

Large Volatility Matrix Estimation for High-Frequency Financial Data

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Outline

1. High-Frequency Data
2. Large Volatility Matrix Estimation
3. Convergence Rate and Positiveness
4. Numerical Studies

High-Frequency Finance

High-Frequency Data: Intradaily observations on asset prices such as tick by tick stock price data and minute by minute exchange rate data.

Data Characteristics: High-frequency data have complex structure with microstructure noise.

One-Dim Model: Observed data: Y_{t_i} , $i = 1, \dots, n$ and $X_t =$ true log-price of a stock

$$Y_{t_i} = X_{t_i} + \varepsilon_{t_i}, \quad i = 1, \dots, n$$

ε_{t_i} : microstructure noise and independent of X_t .

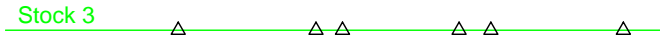
Very High Dim: Large Volatility Matrix

High Dim Model: For the i -th asset, observation times t_{ij} , $i = 1, \dots, p$, $j = 1, \dots, n_i$ and observed log price $Y_i(t_{i,j})$,

$$Y_i(t_{i,j}) = X_i(t_{i,j}) + \varepsilon_i(t_{i,j}),$$

$X_i(t)$: true log price of asset i , and microstructure noise $\varepsilon_i(\cdot)$: i.i.d. with zero mean, and independent of $X_i(t)$.

Nonsynchronization: stocks' transactions occur at distinct times and the prices of different stocks are recorded at mismatched time points.



Time

Price Model

$X_t = (X_{1t}, \dots, X_{pt})^\dagger$: log price of p assets

$$dX_t = \mu_t dt + \sigma_t dW_t, \quad t \in [0, 1],$$

where W_t : p -dimensional BM, and σ_t : $p \times p$ matrix.

Integrated volatility matrix:

$$\Gamma = \int_0^1 \gamma(t) dt, \quad \gamma(t) = \sigma_t \sigma_t^\dagger$$

Goal: Estimate Γ based on data $Y_i(t_{ij})$.

Methodology:

1. Form volatility matrix estimators
2. Regularize the matrix estimators

Realized co-volatility based on previous tick

$\tau = \{\tau_r = r/m, r = 1, \dots, m\}$: pre-determined sampling frequency.

For asset i , select previous-tick times:

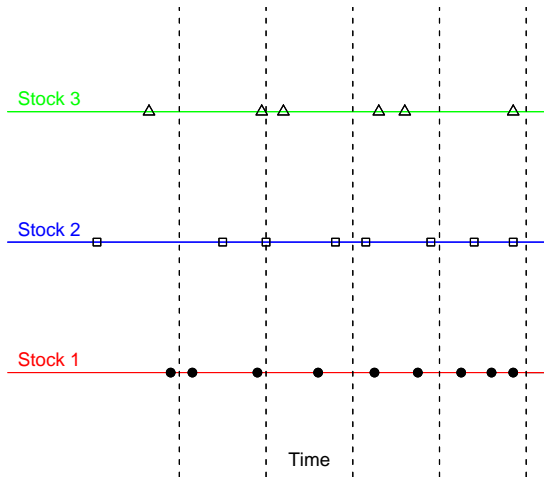
$$\tau_{i,r} = \max\{t_{i_s,j} \leq \tau_r, j = 1, \dots, n_{i_s}\}, \quad r = 1, \dots, m$$

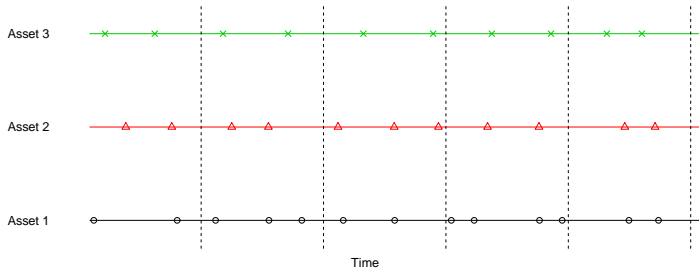
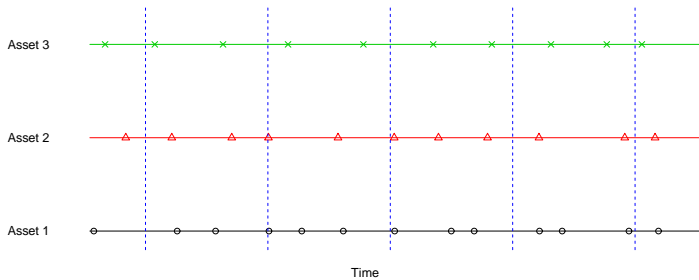
Realized co-volatility $\hat{\Gamma}_{i_1 i_2}(\tau)$ between assets i_1 and i_2 :

$$\hat{\Gamma}_{i_1, i_2}(\tau) = \sum_{r=1}^m [Y_{i_1}(\tau_{i_1, r}) - Y_{i_1}(\tau_{i_1, r-1})] [Y_{i_2}(\tau_{i_2, r}) - Y_{i_2}(\tau_{i_2, r-1})].$$

Realized co-volatility matrix: $\hat{\mathbf{\Gamma}}(\tau) = (\hat{\Gamma}_{i_1 i_2}(\tau))$

Data synchronization: Previous tick





Two-scale

Realized volatility matrix estimator

$$\tau^k = \tau + (k - 1)/n, \quad k = 1, \dots, K = [n/m]$$

$$\hat{\Gamma}^K = \frac{1}{K} \sum_{k=1}^K \hat{\Gamma}(\tau^k), \quad n = \sum_{i=1}^p n_i/p$$

where $\hat{\Gamma}_{ii}$ are adjusted by subtracting them from estimated noise variance components: $\frac{2m}{n_i} \sum_{\ell=1}^{n_i} [Y_i(t_{i,\ell}) - Y_i(t_{i,\ell-1})]^2$

Asymptotics:

$$\text{Entrywise} \quad \hat{\Gamma}^K - \Gamma = O_P(n^{-1/6}), \quad \text{if } K \sim n^{2/3}$$

Multi-scale

Realized volatility matrix estimator

$$\hat{\Gamma} = \sum_{m=1}^M a_m \hat{\Gamma}^{K_m} + \zeta (\hat{\Gamma}^{K_1} - \hat{\Gamma}^{K_M}), \quad (1)$$

where $K_m = m + N$,

$$a_m = \frac{12(m+N)(m-M/2-1/2)}{M(M^2-1)}, \quad \zeta = \frac{(M+N)(N+1)}{(n+1)(M-1)} \quad (2)$$

Asymptotics:

$$\text{Entrywise} \quad \hat{\Gamma} - \Gamma = O_P(n^{-1/4}), \quad \text{if } M, N \sim n^{1/2}$$

Data Synchronization: Refresh time

Asset i has trading time $t_j^i, j = 1, \dots, n^i = N_1^i$

$N_t^i = \#$ of $t_j^i, j = 1, \dots, n^i$, that $\leq t$

Define 1st refresh time: $\tau_1 = \max(t_1^1, \dots, t_1^p)$, subsequent refresh times

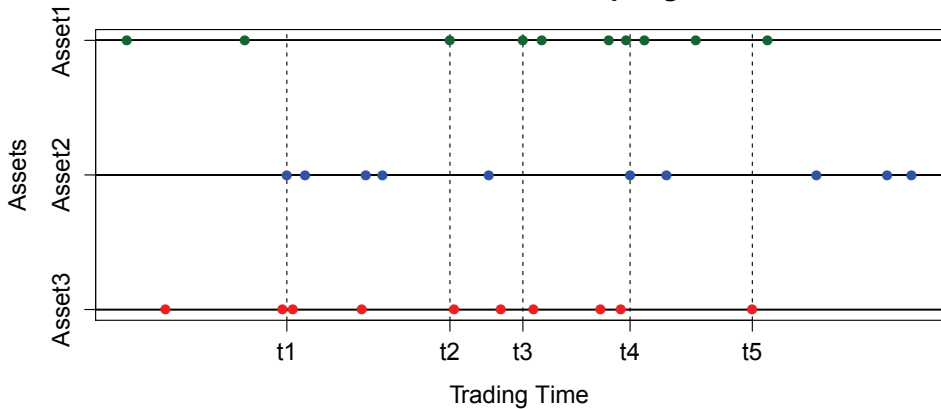
$$\tau_{j+1} = \max(t_{N_{\tau_j}^1+1}^1, \dots, t_{N_{\tau_j}^p+1}^p).$$

Intuition: τ_1 is the time all their posted prices have been updated (i.e it has taken for all assets to trade); τ_2 is the first time when all the prices are again updated.

At each refreshed time τ_j , one new price and $p - 1$ stale prices

Let $m =$ the resulting Refresh Time sample size

Refresh Time Sampling



Realized kernel based on refresh time

Synchronized data: at refresh time $\tau_j, j = 1, \dots, m$, define

$Y_i(\tau_j) =$ observation of asset i at time point $t_{N\tau_j}^i$

$\mathbf{Y}_j(\cdot) = (Y_1(\tau_j), \dots, Y_p(\tau_j))'$, $\mathbf{y}_j = \mathbf{Y}(\tau_j) - \mathbf{Y}(\tau_{j-1}), j = 1, \dots, m$

$$\gamma_h = \sum_{j=|h|+1}^m \mathbf{y}_j \mathbf{y}'_{j-h}, \quad h \geq 0 \quad \gamma_h = \sum_{j=|h|+1}^m \mathbf{y}_{j-1} \mathbf{y}'_j, \quad h < 0$$

Realized Kernel estimator $H(\mathbf{Y}) = \sum_{h=-m}^m H\left(\frac{h}{K+1}\right) \gamma_h$ for kernel $H(\cdot)$

Asymptotics: $H(\mathbf{Y})$ can be semi-positive but with entrywise

convergence rate $n^{-1/5}$

Or it may achieve $n^{-1/4}$ convergence rate but not semi-positive.

Data Synchronization: Generalized sampling time

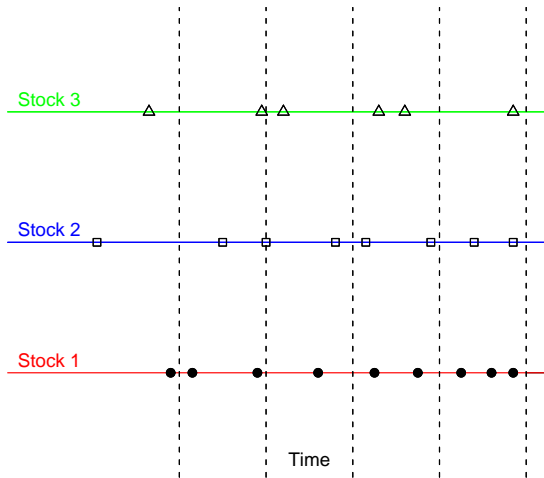
A sequence of time points $\{\tau_0, \tau_1, \tau_2, \dots, \tau_m\}$ is said to be the Generalized Sampling Time for a collection of p assets, if

1. $0 = \tau_0 < \tau_1 < \dots < \tau_m = T$.
2. Each asset has at least one observation between consecutive τ_j 's.
3. Time intervals, $\{\Delta_j = \tau_j - \tau_{j-1}, 1 \leq j \leq m\}$, satisfy $\sup_i \Delta_i \xrightarrow{P} 0$.

The synchronized data sets are generated by selecting an arbitrary observation $Y_i(\check{t}_j)$ of the i th asset in time interval $(\tau_{j-1}, \tau_j]$. Therefore, the synchronized data are $\{Y_i(\tau_j), 1 \leq i \leq p, 1 \leq j \leq m\}$ such that $Y_i(\tau_j) = Y_i(\check{t}_j)$.

It allows to choose the sampling times by requiring each asset to lead in turn.

Data synchronization: Generalized sampling time



Estimators based on generalized sampling time

Previous-tick and refresh time schemes may be treated as special cases of generalized sampling time.

With synchronized data $Y_i(\tau_j)$ we may define MSRVE estimator, Realized kernel estimator, and quasi-MLE to achieve entrywise convergence rate $n^{-1/4}$.

Pre-averaging estimator

Define the difference of two local averages at j/n ,

$$\bar{Y}_{ij} = \frac{2}{K} \left[\sum_{\ell=K/2}^{K-1} Y_i(t_{i,j+\ell}) - \sum_{j=0}^{K/2-1} Y_i(t_{i,j+\ell}) \right],$$

and realized volatility based on all \bar{Y}_{ij}

$$ARV = \frac{1}{K} \sum_{i=0}^{n-K+1} (\bar{Y}_{1j}, \dots, \bar{Y}_{pj})' (\bar{Y}_{1j}, \dots, \bar{Y}_{pj}).$$

Asymptotics: ARV can be semi-positive but with entrywise convergence rate $n^{-1/5}$.

Or adjust the biases of ARV for the noise variances to obtain $PARV$ with $n^{-1/4}$ convergence rate but not semi-positive.

Matrix Size

Dimension Reduction For moderate to large p , $(p^2 + p)/2$ entries in Γ : too many parameters and too much random fluctuation.

Issue: Usual dimension reduction techniques are **not applicable** to non-synchronized data.

Numerical Illustration

$X(t) = (W_1(t), \dots, W_p(t))$: vector of p independent Brownian motions.

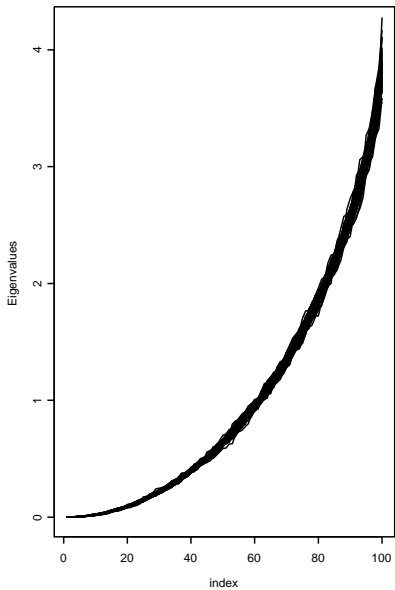
Observations = $X(k/n)$, $k = 0, 1, \dots, n$.

$$\Gamma = I_p, \quad \hat{\Gamma} = (\hat{\Gamma}_{ij}), \quad \hat{\Gamma}_{ij} = \frac{1}{n} \sum_{k=1}^N Z_{ik} Z_{jk}$$

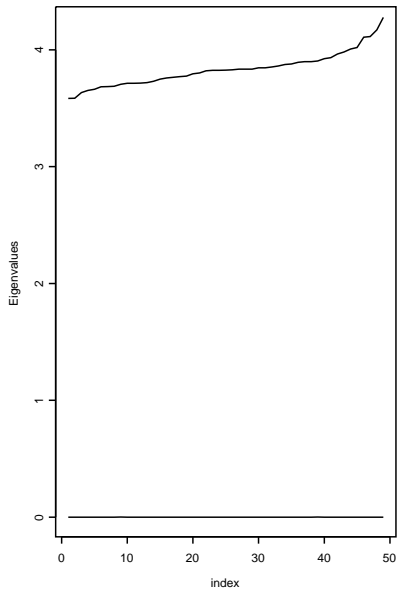
$$Z_{ik} = \sqrt{n}[W_i(k/n) - W_i((k-1)/n)] \sim N(0, 1)$$

Take $n = 100$ and $p = 100$. We compute the eigenvalues of $\hat{\Gamma}$ in a simulation with 50 replications.

(a) 50 sets of ordered 100 eigenvalues



(b) 50 pairs of max and min eigenvalues



Regularize Volatility Matrix

Write $\Gamma = (\Gamma_{ij})$

Sparsity: assume Γ has a sparse representation

$$\sum_{j=1}^p |\Gamma_{ij}|^\delta \leq M \pi(p), \quad i = 1, \dots, p, \quad E[M] \leq C,$$

where $0 \leq \delta < 1$ and $\pi(p) = 1, \log p$, or a small power of p .

Examples: (1) Block diagonal matrix

(2) Matrix with decay elements from diagonal

(3) Matrix with small number of non-zero elements in each row

(4) Random permutations of rows and columns for above matrices

Estimation with regularization

Write $\hat{\Gamma} = (\hat{\Gamma}_{ij})$ as any of volatility matrix estimators

Thresholding: for sparse Γ , regularize $\hat{\Gamma}$ by hard and soft thresholding rules

$$\text{Hard : } \mathcal{T}_{\varpi}[\hat{\Gamma}] = \left(\hat{\Gamma}_{ij} \mathbf{1}(|\hat{\Gamma}_{ij}| \geq \varpi, i \neq j) \right) + \left(\hat{\Gamma}_{ij} \mathbf{1}(|\hat{\Gamma}_{ij}| \geq 0, i = j) \right),$$

$$\text{Soft: } \mathcal{T}_{\varpi}[\hat{\Gamma}] = \left((\hat{\Gamma}_{ij} - \text{sign}(\hat{\Gamma}_{ij})\varpi) \mathbf{1}(|\hat{\Gamma}_{ij}| \geq \varpi, i \neq j) \right) + \left(\hat{\Gamma}_{ij} \mathbf{1}(|\hat{\Gamma}_{ij}| \geq 0, i = j) \right).$$

where ϖ is a threshold.

Technical conditions

A1: $\varepsilon_i(\cdot)$, $\mu_i(t)$, and $\sigma_{ii}^{1/2}(t)$ all have bounded 2β moments.

A2: Each asset has at least one observation between consecutive time points of the selected sampling frequency. With $n = (n_1 + \dots + n_p)/p$,

$$C_1 \leq \min_{1 \leq i \leq p} \frac{n_i}{n} \leq \max_{1 \leq i \leq p} \frac{n_i}{n} \leq C_2, \quad \max_{1 \leq i \leq p} \max_{1 \leq \ell \leq n_i} |t_{i\ell} - t_{i,\ell-1}| = O(n^{-1}).$$

Asymptotic Theory: Convergence rate

Matrix norm

$$\|\Gamma\|_2 = \sup\{\|\Gamma \mathbf{x}\|_2, \|\mathbf{x}\|_2 = 1\} = \max \text{ absolute eigenvalue}$$

Theorem Assume sparsity on Γ and conditions A1-A2. If $\hat{\Gamma}$ is any of volatility matrix estimators using [\(i\)](#) multi-scale based on previous-tick or generalized sampling scheme; [\(ii\)](#) realized kernel based on refresh time or generalized sampling scheme; [\(iii\)](#) pre-averaging, and $\hat{\Gamma}$ has entrywise convergence rate $n^{-1/4}$, we have

$$\|\mathcal{I}_{\varpi}[\hat{\Gamma}] - \Gamma\|_2 = O_P\left(\pi(p) \left[n^{-1/4} p^{2/\beta}\right]^{1-\delta}\right),$$

where $\varpi \sim n^{-1/4} p^{2/\beta}$.

Asymptotic Theory: Semi-positiveness

Theorem Assume sparsity on Γ and conditions A1-A2. If $\hat{\Gamma}$ is one of **(a)** semi-positive pre-averaging estimator; **(b)** semi-positive realized kernel estimator based on refresh time or generalized sampling scheme, and $\hat{\Gamma}$ has entrywise convergence rate $n^{-1/5}$, then $\mathcal{T}_{\varpi}[\hat{\Gamma}]$ is semi-positive and

$$\|\mathcal{T}_{\varpi}[\hat{\Gamma}] - \Gamma\|_2 = O_P \left(\pi(p) \left[n^{-1/5} p^{2/\beta} \right]^{1-\delta} \right),$$

where $\varpi \sim n^{-1/5} p^{2/\beta}$.

Asymptotic optimality: Multi-scale RV with sub-Gaussian noise

$\varepsilon_i(\cdot)$ have sub-Gaussian tail, $\mu_i(t)$ and $\sigma_{ii}(t)$ are bounded, data are synchronized.

Theorem For sparse Γ , we have for multi-scale RV based on previous-tick scheme,

$$\|\mathcal{I}_{\varpi}[\hat{\Gamma}] - \Gamma\|_2 = O_P\left(\pi(p) \left[n^{-1/4} \sqrt{\log p}\right]^{1-\delta}\right),$$

where $\varpi \sim n^{-1/4} \sqrt{\log p}$.

Lower bound: For sparse Γ , we have that for any estimator $\check{\Gamma}$

$$\inf_{\check{\Gamma}} \sup_{\Gamma} \mathbb{E} \|\check{\Gamma} - \Gamma\|_2 \asymp c\pi(p) \left[n^{-1/4} \sqrt{\log p}\right]^{1-\delta},$$

where c is a generic constant.

Optimal Estimator: Threshold Multi-scale RV based on previous-tick

Optimality

Take $\boldsymbol{\mu}_t = \mathbf{0}$, $\sigma_t = \sigma$, $\boldsymbol{\Gamma} = \sigma \sigma^\dagger$,

$$Y_i(t_j) = \sigma \mathbf{W}_{t_j} + \varepsilon_i(t_j), \quad j = 1, \dots, n$$

$$Y_i(t_j) - Y_i(t_{j-1}) = \sigma [\mathbf{W}_{t_j} - \mathbf{W}_{t_{j-1}}] + \varepsilon_i(t_j) - \varepsilon_i(t_{j-1})$$

Take discrete sine transform

$$\mathbf{U}_l = \sigma \mathbf{V}_l + \kappa \sin \left[\frac{\pi l}{2(n+1)} \right] \mathbf{e}_l, \quad l = 1, \dots, n$$

where $\mathbf{V}_l \sim N(\mathbf{0}, \mathbf{I}_p)$, $\mathbf{e}_l \sim N(\mathbf{0}, \mathbf{I}_p)$

Covariance matrix estimation: Lower Bound

$$\mathbf{u}_l \sim N\left(0, \mathbf{\Gamma} + \kappa^2 \sin^2\left[\frac{\pi l}{2(n+1)}\right] \mathbf{I}_p\right), \quad l = 1, \dots, n$$

Theorem For sparse $\mathbf{\Gamma}$, we have that for any estimator $\check{\mathbf{\Gamma}}$

$$\inf_{\check{\mathbf{\Gamma}}} \sup_{\mathbf{\Gamma}} \mathbb{E} \|\check{\mathbf{\Gamma}} - \mathbf{\Gamma}\|_2 \asymp c\pi(p) \left[n^{-1/4} \sqrt{\log p}\right]^{1-\delta},$$

where c is a generic constant.

Optimal Estimator: $\mathcal{T}_{\varpi}[\hat{\mathbf{\Gamma}}]$.

Some Insights

$$Y_i(t_{i,j}) = X_i(t_{i,j}) + \varepsilon_i(t_{i,j})$$

$$X_i(t_{i,j}) = \int_0^{t_{i,j}} \mu_{i,s} ds + \int_0^{t_{i,j}} \sigma_{i,s} dW_s$$

- (1) Noise = Measurement Error: $n^{-1/4}$
- (2) SubGaussian: $\sqrt{\log p}$
- (3) Matrix Sparsity: $\pi(\rho) \& \delta$

Concluding Remarks

- Good matrix estimators may perform poorly when the matrix size is very large. We need to regularize large sample covariance and volatility matrix estimators.
- For sparse volatility matrices, thresholding yields great or even optimal volatility matrix estimators.

<http://www.stat.wisc.edu/~yzwang>