# Recovering an homogeneous polynomial from moments of its level set 

Jean B. Lasserre

LAAS-CNRS and Institute of Mathematics, Toulouse, France
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- Motivation
- An important property of Positively Homogeneous Functions (PHF)
- Some properties (convexity, polarity)
- Sub-level sets of minimum volume containing K
- Exact reconstruction from moments
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## Exact reconstruction

Reconstruction of a shape $\mathrm{K} \subset \mathbb{R}^{n}$ (convex or not)
from knowledge of finitely many moments

$$
y_{\alpha}=\int_{\mathbf{K}} x_{1}^{\alpha_{1}} \cdots x_{n}^{\alpha_{n}} d x, \quad \alpha \in \mathbb{N}_{d}^{n}
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for some integer $d$, is a difficult and challenging problem!

## EXACT recovery of K

from $y=\left(y_{a}\right), a \in \mathbb{N}^{n}$, is even more difficult and challenging!

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## Exact recovery (continued)

## Examples of exact recovery:

- Quadrature (planar) Domains in $\left(\mathbb{R}^{2}\right)$ (Gustafsson, He, Milanfar and Putinar (Inverse Problems, 2000))
- via an exponential transform
- Convex Polytopes (in $\mathbb{R}^{n}$ ) (Gravin, Lasserre, Pasechnik and Robins (Discrete \& Comput. Geometry (2012))
- Use Brion-Barvinok-Khovanski-Lawrence-Pukhlikov moment formula for projections $\int_{P}\langle c, x\rangle^{j} d x$ combined with a Prony-type method to recover the vertices of $P$.
- and extension to Non convex poyhedra by Pasechnik et al.
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Approximate recovery can de done in multi-dimensions
(Cuyt, Golub, Milanfar and Verdonk, 2005) via :

- (multi-dimensional versions of) homogeneous Padé approximants applied to the Stieltjes transform.
- cubature formula at each point of grid
- solving a linear system of equations to retrieve the indicator function of $\mathbf{K}$


## This talk

## - Exact recovery.

- $K=\left\{x \in \mathbb{R}^{n}: g(\mathbf{x}) \leq 1\right\}$ compact.
- $g$ is a nonnegative homogeneous polynomial
- Data are finitely many moments:

$$
y_{\alpha}=\int_{\mathbf{K}} \mathbf{x}^{\alpha} d \mathbf{x}, \quad \alpha \in \mathbb{N}_{d}^{n} .
$$

- Also works for Quasi-homogeneous polynomials, i.e., when

$$
g\left(\lambda^{u_{1}} x_{1}, \ldots, \lambda^{u_{n}} x_{n}\right)=\lambda g(x), \quad x \in \mathbb{R}^{n},
$$

for some vector $u \in \mathbb{Q}^{n}$.
(d-Homogeneous =u-quasi homogeneous with $u_{i}=\frac{1}{d}$ for all $\left.i\right)$.

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$\left(d\right.$-Homogeneous $=$ u-quasi homogeneous with $u_{i}=\frac{1}{d}$ for all $\left.i\right)$.

## A little detour

Positively Homogeneous functions (PHF) form a wide class of functions encountered in many applications. As a consequence of homogeneity, they enjoy very particular properties, and among them the celebrated and very useful Euler's identity which allows to deduce additional properties of PHFs in various contexts.

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The case of homogeneous polynomials is even more interesting!

So we are now concerned with PHFs, their sublevel sets and in particular, the integral

$$
y \mapsto I_{g, h}(y):=\int_{\{x: g(\mathbf{x}) \leq y\}} h(\mathbf{x}) d \mathbf{x},
$$

as a function $I_{g, h}: \mathbb{R}_{+} \rightarrow \mathbb{R}$ when $g, h$ are PHFs.
With $y$ fixed, we are also interested in
now as a function of $g$, especially when $g$ is a nonnegative homogeneous polynomial.

Nonnegative homogeneous polynomials are particularly
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Nonnegative homogeneous polynomials are particularly interesting as they can be used to approximate norms; see e.g. Barvinok

## Some motivation

Interestingly, the latter integral is related in a simple and remarkable manner to the non-Gaussian integral

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\int_{\mathbb{R}^{n}} h \exp (-g) d x .
$$

Functional integrals appear frequently in quantum Physics

## ...... where a challenging issue is to provide

exact formulas for $\int \exp (-g) d x$, the most well-known being when $\operatorname{deg} g=2$,

$$
d=2 \Rightarrow \int \exp (-g) d x=\frac{\mathrm{Cte}}{\sqrt{\operatorname{det}(g)}} .
$$

Observe that $\operatorname{det}(g)$ is an algebraic invariant of $g$,

## The key tools are discriminants and $S L(n)$-invariants.

## An integral

$$
J(g):=\int \exp (-g) d x
$$

is called a discriminant integral.

## Integral discriminants satisfy <br> 

where $a_{i}+b_{i}=c_{i}+d_{i}$ for all $i$.
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## An integral

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## Integral discriminants satisfy WARD Identities

$$
\left(\frac{\partial}{\partial g_{a_{1} \cdots a_{n}}} \frac{\partial}{\partial g_{b_{1} \cdots b_{n}}}-\frac{\partial}{\partial g_{c_{1} \cdots c_{n}}} \frac{\partial}{\partial g_{d_{1} \cdots d_{n}}}\right) \cdot J(g)=0
$$

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which permits to obtain exact formulas in low-dimensional cases in terms of algebraic invariants of $g$. See e.g. Morosov and Shakirov ${ }^{1}$

[^0]In particular, as a by-product in the important particular case when $h=1$, they have proved that for all forms $g$ of degree $d$,

$$
\begin{aligned}
\operatorname{Vol}(\{x: g(x) \leq 1\}) & =\int_{\{x: g(x) \leq 1\}} d x \\
& =\operatorname{cte}(d) \cdot \int_{\mathbb{R}^{n}} \exp (-g) d \mathbf{x},
\end{aligned}
$$

where the constant depends only on $d$ and $n$.

In fact, a formula of exactly the same flavor was already known for convex sets, and was the initial motivation of our work. Namely, if $C \subset \mathbb{R}^{n}$ is convex, its support function

$$
x \mapsto \sigma_{C}(x):=\sup \left\{x^{\top} y: y \in C\right\},
$$

is a PHF of degree 1 , and the polar $C^{\circ} \subset \mathbb{R}^{n}$ of $C$ is the convex set $\left\{x: \sigma_{C}(x) \leq 1\right\}$.

## Then...

$$
\operatorname{vol}\left(C^{\circ}\right)=\frac{1}{n!} \int_{\mathbb{R}^{n}} \exp \left(-\sigma_{C}(x)\right) d x, \quad \forall C
$$

## I. An important property of PHF's

## Theorem

Let $\phi: \mathbb{R}_{+} \rightarrow \mathbb{R}$ be a measurable mapping, and let $g \geq 0$ and $h$ be PHFs of respective degree $0 \neq d, p \in \mathbb{Z}$ and such that $\int|h| \exp (-g) d x$ is finite,

$$
\int_{\mathbb{R}^{n}} \phi(g(x)) h(x) d x=C(\phi, d, p) \cdot \int_{\mathbb{R}^{n}} h \exp (-g) d x
$$

where the constant $\boldsymbol{C}(\phi, d, p)$ depends only on $\phi, d, p$. In particular, if the sublevel set $\{x: g(x) \leq 1\}$ is bounded, then

$$
\int_{\{x: g(x) \leq y\}} h d x=\frac{y^{(n+p) / d}}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} h \exp (-g) d x
$$

with $\Gamma$ being the standard Gamma function

## Proof for nonnegative

With $z=\left(z_{1}, \ldots, z_{n-1}\right)$, do the change of variable $x_{1}=t$, $\left.x_{2}=t z_{1}, \ldots, x_{n}=t z_{n-1}\right)$ so that one may decompose $\int_{\mathbb{R}^{n}} \phi(g(x)) h(x) d x$ into the sum

$$
\begin{aligned}
& \int_{\mathbb{R}_{+} \times \mathbb{R}^{n-1}} t^{n+p-1} \phi\left(t^{d} g(1, z)\right) h(1, z) d t d z \\
+ & \int_{\mathbb{R}_{+} \times \mathbb{R}^{n-1}} t^{n+p-1} \phi\left(t^{d} g(-1,-z)\right) h(-1,-z) d t d z \\
= & \int_{\mathbb{R}^{n-1}}\left(\int_{0}^{\infty} t^{n+p-1} \phi\left(t^{d} g(1, z)\right) d t\right) h(1, z) d z \\
+ & \int_{\mathbb{R}^{n-1}}\left(\int_{0}^{\infty} t^{n+p-1} \phi\left(t^{d} g(-1,-z)\right) d t\right) h(-1,-z) d z
\end{aligned}
$$

where the last two integrals are obtained from the sum of the previous two by using Tonelli's Theorem.

## Proof (continued)

Next, with the change of variable $u=t g(1, z)^{1 / d}$ and $u=\operatorname{tg}(-1,-z)^{1 / d}$

$$
\int_{\mathbb{R}^{n}} \phi(g(x)) h(x) d x=\underbrace{\left(\int_{\mathbb{R}_{+}} u^{n+p-1} \phi\left(u^{d}\right) d u\right)}_{\operatorname{Cte}(\phi, p, d)} \cdot A(g, h)
$$

with

$$
A(g, h)=\int_{\mathbb{R}^{n-1}}\left(\frac{h(1, z)}{g(1, z)^{(n+p) / d}}+\frac{h(-1,-z)}{g(-1,-z)^{(n+p) / d}}\right) d z
$$

Choosing $\phi(t)=\exp (-t)$ on $[0,+\infty)$ yields:

$$
\int_{\mathbb{R}^{n}} \exp (-g(x)) h(x) d x=\frac{\Gamma(1+(n+p) / d)}{n+p} \cdot A(g, h),
$$

whereas, choosing $\phi(t)=\mathrm{I}_{[0,1]}(t)$ on $[0,+\infty)$ yields:

$$
\int_{\{x: g(x) \leq 1\}} h(x) d x=\frac{1}{n+p} \cdot A(g, h)
$$

And so in particular, whenever $g$ is nonnegative and $\{x: g(x) \leq 1\}$ is bounded:

## Theorem

If $g, h$ are PHFs of degree $0<d$ and $p$ respectively, then:

$$
\begin{aligned}
\int_{\{x: g(x) \leq y\}} h d x & =\frac{y^{(n+p) / d}}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} \exp (-g) h d x \\
\operatorname{vol}(\{x: g(x) \leq y\}) & =\frac{y^{n / d}}{\Gamma(1+n / d)} \int_{\mathbb{R}^{n}} \exp (-g) d x
\end{aligned}
$$

## An alternative proof

Let $g, h$ be nonnegative so that $I_{g, h}(y)$ vanishes on $(-\infty, 0]$. Its Laplace transform $\lambda \mapsto \mathcal{L}_{g, h}(\lambda)=\int_{0}^{\infty} \exp (-\lambda y) I_{g, h}(y) d y$

$$
\begin{aligned}
\mathcal{L}_{l_{g, h}}(\lambda) & =\int_{0}^{\infty} \exp (-\lambda y)\left(\int_{\{x: g(x) \leq y\}} h d x\right) d y \\
& =\int_{\mathbb{R}^{n}} h(x)\left(\int_{g(x)}^{\infty} \exp (-\lambda y) d y\right) d x \quad \text { [by Fubini] } \\
& =\frac{1}{\lambda} \int_{\mathbb{R}^{n}} h(x) \exp (-\lambda g(x)) d x \\
& =\frac{1}{\lambda^{1+(n+p) / d}} \int_{\mathbb{R}^{n}} h(z) \exp (-g(z)) d z \quad \text { [by homog] } \\
& =\frac{\int_{\mathbb{R}^{n}} h(z) \exp (-g(z)) d z}{\Gamma(1+(n+p) / d)} \mathcal{L}_{y^{(n+p) / d}}(\lambda) .
\end{aligned}
$$

And so, by uniqueness of the Laplace transform,

$$
I_{g, h}(y)=\frac{y^{(n+p) / d}}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} h(x) \exp (-g(x)) d x
$$

## II. Approximating a non gaussian integral

Hence computing the non Gaussian integral $\int \exp (-g) d x$
reduces to computing the volume of the level set
$G:=\{x: g(x) \leq 1\}$,
which is the same as solving the optimization problem:

where

- $\mathbf{B}$ is a box $[-a, a]^{n}$ containing $G$ and
- $\lambda$ is the Lebesgue measure.


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where :

- $B$ is a box $[-a, a]^{n}$ containing $G$ and
- $\lambda$ is the Lebesgue measure.
... and we know how to approximate $\mu(G)$ as closely as desired
Let $G \subseteq B:=[-1,1]^{n}$ (possibly after scaling), and let $z=\left(z_{\alpha}\right)$, $\alpha \in \mathbb{N}_{2 k}^{n}$, be the moments of the Lebesgue measure $\lambda$ on $B$.


## Solve the hierarchy of semidefinite programs:

```
\rhok}=\operatorname{max}\quad\mp@subsup{y}{0}{
    s.t. }\mp@subsup{\mathbf{M}}{k}{}(y),\mp@subsup{M}{k}{}(v)\succeq0
    M
    M}\mp@subsup{\mathbf{k}}{k-1}{}((1-\mp@subsup{x}{i}{2})v)\succeq0,\quadi=1,\ldots,
    y\alpha}+\mp@subsup{v}{\alpha}{}=\mp@subsup{z}{\alpha}{},\quad\alpha\in\mp@subsup{\mathbb{N}}{2k}{n
```

for some moment and localizing matrices $\mathbf{M}_{k}(y)$ and $\mathbf{M}_{k}(g, y)$.

- The linear constraints $y_{\alpha}+v_{\alpha}=z_{\alpha}$ for all $\alpha \in \mathbb{N}_{2 k}^{n}$ "ensure"
$\mu+\nu=\lambda$, while the " $\succeq 0$ " constraints "ensure" supp $\mu=G$ and
$\operatorname{supp} \nu=B$.
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\begin{aligned}
\rho_{k}=\max & y_{0} \\
\text { s.t. } & \mathbf{M}_{k}(y), \mathbf{M}_{k}(v) \succeq 0, \\
& \mathbf{M}_{k-\lceil(d) / 2\rceil}(g y) \succeq 0 \\
& \mathbf{M}_{k-1}\left(\left(1-x_{i}^{2}\right) v\right) \succeq 0, \quad i=1, \ldots, n \\
& y_{\alpha}+v_{\alpha}=z_{\alpha}, \quad \alpha \in \mathbb{N}_{2 k}^{n}
\end{aligned}
$$


supp


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## Lemma

$\rho_{k} \rightarrow \lambda(G)$ as $k \rightarrow \infty$.
(see: Approximate volume and integration for basic semi algebraic sets, Henrion, Lasserre and Savorgnan, SIAM Review 51, 2009.)

## However

the resulting SDPs are numerically difficult to solve.
Solving the dual reduces to approximating the
$/(G)$ by polynomials of increasing degrees $\rightarrow$ Gibbs effect, etc.

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## However ...

the resulting SDPs are numerically difficult to solve.
Solving the dual reduces to approximating the indicator function $I(G)$ by polynomials of increasing degrees $\rightarrow$ Gibbs effect, etc.

## Another identity

## Corollary

If $g$ has degree $d$ and $G$ is bounded then

$$
\begin{aligned}
\frac{\int_{\{x: g(x) \leq y\}} \exp (-g) d x}{\int_{\mathbb{R}^{n}} \exp (-g) d x} & =\frac{\int_{0}^{y} t^{n / d-1} \exp (-t) d t}{\int_{0}^{\infty} t^{n / d-1} \exp (-t) d t} \\
& =\frac{\int_{0}^{y} t^{n / d-1} \exp (-t) d t}{\Gamma(n / d)}
\end{aligned}
$$

expresses how fast $\mu(\{x: g(x) \leq y\})$ goes to $\mu\left(\mathbb{R}^{n}\right)$ as $y \rightarrow \infty$, for the Borel measure $d \mu=\exp (-g) d x$.
It is like for the Gamma function $\Gamma(n / d)$ when approximated by $\int_{0}^{y} t^{n / d-1} \exp (-t) d t$.

## III. Convexity

An interesting issue is to analyze how the Lebesgue volume $\operatorname{vol}\left\{x \in \mathbb{R}^{n}: g(x) \leq 1\right\}$, (i.e. vol $\left.(G)\right)$ changes with $g$.
Recall that $G=\{x: g(x) \leq 1\}$.

## Corollary

Let $h$ be a PHF of degree $p$ and let $C_{d} \subset \mathbb{R}[x]_{d}$ be the convex cone of homogeneous polynomials of degree at most $d$ such that $G$ is bounded. Then the function $f_{h}: C_{d} \rightarrow \mathbb{R}$,

$$
g \mapsto f_{h}(g):=\int_{G} h d x, \quad g \in C_{d},
$$

- is a PHF of degree $-(n+p) / d$,
- convex whenever $h$ is nonnegative and strictly convex if $h>0$ on $\mathbb{R}^{n} \backslash\{0\}$


## Convexity (continued)

## Corollary (continued)

Moreover, if $h$ is continuous and $\int|h| \exp (-g) d x<\infty$ then:

$$
\begin{aligned}
\frac{\partial f_{h}(g)}{\partial g_{\alpha}} & =\frac{-1}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} x^{\alpha} h \exp (-g) d x \\
& =\frac{-\Gamma(2+(n+p) / d)}{\Gamma(1+(n+p) / d)} \int_{G} x^{\alpha} h d x \\
\frac{\partial^{2} f_{h}(g)}{\partial g_{\alpha} \partial g_{\beta}} & =\frac{-1}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} x^{\alpha+\beta} h \exp (-g) d x
\end{aligned}
$$

## PROOF: Just use

$$
\int_{\{x: g(x) \leq 1\}} h d x=\frac{1}{\Gamma(1+(n+p) / d)} \int_{\mathbb{R}^{n}} h \exp (-g) d x
$$

## Notice that proving convexity directly would be non trivial but becomes easy when using the previous lemma!

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Notice that proving convexity directly would be non trivial but becomes easy when using the previous lemma!

## III. Polarity

For a set $C \subset \mathbb{R}^{n}$, recall:

- The support function $x \mapsto \sigma_{C}(x):=\sup _{y}\left\{x^{\top} y: y \in C\right\}$
- The POLAR $C^{\circ}:=\left\{x \in \mathbb{R}^{n}: \sigma_{C}(x) \leq 1\right\}$
- and for a PHF $g$ of degree $d$, its Legendre-Fenchel conjugate $g^{*}(x)=\sup \left\{x^{\top} y-g(y)\right\}$ is a PHF of degree $q$ with $\frac{1}{d}+\frac{1}{q}=1$.


## Polarity (continued)

## Lemma

Let $g$ be a closed proper convex PHF of degree $1<d$ and let $G=\{x: g(x) \leq 1 / d\}$. Then:

$$
\begin{aligned}
G^{\circ} & =\left\{x \in \mathbb{R}^{n}: g^{*}(x) \leq 1 / q\right\} \\
\operatorname{vol}(G) & =\frac{p^{-n / p}}{\Gamma(1+n / p)} \int \exp (-g) d x \\
\operatorname{vol}\left(G^{\circ}\right) & =\frac{q^{-n / q}}{\Gamma(1+n / q)} \int \exp \left(-g^{*}\right) d x
\end{aligned}
$$

$\rightarrow$ yields completly symmetric formulas for $g$ and its conjugate $g^{*}$.

## Examples

- $g(x)=|x|^{3}$ so that $g^{*}(x)=\frac{2}{3 \sqrt{3}}|x|^{3 / 2}$. And so

$$
G=\left[-3^{-1 / 3}, 3^{-1 / 3}\right] ; \quad G^{\circ}=\left[-3^{1 / 3}, 3^{1 / 3}\right]
$$

- TV screen: $g(x)=x_{1}^{4}+x_{2}^{4}$ so that

$$
\begin{aligned}
& g^{*}(x)=4^{-4 / 3} 3\left(x_{1}^{4 / 3}+x_{2}^{4 / 3}\right) . \text { And } \\
& G=\left\{x: x_{1}^{2}+x_{2}^{4} \leq \frac{1}{4}\right\} ; \quad G^{\circ}=\left\{x: x_{1}^{4 / 3}+x_{2}^{4 / 3} \leq 4^{1 / 3}\right\} .
\end{aligned}
$$

- $g(x)=|x|$ so that $d \ngtr 1$, and $g^{*}(x)=0$ if $x \in[-1,1]$, and $+\infty$ otherwise. Hence $G=\{x:|x| \leq 1\}=[-1,1]$ and with $q=+\infty$,

$$
G^{\circ}=[-1,1]=\left\{x: g^{*}(x) \leq \frac{1}{q}=0\right\}
$$

## IV. A variational property of homogeneous polynomials

Let $\mathbf{v}_{d}(x)$ be the vector of monomials $\left(x^{\alpha}\right)$ of degree $d$, i.e., such that $\alpha_{1}+\cdots+\alpha_{n}=d$.
If $g \in \mathbb{R}[x]_{2 d}$ is homogeneous and SOS then

$$
g(x)=\frac{1}{2} \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)
$$

for some real symmetric positive semidefinite matrix $\Sigma \succeq 0$.
And if $d=1$ one has the Gaussian property

$$
\begin{gathered}
\int_{\mathbb{R}^{n}} \exp (-g) d x=\frac{(2 \pi)^{n / 2}}{\sqrt{\operatorname{det} \Sigma}} \\
\frac{\int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} \exp (-g) d x}{\int_{\mathbb{R}^{n}} \exp (-g) d x}=\Sigma^{-1}
\end{gathered}
$$

In other words, if $\mu$ is the Gaussian measure

$$
\mu(B):=\frac{\int_{B} \exp \left(-\frac{1}{2} x^{\top} \Sigma x\right) d x}{\int_{\mathbb{R}^{n}} \exp \left(-\frac{1}{2} x^{\top} \Sigma x\right) d x}, \quad \forall B,
$$

then its (covariance) matrix of moments of order 2 satisfies:

$$
\mathbf{M}_{1}(\Sigma):=\int_{\mathbb{R}^{n}} x x^{\top} d \mu(x)=\Sigma^{-1} .
$$

$\ldots$ not true anymore for $d>1$ !

However, let $\ell(d)=\binom{n+d}{n-1}$, and $\mathcal{S}_{++}^{\ell(d)}$ be the cone of real positive definite $\ell(d) \times \ell(d)$ matrices. Let $k:=n /(2 d \ell(d))$.

With $\Sigma \in \mathcal{S}_{++}^{\ell(d)}$, define the probability measure $\mu$

$$
\mu(B):=\frac{\int_{B} \exp \left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) d x}{\int_{\mathbb{R}^{n}} \exp \left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) d x}, \quad \forall B,
$$

with matrix of moments of order 2d given by:

$$
\mathbf{M}_{d}(\Sigma):=\int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} d \mu(x)
$$

Define $\theta_{d}: \mathcal{S}_{++}^{\ell(d)} \rightarrow \mathbb{R}$ to be the function

$$
\Sigma \mapsto \theta_{d}(\Sigma):=(\operatorname{det} \Sigma)^{k} \int_{\mathbb{R}^{n}} \exp \left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) d x .
$$

## Theorem

$$
\mathbf{M}_{d}(\Sigma)=\Sigma^{-1} \Longleftrightarrow \quad \nabla \theta_{d}(\Sigma)=0
$$

Hence critical points $\Sigma^{*}$ of $\theta_{d}$ have the Gaussian property

$$
\frac{\int \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} \exp \left(-k \mathbf{v}_{d}(x)^{\top} \Sigma^{*} \mathbf{v}_{d}(x)\right) d x}{\int \exp \left(-k \mathbf{v}_{d}(x)^{T} \Sigma^{*} \mathbf{v}_{d}(x)\right) d x}=\left(\Sigma^{*}\right)^{-1}
$$

$\star$ If $d=1$ then $\theta_{d}(\cdot)$ is constant and so $\nabla \theta_{d}(\cdot)=0$.
$\star$ If $d>1$ then $\theta_{d}(\cdot)$ is constant in each ray $\lambda \Sigma, \lambda>0$.

$$
\begin{aligned}
\nabla \theta_{d}(\Sigma)= & k \frac{\Sigma^{\mathbb{A}}}{\operatorname{det} \Sigma} \theta_{d}(\Sigma) \\
& -k(\operatorname{det} \Sigma)^{k} \int_{\mathbb{R}^{n}} \mathbf{v}_{d}(x) \mathbf{v}_{d}(x)^{T} \exp \left(-k \mathbf{v}_{d}(x)^{T} \Sigma \mathbf{v}_{d}(x)\right) d x \\
= & k \theta_{d}(\Sigma)\left[\Sigma^{-1}-\mathbf{M}_{d}(\Sigma)\right]
\end{aligned}
$$

and so

$$
\mathbf{M}_{d}(\Sigma)=\Sigma^{-1} \quad \Rightarrow \quad \nabla \theta_{d}(\Sigma)=0
$$

## V. Sublevel sets $G$ of minimum volume

If $\mathbf{K} \subset \mathbb{R}^{n}$ is compact then computing the ellipsoid $\xi$ of minimum volume containing $\mathbf{K}$ is a classical problem whose optimal solution is called the Löwner-John ellipsoid.
So consider the following problem:

Find an homogeneous polynomial $g \in \mathbb{R}[x]_{2 d}$ such that its sub level set $G:=\{x: g(x) \leq 1\}$ contains K and has minimum volume among all such levels sets with this inclusion property.

Let $\mathbf{P}[x]_{2 d}$ be the convex cone of homogeneous polynomials of degree $2 d$ with compact sub-level set $\{x: g(x) \leq 1\}$, and with $\mathbf{K} \subset \mathbb{R}^{n}$, let $C_{2 d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on $\mathbf{K}$.


Let $\mathbf{P}[x]_{2 d}$ be the convex cone of homogeneous polynomials of degree $2 d$ with compact sub-level set $\{x: g(x) \leq 1\}$, and with $\mathbf{K} \subset \mathbb{R}^{n}$, let $C_{2 d}(\mathbf{K})$ be the convex cone of polynomials nonnegative on $\mathbf{K}$.

## Lemma

Let $\mathrm{K} \subset \mathbb{R}^{n}$ be compact. The minimum volume of a sublevel set $\{\mathbf{x}: g(\mathbf{x}) \leq 1\}, g \in \mathbf{P}[x]_{2 d}$, that contains $\mathbf{K} \subset \mathbb{R}^{n}$ is
$\rho / \Gamma(1+n / 2 d)$ where:
$\mathcal{P}: \quad \rho=\inf _{g \in \mathbf{P}[x]_{2 d}}\left\{\int_{\mathbb{R}^{n}} \exp (-g) d x: 1-g \in C_{2 d}(\mathbf{K})\right\}$.
a finite-dimensional convex optimization problem!

- We have seen that:

$$
\operatorname{vol}(\{x: g(x) \leq 1\})=\frac{1}{\Gamma(1+n / 2 d)} \int_{\mathbb{R}^{n}} \exp (-g) d x
$$

Moreover, the sub-level set $\{x: g(x) \leq 1\}$ contains K if and only if $1-g \in C_{2 d}(\mathbf{K})$, and so $\rho / \Gamma(1+n / 2 d)$ is the minimum value of all volumes of sub-levels sets $\{x: g(x) \leq 1\}$, $g \in \mathbf{P}[\mathbf{x}]_{2 d}$, that contain K.

- Now since $g \mapsto \int_{\mathbb{R}^{n}} \exp (-g) d x$ is strictly convex and $C_{2 d}(K)$ is a convex cone, problem $\mathcal{P}$ is a finite-dimensional convex optimization problem.


## V (continued). Characterizing an optimal solution

## Theorem

(a) $\mathcal{P}$ has a unique optimal solution $g^{*} \in \mathbf{P}[x]_{2 d}$ and there exists a Borel measure $\mu^{*}$ supported on $\mathbf{K}$ such that:

$$
(*):\left\{\begin{array}{l}
\int_{\mathbb{R}^{n}} x^{\alpha} \exp \left(-g^{*}\right) d x=\int_{\mathbf{K}} x^{\alpha} d \mu^{*}, \quad \forall|\alpha|=2 d \\
\int_{\mathbf{K}}\left(1-g^{*}\right) d \mu^{*}=0
\end{array}\right.
$$

In particular, $\mu^{*}$ is supported on the real variety $V:=\left\{x \in \mathbf{K}: g^{*}(\mathbf{x})=1\right\}$ and in fact, $\mu^{*}$ can be substituted with another measure $\nu^{*}$ supported on at most $\binom{n+2 d-1}{2 d}+1$ points of $V$.
(b) Conversely, if $g^{*} \in \mathbf{P}[x]_{2 d}$ and $\mu^{*}$ satisfy (*) then $g^{*}$ is an optimal solution of $\mathcal{P}$.

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## VI. Recovering $g$ from moments of $G$

Write $g(x)=\sum_{\beta} g_{\beta} x^{\beta}$.

## Lemma

If $g$ is nonnegative and $d$-homogeneous with $G$ compact then:

$$
\underbrace{\int_{G} x^{\alpha} g(x) d x}_{\sum_{\beta} g_{\beta} y_{\alpha+\beta}}=\frac{n+|\alpha|}{n+d+|\alpha|} \underbrace{\int_{G} \mathbf{x}^{\alpha} d x}_{y_{\alpha}}, \quad \alpha \in \mathbb{N}^{n} .
$$

and so we see that the moments $\left(y_{\alpha}\right)$ satisfy linear relationships explicit in terms of the coefficients of the polynomial $g$ that describes the boundary of $G$.

So let us write $\mathbf{g} \in \mathbb{R}^{s(d)}$ the unknown vector of coefficients of the unknown polynomial $g$.
Let $\mathbf{M}_{d}(y)$ be the moment matrix of order $d$ whose rows and columns are indexed in the canonical basis of monomials ( $x^{\alpha}$ ), $\alpha \in \mathbb{N}_{d}^{n}$, and with entries

$$
\mathbf{M}_{d}(y)(\alpha, \beta)=y_{\alpha+\beta}, \quad \alpha, \beta \in \mathbb{N}_{d}^{n} .
$$

and let $\mathbf{y}^{d}$ be the vector $\left(y_{\alpha}\right), \alpha \in \mathbb{N}_{d}^{n}$.

## Previous Lemma states that

$$
\mathbf{M}_{d}(y) \mathbf{g}=\mathbf{y}^{d},
$$

or, equivalently,

$$
\mathbf{g}=\mathbf{M}_{d}(y)^{-1} \mathbf{y}^{d},
$$

because the moment matrix $\mathbf{M}_{d}(y)$ is nonsingular whenever $G$ has nonempty interior.

## In other words ...

## one may recover $g$ EXACTLY from knowledge of moments $\left(y_{\alpha}\right)$ of order $d$ and $2 d$ !

## Conclusion

- Compact sub-level sets $G:=\{x: g(x) \leq y\}$ of homogeneous polynomials exhibit surprising properties. E.g.:
- convexity of volume $(G)$ with respect to the coefficients of $g$
- Integrating a PHF $h$ on $G$ reduce to evaluating the non Gaussian integral $\int h \exp (-g) d x$
- A variational property yields a Gaussian-like property
- exact recovery of $G$ from finitely moments.

Also works for
polynomials with bounded
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- convexity of volume $(G)$ with respect to the coefficients of $g$
- Integrating a PHF $h$ on $G$ reduce to evaluating the non Gaussian integral $\int h \exp (-g) d x$
- A variational property yields a Gaussian-like property
- exact recovery of $G$ from finitely moments.

Also works for quasi-homogeneous polynomials with bounded sublevel sets!

## Practical and important issues

- COMPUTATION!: Efficient evaluation of $\int_{\mathbb{R}^{n}} \exp (-g) d x$, or equivalently, evaluation of $\operatorname{vol}(\{x: g(x) \leq 1\}$ !
- The property

$$
\int_{G} \mathbf{x}^{\alpha} g(x) d x=\frac{n+|\alpha|}{n+d+|\alpha|} \int_{G} x^{\alpha} d x, \quad \forall \alpha,
$$

helps a lot to improve efficiency of the method in Henrion, Lasserre and Savorgnan (SIAM Review)

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- What about non-homogeneous polynomials?


## THANK YOU!


[^0]:    ${ }^{1}$ New and old results in Resultant theory, arXiv.0911.5278v1.

