Workshop on Stochastic Games IMS, National University of Singapore

Symmetric Equilibria in Stochastic Timing Games

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Motivation

Most timing games fall into two classes:

- First-mover advantage ⇒ preemption
- Second-mover advantage \Rightarrow war of attrition
- > Equilibria for general games?
- > Payoffs in different equilibria?
- > When does preemption (have to) occur?

Examples

- Preemption: market entry
- War of attrition: market exit
- In general: strategic investment, real options

Stochastic stopping games in continuous time with non-zero-sum payoffs

- Subgame-perfect equilibria for general symmetric games
- "Efficiency" and degree of preemption in equilibrium

Literature

- Fudenberg & Tirole (1985)
- Hendricks, Weiss & Wilson (1987, 88, 92)
- Laraki, Solan & Vieille (2005), Laraki & Solan (2013)
- Hamadène & Zhang (2010), Hamadène & Hassani (2011)
- zero-sum Dynkin games, applications ...

Introduction: The setting

We consider a **stopping game** for the players $i \in \{1, 2\}$ in terms of

- a filtered probability space $\left(\Omega,\mathscr{F},(\mathscr{F}_t)_{t\geq 0},P
 ight)$ and
- the processes $(L_t)_{t\geq 0}$, $(F_t)_{t\geq 0}$ and $(M_t)_{t\geq 0}$,

where it is assumed that

- $(\mathscr{F}_t)_{t\geq 0}$ satisfies the "usual conditions",
- L, F, and M are adapted, right-continuous (a.s.) and of class (D).

> Payoffs from *pure* strategies = stopping times:

$$V_i(\tau_i, \tau_j) = E \Big[\mathbf{1}_{\tau_i < \tau_j} L_{\tau_i} + \mathbf{1}_{\tau_i > \tau_j} F_{\tau_j} + \mathbf{1}_{\tau_i = \tau_j} M_{\tau_i} \Big].$$

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Mixed strategies Riedel & Steg (2014)

A **subgame** of the stopping game is any (\mathscr{F}_t) -stopping time ϑ with the connotation that no player has stopped before.

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An **extended mixed strategy** for player $i \in \{1, 2\}$ in the stopping game is a family of progressively measurable processes

$$(G_i, \alpha_i) = (G_i^\vartheta, \alpha_i^\vartheta)_{\vartheta \in \mathscr{T}}$$

where for any subgame/stopping time $\vartheta \in \mathscr{T}$:

- G_i^ϑ is non-decreasing, right-continuous, and [0,1]-valued with $G_i^\vartheta(\vartheta-)=0$,
- α_i^ϑ is [0,1]-valued and right-continuous where $\alpha_i^\vartheta < 1$,

•
$$\alpha_i^{\vartheta}(t) > 0 \Rightarrow G_i^{\vartheta}(t) = 1 \ \forall t \ge \vartheta.$$

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[cf. Fudenberg & Tirole, 1985; Touzi & Vieille, 2002]

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Payoffs Riedel & Steg (2014)

The **continuation payoff** for player *i* in the subgame at ϑ is

$$\begin{split} V_i^\vartheta \big(G_i^\vartheta, \alpha_i^\vartheta, G_j^\vartheta, \alpha_j^\vartheta \big) &= E \bigg[\int_{\vartheta}^{\hat{\tau}^\vartheta} \big(1 - G_j^\vartheta(t) \big) L_t \, dG_i^\vartheta(t) \\ &+ \int_{\vartheta}^{\hat{\tau}^\vartheta} \big(1 - G_i^\vartheta(t) \big) F_t \, dG_j^\vartheta(t) \\ &+ \sum_{t < \hat{\tau}^\vartheta} \Delta G_i^\vartheta(t) \Delta G_j^\vartheta(t) M_t \\ &+ \lambda_{L,i}^\vartheta L_{\hat{\tau}^\vartheta} + \lambda_{L,j}^\vartheta F_{\hat{\tau}^\vartheta} + \lambda_M^\vartheta M_{\hat{\tau}^\vartheta} \bigg| \mathscr{F}_\vartheta \bigg] \end{split}$$

with "definite stopping" time

$$\hat{\tau}^{\vartheta} := \inf\{t \ge \vartheta \mid \alpha_1(t) + \alpha_2(t) > 0\}$$

and outcome probabilities $\lambda_{L,i}^{\vartheta}$, $\lambda_{F,i}^{\vartheta}$ and λ_{M}^{ϑ} determined by α_{1}, α_{2} .

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Equilibrium concept Riedel & Steg (2014)

A mixed strategy is **time consistent** if for all stopping times $\vartheta \leq \tau$

•
$$t \ge \tau \Rightarrow G_i^\vartheta(t) = G_i^\vartheta(\tau-) + (1 - G_i^\vartheta(\tau-))G_i^\tau(t)$$
 (Bayes),

• $\alpha_i^{\vartheta}(t) = \alpha_i^{\tau}(t)$ (conditional stopping probabilities).

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A subgame-perfect equilibrium for the stopping game is a pair of time consistent extended mixed strategies such that for all stopping times ϑ , $i, j \in \{1, 2\}$, and extended mixed strategies $(G_a^\vartheta, \alpha_a^\vartheta)$

$$V_i^\vartheta(G_i^\vartheta,\alpha_i^\vartheta,G_j^\vartheta,\alpha_j^\vartheta) \geq V_i^\vartheta(G_a^\vartheta,\alpha_a^\vartheta,G_j^\vartheta,\alpha_j^\vartheta) \quad \text{a.s.},$$

i.e., such that every pair $(G_1^\vartheta, \alpha_1^\vartheta)$, $(G_2^\vartheta, \alpha_2^\vartheta)$ is an *equilibrium* in the subgame at ϑ , respectively.

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Preemption for L > F [cf. Fudenberg & Tirole, 1985]



extended strategies \Rightarrow partial coordination \Rightarrow immediate stopping, symmetric payoffs F_{ϑ}

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Preemption for L > F [cf. Fudenberg & Tirole, 1985]



Riedel & Steg (2014): extension to stochastic games (also asymmetric)

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War of attrition for $F \ge L$



War of attrition for $F \ge L$



War of attrition for $F \ge L$

Define preemption point $au_{\mathcal{P}}^{\vartheta} := \inf\{t \geq \vartheta \mid L_t > F_t\}$

Constrained leader payoff

$$\tilde{L}^{\vartheta} := \begin{cases} L & \text{if } t < \tau_{\mathcal{P}}^{\vartheta} \\ F_{\tau_{\mathcal{P}}^{\vartheta}} & \text{if } t \ge \tau_{\mathcal{P}}^{\vartheta} \end{cases}$$

 \Rightarrow quit if optimal to stop \tilde{L}^ϑ

- \Rightarrow value given by Snell envelope $U_{\tilde{L}}^{\vartheta}=M_{\tilde{L}}^{\vartheta}-D_{\tilde{L}}^{\vartheta}$
- \Rightarrow expected loss of waiting given by monotone compensator $D_{\tilde{L}}^{\vartheta}$

General symmetric equilibria

Theorem

Assume that $\min(L, F)$ is upper-semicontinuous in expectation. The mixed strategies G_1 and G_2 given by

$$\begin{aligned} G_1^\vartheta(t) &:= 1 - \mathbf{1}_{t < \tau_{\mathcal{P}}^\vartheta} \exp\left\{-\int_\vartheta^t \frac{dD_{\tilde{L}}^\vartheta(s)}{F_s - L_s}\right\} \\ G_2^\vartheta(t) &:= 1 - \mathbf{1}_{t < \tau_{\mathcal{P}}^\vartheta} \exp\left\{-\int_\vartheta^t \mathbf{1}_{F > L} \frac{dD_{\tilde{L}}^\vartheta(s)}{F_s - L_s}\right\} \end{aligned}$$

are part of a subgame perfect equilibrium with symmetric payoffs.

- $dD^{\vartheta}_{\tilde{L}}$ expected loss from late stopping ightarrow teased by payoff F
- time consistency over subgames ϑ : $D^{\vartheta}_{\tilde{L}}$ depends on $\tau^{\vartheta}_{\mathcal{P}}$

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Avoiding preemption

So far: game ends wherever L > F

High future continuation values

 \Rightarrow abstain from preemption

 \Rightarrow higher equilibrium payoffs



Payoff bounds

Proposition

Suppose $M \leq \min(L, F)$. Then, in any **payoff-symmetric** equilibrium and for any $\vartheta \in \mathscr{T}$,

$$V_i^\vartheta \left(G_i^\vartheta, \alpha_i^\vartheta, G_j^\vartheta, \alpha_j^\vartheta \right) \le U_{L \wedge F}(\vartheta) := \operatorname{ess\,sup}_{\tau \ge \vartheta} E \left[L_\tau \wedge F_\tau \mid \mathscr{F}_\vartheta \right].$$

- $\Rightarrow \text{ definite preemption at } \tau_0^\vartheta := \inf\{t \ge \vartheta \mid L > U_{L \wedge F}\}$
- \Rightarrow equilibrium payoffs bounded by $\operatorname{ess\,sup}_{\tau \in [\vartheta, \tau_0^\vartheta]} E \left[L_\tau \wedge F_\tau \mid \mathscr{F}_\vartheta \right]$

Preemption points

Preemption: L > F, M at global Maximum



Case A, Fudenberg and Tirole (1985)

Efficient equilibria

Theorem

Assume $M \leq \min(L, F)$ and that the latter is upper-semicontinuous in expectation. Then there exists a maximal payoff-symmetric equilibrium with value

$$V_1^{\vartheta} = V_2^{\vartheta} = \operatorname{ess\,sup}_{\tau \in [\vartheta, \tilde{\tau}(\vartheta)]} E\left[L_{\tau} \wedge F_{\tau} \mid \mathscr{F}_{\vartheta}\right]$$

for any $\vartheta \in \mathscr{T}$, where $\tilde{\tau}(\vartheta)$ is the latest sustainable preemption point after ϑ given by the limit

$$\tilde{\tau}(\vartheta) := \lim_{n \to \infty} \tau_n(\vartheta)$$

of iterating the previous scheme.

(Problem: Make α_i^{ϑ} measurable.)

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Conclusion and Outlook

- Construction of subgame perfect equilibria for symmetric games with arbitrary **local** first or second mover advantages
- Algorithm to determine latest sustainable preemption points
- Least preemption yields payoff-maximal equilibrium
- Application to strategic real option models with varying incentives:
 e.g. Steg & Thijssen (2015) → Markovian stopping rates

Thank you!

Application Steg & Thijssen (2015)

Example:

- Two firms operating in the same market, not much duopoly profit
- Profit that monopolist could make given by process \boldsymbol{X}
- Both have the option to switch to a new market at sunk cost I
- There, monopolist could earn profit given by process Y

$$L_t = E\left[\int_t^\infty e^{-rs} Y_s \, ds \, \middle| \, \mathscr{F}_t\right] - e^{-rt} I$$

$$F_t = E\left[\int_t^\infty e^{-rs} X_s \, ds \, \bigg| \, \mathscr{F}_t\right]$$

$$M_t = -e^{-rt}I$$

 \boldsymbol{X} and \boldsymbol{Y} geometric Brownian motions

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Application Steg & Thijssen (2015)

Equilibrium:



Attrition: $\frac{dG(t)}{1-G(t)} = e^{-rt} \frac{Y_t - rI}{F_t - L_t} dt$

Preemption: $\alpha(t) = \frac{L_t - F_t}{L_t - M_t} \rightarrow 0$ on boundary

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