < d and let $G = \{x : g(x) \le 1/d\}$. Then:

$$G^{\circ} = \{x \in \mathbb{R}^{n} : g^{*}(x) \leq 1/q\}$$

$$\operatorname{vol}(G) = \frac{p^{-n/p}}{\Gamma(1+n/p)} \int \exp(-g) \, dx$$

$$\operatorname{vol}(G^{\circ}) = \frac{q^{-n/q}}{\Gamma(1+n/q)} \int \exp(-g^{*}) \, dx$$

 \rightarrow yields completly symmetric formulas for g and its conjugate g^* .

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Examples

•
$$g(x) = |x|^3$$
 so that $g^*(x) = \frac{2}{3\sqrt{3}}|x|^{3/2}$. And so
 $G = [-3^{-1/3}, 3^{-1/3}]; \quad G^\circ = [-3^{1/3}, 3^{1/3}].$

• TV screen:
$$g(x) = x_1^4 + x_2^4$$
 so that $g^*(x) = 4^{-4/3} \Im(x_1^{4/3} + x_2^{4/3})$. And,

$$G = \{x : x_1^2 + x_2^4 \le \frac{1}{4}\}; \quad G^\circ = \{x : x_1^{4/3} + x_2^{4/3} \le 4^{1/3}\}.$$

• g(x) = |x| so that $d \neq 1$, and $g^*(x) = 0$ if $x \in [-1, 1]$, and $+\infty$ otherwise. Hence $G = \{x : |x| \leq 1\} = [-1, 1]$ and with $q = +\infty$,

$$G^{\circ} = [-1,1] = \{x : g^*(x) \leq \frac{1}{q} = 0\}.$$

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IV. A variational property of homogeneous polynomials

Let $\mathbf{v}_d(x)$ be the vector of monomials (x^{α}) of degree d, i.e., such that $\alpha_1 + \cdots + \alpha_n = d$.

If $g \in \mathbb{R}[x]_{2d}$ is homogeneous and SOS then

$$\boldsymbol{g}(\boldsymbol{x}) = \frac{1}{2} \boldsymbol{v}_d(\boldsymbol{x})^T \boldsymbol{\Sigma} \boldsymbol{v}_d(\boldsymbol{x}),$$

for some real symmetric positive semidefinite matrix $\Sigma \succeq 0$.

And if
$$d = 1$$
 one has the Gaussian property

$$\int_{\mathbb{R}^{n}} \exp(-g) \, dx = \frac{(2\pi)^{n/2}}{\sqrt{\det \Sigma}},$$

$$\frac{\int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \, \mathbf{v}_{d}(x)^{T} \, \exp(-g) \, dx}{\int_{\mathbb{R}^{n}} \exp(-g) \, dx} = \Sigma^{-1}.$$

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In other words, if μ is the Gaussian measure

$$\mu(B) := \frac{\int_{B} \exp\left(-\frac{1}{2}x^{T}\Sigma x\right) dx}{\int_{\mathbb{R}^{n}} \exp\left(-\frac{1}{2}x^{T}\Sigma x\right) dx}, \quad \forall B,$$

then its (covariance) matrix of moments of order 2 satisfies:

$$\mathbf{M}_1(\mathbf{\Sigma}) := \int_{\mathbb{R}^n} x \, x^T \, d\mu(x) = \mathbf{\Sigma}^{-1}.$$

... not true anymore for d > 1!

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However, let $\ell(d) = \binom{n+d}{n-1}$, and $\mathcal{S}_{++}^{\ell(d)}$ be the cone of real positive definite $\ell(d) \times \ell(d)$ matrices. Let $k := n/(2d\ell(d))$.

With $\Sigma \in \mathcal{S}_{++}^{\ell(d)}$, define the probability measure μ

$$\mu(B) := \frac{\int_{B} \exp\left(-k\mathbf{v}_{d}(x)^{\mathsf{T}} \mathbf{\Sigma} \, \mathbf{v}_{d}(x)\right) \, dx}{\int_{\mathbb{R}^{n}} \exp\left(-k\mathbf{v}_{d}(x)^{\mathsf{T}} \mathbf{\Sigma} \, \mathbf{v}_{d}(x)\right) \, dx}, \quad \forall B$$

with matrix of moments of order 2d given by:

$$\mathbf{M}_d(\boldsymbol{\Sigma}) := \int_{\mathbb{R}^n} \mathbf{v}_d(x) \, \mathbf{v}_d(x)^T \, \boldsymbol{d}\mu(x).$$

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Define $\theta_d : \mathcal{S}_{++}^{\ell(d)} \to \mathbb{R}$ to be the function

$$\boldsymbol{\Sigma} \mapsto \theta_d(\boldsymbol{\Sigma}) := (\det \boldsymbol{\Sigma})^k \int_{\mathbb{R}^n} \exp\left(-k \mathbf{v}_d(x)^T \boldsymbol{\Sigma} \, \mathbf{v}_d(x)\right) \, dx.$$

Theorem

$$\mathbf{M}_{d}(\mathbf{\Sigma}) = \mathbf{\Sigma}^{-1} \iff \nabla \theta_{d}(\mathbf{\Sigma}) = \mathbf{0}$$

Hence critical points Σ^* of θ_d have the Gaussian property

$$\frac{\int \mathbf{v}_d(x) \mathbf{v}_d(x)^T \exp\left(-k\mathbf{v}_d(x)^T \mathbf{\Sigma}^* \mathbf{v}_d(x)\right) dx}{\int \exp\left(-k\mathbf{v}_d(x)^T \mathbf{\Sigma}^* \mathbf{v}_d(x)\right) dx} = (\mathbf{\Sigma}^*)^{-1}$$

* If d = 1 then $\theta_d(\cdot)$ is constant and so $\nabla \theta_d(\cdot) = 0$. * If d > 1 then $\theta_d(\cdot)$ is constant in each ray $\lambda \Sigma$, $\lambda > 0$.

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$$\nabla \theta_{d}(\Sigma) = k \frac{\Sigma^{\mathbb{A}}}{\det \Sigma} \theta_{d}(\Sigma)$$
$$-k(\det \Sigma)^{k} \int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} \exp\left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) dx$$
$$= k \theta_{d}(\Sigma) \left[\Sigma^{-1} - \mathbf{M}_{d}(\Sigma)\right]$$

and so

$$\mathbf{M}_d(\boldsymbol{\Sigma}) = \boldsymbol{\Sigma}^{-1} \quad \Rightarrow \quad \nabla \theta_d(\boldsymbol{\Sigma}) = \mathbf{0}.$$

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If $\mathbf{K} \subset \mathbb{R}^n$ is compact then computing the ellipsoid ξ of minimum volume containing \mathbf{K} is a classical problem whose optimal solution is called the Löwner-John ellipsoid. So consider the following problem:

Find an homogeneous polynomial $g \in \mathbb{R}[x]_{2d}$ such that its sub level set $G := \{x : g(x) \le 1\}$ contains K and has minimum volume among all such levels sets with this inclusion property.

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Let $\mathbf{P}[x]_{2d}$ be the convex cone of homogeneous polynomials of degree 2d with compact sub-level set $\{x : g(x) \le 1\}$, and with $\mathbf{K} \subset \mathbb{R}^n$, let $C_{2d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on \mathbf{K} .

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Let $\mathbf{K} \subset \mathbb{R}^n$ be compact. The minimum volume of a sublevel set $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}, g \in \mathbf{P}[x]_{2d}$, that contains $\mathbf{K} \subset \mathbb{R}^n$ is $\rho/\Gamma(1 + n/2d)$ where:

$$\mathcal{P}: \qquad \rho = \inf_{g \in \mathbf{P}[x]_{2d}} \left\{ \int_{\mathbb{R}^n} \exp(-g) \, dx \, : \, 1 - g \, \in \, C_{2d}(\mathbf{K}) \right\}$$

a finite-dimensional convex optimization problem!

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Lemma

Let $\mathbf{K} \subset \mathbb{R}^n$ be compact. The minimum volume of a sublevel set $\{\mathbf{x} : g(\mathbf{x}) \leq 1\}, g \in \mathbf{P}[x]_{2d}$, that contains $\mathbf{K} \subset \mathbb{R}^n$ is $\rho/\Gamma(1 + n/2d)$ where:

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Proof

• We have seen that:

$$\operatorname{vol}(\{x : g(x) \leq 1\}) = \frac{1}{\Gamma(1 + n/2d)} \int_{\mathbb{R}^n} \exp(-g) \, dx.$$

Moreover, the sub-level set $\{x : g(x) \le 1\}$ contains **K** if and only if $1 - g \in C_{2d}(\mathbf{K})$, and so $\rho/\Gamma(1 + n/2d)$ is the minimum value of all volumes of sub-levels sets $\{x : g(x) \le 1\}$, $g \in \mathbf{P}[\mathbf{x}]_{2d}$, that contain **K**.

• Now since $g \mapsto \int_{\mathbb{R}^n} \exp(-g) dx$ is strictly convex and $C_{2d}(\mathsf{K})$ is a convex cone, problem \mathcal{P} is a finite-dimensional convex optimization problem. \Box

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V (continued). Characterizing an optimal solution

Theorem

(a) \mathcal{P} has a unique optimal solution $g^* \in \mathbf{P}[x]_{2d}$ and there exists a Borel measure μ^* supported on K such that:

(*):
$$\begin{cases} \int_{\mathbb{R}^n} x^{\alpha} \exp(-g^*) dx = \int_{\mathbf{K}} x^{\alpha} d\mu^*, \quad \forall |\alpha| = 2d \\ \int_{\mathbf{K}} (1 - g^*) d\mu^* = 0 \end{cases}$$

In particular, μ^* is supported on the real variety $V := \{x \in \mathbf{K} : g^*(\mathbf{x}) = 1\}$ and in fact, μ^* can be substituted with another measure ν^* supported on at most $\binom{n+2d-1}{2d} + 1$ points of V.

(b) Conversely, if $g^* \in \mathbf{P}[x]_{2d}$ and μ^* satisfy (*) then g^* is an optimal solution of \mathcal{P} .

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VI. Recovering g from moments of G

Write
$$g(x) = \sum_{\beta} g_{\beta} x^{\beta}$$
.

Lemma

If g is nonnegative and d-homogeneous with G compact then:

$$\underbrace{\int_{G} x^{\alpha} g(x) dx}_{\sum_{\beta} g_{\beta} y_{\alpha+\beta}} = \frac{n+|\alpha|}{n+d+|\alpha|} \underbrace{\int_{G} x^{\alpha} dx}_{y_{\alpha}}, \qquad \alpha \in \mathbb{N}^{n}.$$

and so we see that the moments (y_{α}) satisfy linear relationships explicit in terms of the coefficients of the polynomial *g* that describes the boundary of *G*.

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So let us write $\mathbf{g} \in \mathbb{R}^{s(d)}$ the unknown vector of coefficients of the unknown polynomial g.

Let $\mathbf{M}_{d}(\mathbf{y})$ be the moment matrix of order d whose rows and columns are indexed in the canonical basis of monomials (x^{α}) , $\alpha \in \mathbb{N}_{d}^{n}$, and with entries

 $\mathbf{M}_{d}(\mathbf{y})(\alpha,\beta) = \mathbf{y}_{\alpha+\beta}, \qquad \alpha,\beta \in \mathbb{N}_{d}^{n}.$

and let \mathbf{y}^d be the vector $(\mathbf{y}_{\alpha}), \alpha \in \mathbb{N}^n_d$.

Previous Lemma states that

 $\mathbf{M}_{\mathbf{d}}(\mathbf{y})\mathbf{g} = \mathbf{y}^{\mathbf{d}},$

or, equivalently,

$$\mathbf{g} = \mathbf{M}_{\mathbf{d}}(\mathbf{y})^{-1} \, \mathbf{y}^{\mathbf{d}},$$

because the moment matrix $\mathbf{M}_d(\mathbf{y})$ is nonsingular whenever *G* has nonempty interior.

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In other words ...

one may recover g EXACTLY from knowledge of moments (y_{α}) of order d and 2d!

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• Compact sub-level sets $G := \{x : g(x) \le y\}$ of homogeneous polynomials exhibit surprising properties. E.g.:

- convexity of volume(G) with respect to the coefficients of g
- Integrating a PHF *h* on *G* reduce to evaluating the non Gaussian integral $\int h \exp(-g) dx$
- A variational property yields a Gaussian-like property
- exact recovery of *G* from finitely moments.

Also works for quasi-homogeneous polynomials with bounded sublevel sets!

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- COMPUTATION!: Efficient evaluation of $\int_{\mathbb{R}^n} \exp(-g) dx$, or equivalently, evaluation of vol $(\{x : g(x) \le 1\}!$
 - The property

$$\int_{G} \mathbf{x}^{\alpha} g(x) \, dx = \frac{n + |\alpha|}{n + d + |\alpha|} \int_{G} x^{\alpha} \, dx, \qquad \forall \alpha,$$

helps a lot to improve efficiency of the method in Henrion, Lasserre and Savorgnan (SIAM Review)

• What about non-homogeneous polynomials?

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• What about non-homogeneous polynomials?

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THANK YOU!

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