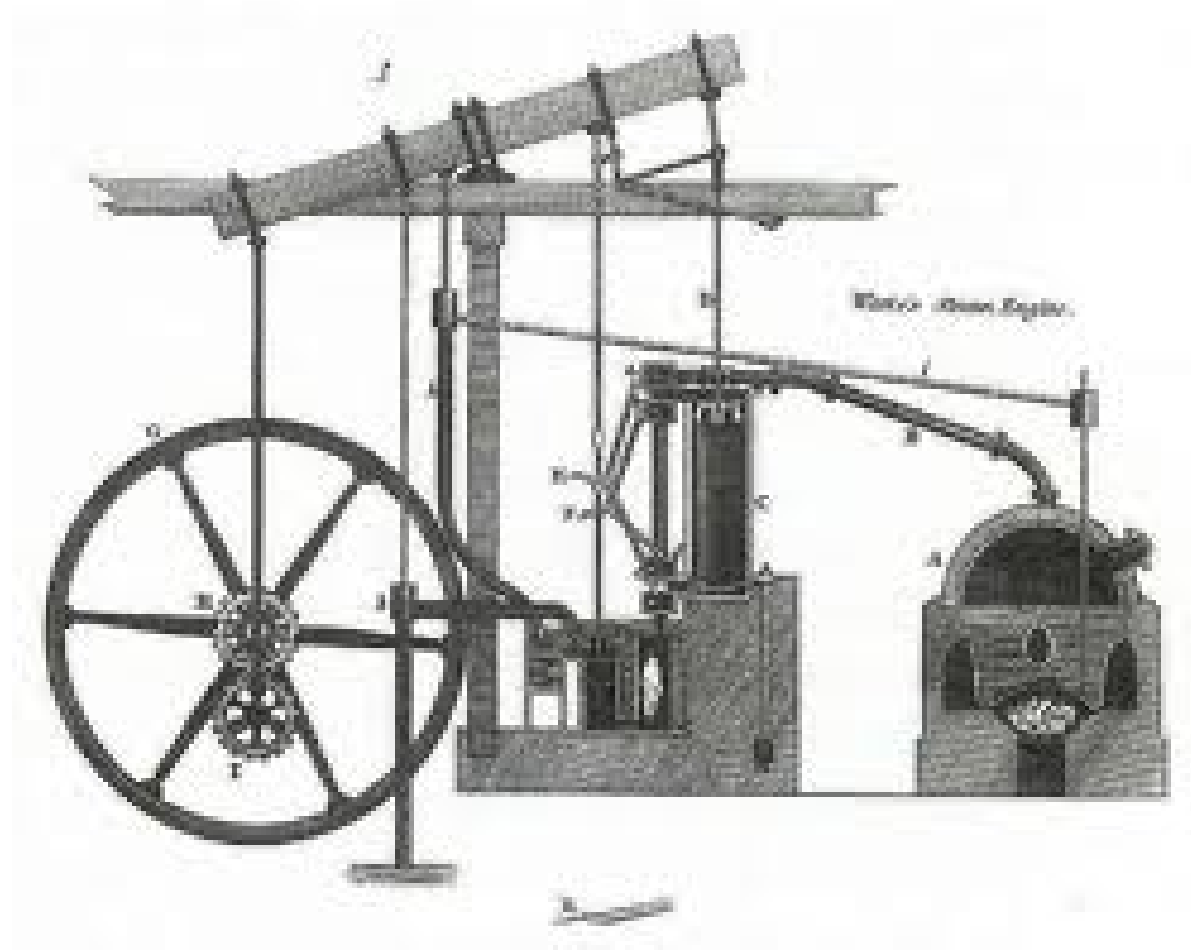


# Continuous transfinite Blum-Shub-Smale computations and a Church-like thesis for poly-time on infinite strings

*P.D. Welch University of Bristol*

*NUS: Sets and Computations 16.iv.15*

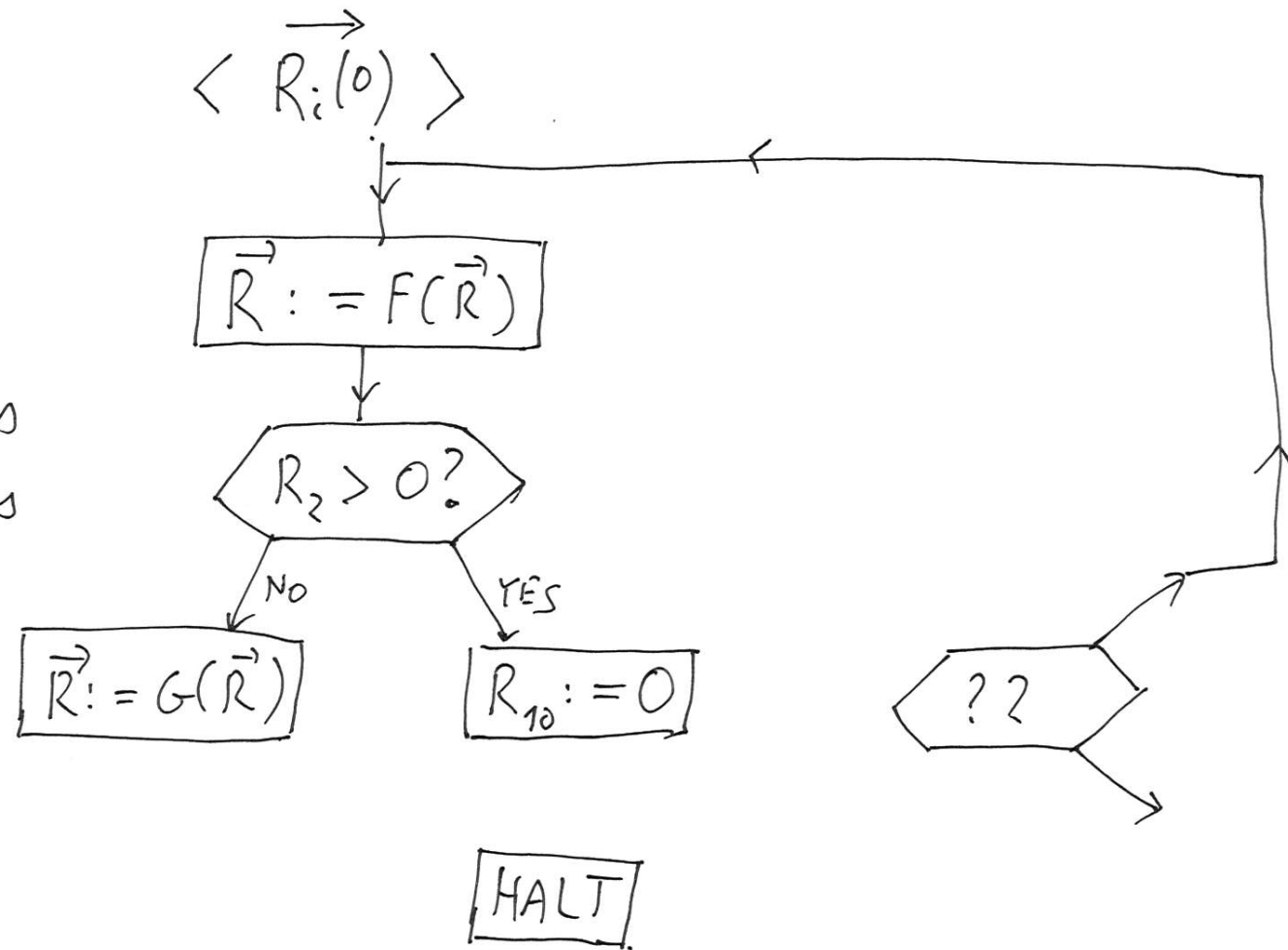


# Introduction: BSS Machines

*Idea:* A conceptual model for handling computations on reals from  $\mathbb{R}$ :

- ▶ *Registers* for reals  $R_1, \dots, R_N$  with contents  $R_1(t), \dots, R_N(t)$  at *time* or *stage*  $t$ .
- ▶ A finite *program*  $P_e$  consisting of instructions  $I_1, \dots, I_K$  - with the current instruction  $I(t)$ .
- ▶ If, and when, the computation halts, at time say  $\theta$ , we say that the machine has *computed*  $R_1(\theta)$ :  $P_e(\overrightarrow{R_i(0)}) \downarrow R_1(\theta)$ .

Assume for simplicity  
only rational functions  
 $F, G$  at function nodes  
(Test for 0 first)



# Transfinite BSS machines: $\lambda$ BSS's<sup>1</sup>

Transfinite Action:

- ▶ **(Continuity)** If, at limit stage  $\lambda$ , any of the  $\lim_{\alpha \rightarrow \lambda} R_i(\alpha)$  do not exist, then  $P_e(\overrightarrow{R_i(0)})$  *crashes*.
- ▶ NB: This includes the case that  $\lim_{\alpha \rightarrow \lambda} R_i(\alpha) = \infty$ .
- ▶ *Limit instruction:*  $I(\lambda) = \liminf_{t \rightarrow \lambda} I(t) =$   
the least instruction  $\#$  performed cofinally in  $\lambda$ .

- **(Continuity)** is a stringent constraint.

---

<sup>1</sup>*Towards a theory of infinite time Blum-Shub-Smale Machines*, P. Koepke and B. Seyfferth, CiE2012 Proceedings, Springer LNCS, 2012.

# Transfinite BSS machines: $\lambda$ BSS's<sup>1</sup>

Transfinite Action:

- ▶ **(Continuity)** If, at limit stage  $\lambda$ , any of the  $\lim_{\alpha \rightarrow \lambda} R_i(\alpha)$  do not exist, then  $P_e(\overrightarrow{R_i(0)})$  *crashes*.
- ▶ NB: This includes the case that  $\lim_{\alpha \rightarrow \lambda} R_i(\alpha) = \infty$ .
- ▶ *Limit instruction:*  $I(\lambda) = \liminf_{t \rightarrow \lambda} I(t) =$   
the least instruction  $\#$  performed cofinally in  $\lambda$ .

- **(Continuity)** is a stringent constraint.

- Koepke-Seyfferth ask:

Q1 How long do the machines compute before looping/crashing?

Q2 What do the machines compute?

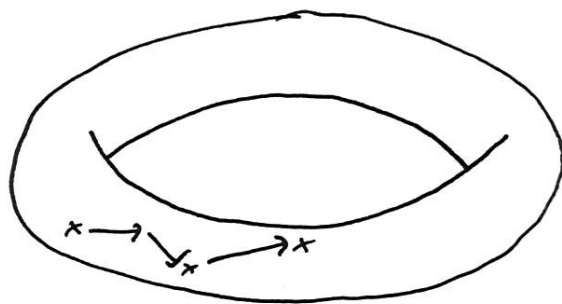
Q3 How do the above depend on  $N$ , the no. of registers?

(They answer Q1& Q3. We have answered Q2.)

---

<sup>1</sup>*Towards a theory of infinite time Blum-Shub-Smale Machines*, P. Koepke and B. Seyfferth, CiE2012 Proceedings, Springer LNCS, 2012.

# A transfinite dynamical system



N-dim. torus  $[0, 1]^N$ , identify  $1 \rightarrow 0$ .

Q4: For program  $P_e$ , what is the origin set  $O_e := \{ \vec{r} : P_e(\vec{r}) \downarrow 0 \}$ ?

Q5: How complex is  $\{ e : O_e \neq \emptyset \}$ ?

## Q1: Looping times

### Theorem (Koepke-Seyfferth)

*Any IBSS machine  $P_e$  crashes, halts, or is looping, by time  $\omega^{M+1}$  where  $M$  is the  $\sharp$  of function nodes in  $P_e$ .*

**Proof:** ( $M = 1$ ) Suppose for a contradiction the point moves after stage  $\omega^2$ . Then the function  $F(\vec{x})$  was applied at some stage  $> \omega^2$  *but was not applied cofinally in  $\omega^2$*  (by **(Continuity)**, since otherwise  $R_i(\vec{\omega}^2)$  is a fixed point). So for some stage  $\alpha < \omega^2$  the computation can be regarded as one starting from  $R_i(\vec{\alpha})$  using a program with one less function node. In this case ( $M=1$ ) the program then use only the finitely many query nodes, and must be looping by stage  $\omega^2$ . Contradiction!

$M = l + 1$ : repeat: argue by induction.



## Q1: Looping times

### Theorem (Koepke-Seyfferth)

*Any IBSS machine  $P_e$  crashes, halts, or is looping, by time  $\omega^{M+1}$  where  $M$  is the  $\sharp$  of function nodes in  $P_e$ .*

**Proof:** ( $M = 1$ ) Suppose for a contradiction the point moves after stage  $\omega^2$ . Then the function  $F(\vec{x})$  was applied at some stage  $> \omega^2$  *but was not applied cofinally in  $\omega^2$*  (by **(Continuity)**, since otherwise  $R_i(\vec{\omega}^2)$  is a fixed point). So for some stage  $\alpha < \omega^2$  the computation can be regarded as one starting from  $R_i(\vec{\alpha})$  using a program with one less function node. In this case ( $M=1$ ) the program then use only the finitely many query nodes, and must be looping by stage  $\omega^2$ . Contradiction!

$M = l + 1$ : repeat: argue by induction. □

*Remark:*

- (1) The number of registers was irrelevant. This answers Q1 and Q3.
- (2) Since time  $\omega^\omega$  is all that's needed, all IBSS computations can be run inside  $L_{\omega^\omega}[\vec{R}_i]$  and by absoluteness are the same computations as in  $V$ . Hence the IBSS computable reals from inputs  $\vec{R}_i$  are all in  $L_{\omega^\omega}[\vec{R}_i]$ . Later we shall see the converse.



# Confluence

## Theorem (W)

*The following classes of functions of the form  $F : (2^{\mathbb{N}})^k \rightarrow 2^{\mathbb{N}}$  are extensionally equivalent:*

- (I) Those functions computed by a continuous IBSSM machine;*
- (II) Those functions that are polynomial time ITTM;*
- (III) Those functions that are SRSF, (PRSF, CRSF).*

Proof:<sup>2</sup> (I)  $\subseteq$  (II): We take  $k = 1$ . By Koepke-Seyfferth for any IBSSM computable  $F$  there is  $N < \omega$  so that  $F(x)$  is computable in less than  $\omega^N$  steps.

- Consider that computation to be performed inside  $L_{\omega^N}[x]$ .
  - ITTM-compute a code for any  $L_{\omega^N}[x]$ , and its theory, uniformly in the input  $x$  by time  $\omega^{N+3}$ . Since we have the theory, we have the digits of the final halting IBSSM-output (or otherwise the fact that it is looping or has crashed), since these are also part of the set theoretical truths of  $L_{\omega^N}[x]$ .
- Thus (I)  $\subseteq$  (II).

---

<sup>2</sup>See, e.g., P. D Welch, *Turing's Legacy*, Ed. R. Downey, LNL, vol 42, CUP, 2012, pp 493-529.

Proof contd.)

### Theorem

*The following classes of functions of the form  $F : (2^{\mathbb{N}})^k \rightarrow 2^{\mathbb{N}}$  are extensionally equivalent:*

- (I) Those functions computed by a continuous IBSSM machine;*
- (II) Those functions that are polynomial time ITTM;*
- (III) Those functions that are SRSF, (PRSF,CRSF).*

(II)  $\subseteq$  (III): If  $F$  is in the class (II), then for some  $N < \omega$ , by absoluteness,  $F(x)$  is ITTM-computable within  $L_{\omega^N}[x]$ . By setting up the definition of the ITTM program  $P$  computing  $F$ , we may define some  $\alpha$  such that the output of that program  $P$  on  $x$  (i.e.  $F(x)$ ) is always the  $\alpha$ 'th element in the natural wellorder of  $L_{\omega^N}[x]$  uniformly in  $x$ . However the set  $L_{\omega^N}[x]$  is SRSF-recursive from  $\{x\}$  (again uniformly in  $x$ ) as is a code for  $\alpha$ . This yields the conclusion that we may find uniformly the output of  $P(x)$  using the code for  $\alpha$ , again as the output of an SRSF-recursive-in- $x$  function. This renders (II)  $\subseteq$  (III).

## Theorem

*The following classes of functions of the form  $F : (2^{\mathbb{N}})^k \rightarrow 2^{\mathbb{N}}$  are extensionally equivalent:*

- (I) Those functions computed by a continuous IBSSM machine;*
- (II) Those functions that are polynomial time ITTM;*
- (III) Those functions that are SRSF, (PRSF, CRSF).*

Proof contd. (III)  $\subseteq$  (I) Let  $F(x/-)$  be in (III), then there is<sup>3</sup>  $M < \omega$  and a  $\Sigma_1$ -formula  $\varphi(v_0, v_1)$  so that

$$F(x/-) = z \text{ iff } L_{\omega^M}[x] \models \varphi[x, z]$$

- We have in turn another  $\Sigma_1$   $\psi(v_0, v_1)$  (in  $\mathcal{L}_{\dot{x}, \dot{\in}}$ ) so that

$$F(x/-)(k) = z(k) = 1 \text{ iff } L_{\omega^M}[x] \models \psi[x, k].$$

- It thus suffices to be able to compute the  $\Sigma_1$ -truth sets for  $L_\alpha[x]$  for all  $\alpha < \omega^\omega$  by IBSSM's. There are a variety of ways one could do this, but it is well known that calculating the  $\alpha$ 'th iterates of the Turing jump relativised to  $x$  for  $\alpha < \omega^\omega$  would suffice.

---

<sup>3</sup>A. Beckmann, S. Buss, S-D. Friedman, “*Safe Recursive Set Functions*”, Thm. 3.5)

## Coding truth sets into IBSSM comps.

- For  $y \in \mathbb{R}$  let  $y$  also denote the element of  $2^{\mathbb{N}}$  coding the set of integers of  $y$ 's expansion as an infinite fraction and *vice versa*. Fix an  $M < \omega$ , to see that we may calculate  $x^{(\beta) '}$  for  $\beta < \omega^M$ .
- Construct a counter to be used in general iterative processes, using registers  $C_{M-1}, \dots, C_0$  whose contents  $C(j) = n_j$  = the multiple of  $\omega^j$  in the Cantor normal form of  $\omega^\beta$ . Thus  $\beta = \omega^{M-1} \cdot n_{M-1} + \dots \omega \cdot n_1 + n_0 < \omega^M$  where we are at the  $\beta$ 'th stage in the process.
- Effect this so that  $C_0 = C_1 = \dots = C_{M-1} = 0$  occurs first at stage  $\omega^M$ .
- Let  $p_0 = 2, p_1 = 3$ , etc., enumerates the primes. Code the characteristic function of  $\{e \in \omega \mid e \in W_e^{x^{(\beta) '}}\}$  as 1/0's in the digits at the  $s$ 'th-places after the decimal point of  $R_1$  where  $s$  is of the form  $p_{M+e} \cdot p_0^{n_0+1} \cdot \dots \cdot p_{M-1}^{n_{M-1}+1}$ .
- For limit stages  $\lambda < \omega^M$ , continuity of the register contents automatically ensures that this real in  $R_1$  also codes the disjoint union of the  $x^{(\beta) '}$  for  $\beta < \lambda$ , and at stage  $\omega^M$  we have the whole sequence of jumps encoded as required. □

## A Church-like thesis

*Thesis: Any effective notion of computation on  $\omega$ -strings  $x_1, \dots, x_n$  that runs in less than  $\omega^\omega$  steps is SRSF-computable from  $(x_1, \dots, x_n)$ .*

- Any claim of justification for this, (as for the original CT-thesis) turns on what one means by ‘effective notion’.
- But the case for this seems watertight:
  - ▶ Any such ‘effective notion’ has to be absolute between  $ZF$ -models, in particular be absolute to  $L$ .
  - ▶ Similarly it surely must be the case that such a notion for computing from  $\vec{x}$ , must be absolute between  $L[\vec{x}]$  and  $L_{\omega^\omega}[\vec{x}]$ . For if this degree of absoluteness failed, then it would mean that the course of computation from  $\vec{x}$  must be appealing to some additional information, some device, some agency, *extra* to  $L_{\omega^\omega}[\vec{x}]$ . How can one argue that any such external input is ‘effective’?
  - ▶ And we have seen above that the theory of  $L_{\omega^M}[\vec{x}]$  is essentially SRSF-computable.

- ▶ It would seem then that any notion of ‘effective algorithm’ for such computation should be coded in some way into  $L_{\omega^\omega}$ , or at the very worst have a description that is coded there.
- ▶ Compare this with arguments of Gandy<sup>4</sup> for standard computation on integers: notions of *effectivity* here must have a finite description, or have finite components which may be coded within the realm of the hereditarily finite sets. Thus a successful, *i.e.* halting, computation is an object in  $HF$  and relies on nothing outside of  $HF$ .
- ▶ Further compare with Kleene recursion, also a recursion on  $2^{\mathbb{N}}$ : a course of computation is coded as living on a well founded finite path tree, and is a hyperarithmetic object. Hence such computations belong precisely to the realm that they compute (since a set is Kleene-computable iff it is  $HYP$  and relies on nothing outside of its realm:  $L_{\omega_1^{ck}}$ ).
- ▶ As above then, any effective notion of poly-time on strings should rely on nothing outside its realm:  $L_{\omega^\omega}$ .

---

<sup>4</sup>R.O. Gandy. *Church’s thesis and principles for mechanisms*. In J. Barwise, H.J. Keisler, and K. Kunen, editors, *The Kleene Symposium, Studies in Logic and the Foundations of Mathematics*, pages 123-148, Amsterdam, 1980. North-Holland.

## Liminf for IBSSM's

- Relax (**Continuity**). Instead use

(**Liminf**): For  $Lim(\lambda)$  define  $R_i(\lambda) = \liminf_{t \rightarrow \lambda} R_i(t)$ .

Interpret  $P_e$  below in this sense.

## Liminf for IBSSM's

- Relax (**Continuity**). Instead use

(**Liminf**): For  $Lim(\lambda)$  define  $R_i(\lambda) = \liminf_{t \rightarrow \lambda} R_i(t)$ .

Interpret  $P_e$  below in this sense.

### Proposition

$KP + \Pi_3\text{-Reflection} \vdash \text{“}\forall x \forall e (P_e(x) \text{ stabilizes } \text{”}.$

## Liminf for IBSSM's

- Relax (**Continuity**). Instead use

(**Liminf**): For  $Lim(\lambda)$  define  $R_i(\lambda) = \liminf_{t \rightarrow \lambda} R_i(t)$ .

Interpret  $P_e$  below in this sense.

### Proposition

$KP + \Pi_3\text{-Reflection} \vdash \text{“}\forall x \forall e (P_e(x) \text{ stabilizes })\text{”}.$

Q6 (Open)  $\Delta_2^1\text{-CA}_0 \vdash \text{“}\forall x \forall e (P_e(x) \text{ stabilizes })\text{”} ?$