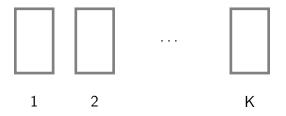
Quantitative Verification of Parameterized Systems

Rayna Dimitrova

MPI-SWS

Joint work with Luis María Ferrer Fioriti, Holger Hermanns and Rupak Majumdar

The Choice Coordination problem



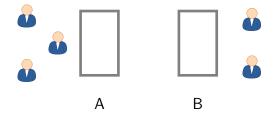
- \blacktriangleright N processes have to agree on exactly one of K alternatives.
- The processes communicate via K shared variables over Σ .
- Size of the alphabet Σ for deterministic protocols?

• in general:
$$|\Sigma| = N + 2$$
 is sufficient [Fischer,Rabin]

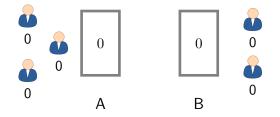
• for
$$k = 2$$
: $|\Sigma| = \frac{N}{2} + 2$ is sufficient

• lower bound: $|\Sigma| > \frac{1}{2} \sqrt[3]{N}$

[Rabin'82]

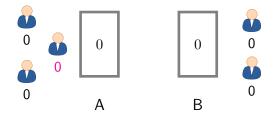


- Fixed synchronization alphabet $\Sigma = \{0, \dots, M\}$ with M even
- ▶ Pair-up the elements of Σ : 0, (1, 2), (3, 4), ..., (M 1, M)
- For a pair (a, b), define $\widehat{a} = b$ and $\widehat{b} = a$.



Initially, all values are 0.

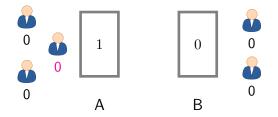
At each step, pick a person outside A or B and perform an action.



If v@A and v = a, and a < M - 1 then set

$$a = \begin{cases} a+2 & \text{with probability } \frac{1}{2}, \\ \widehat{(a+2)} & \text{with probability } \frac{1}{2}. \end{cases}$$

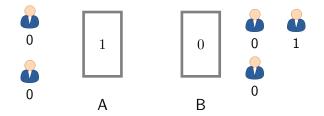
Set v to a and move to B.



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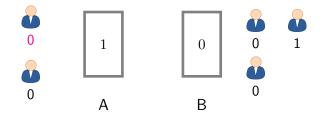
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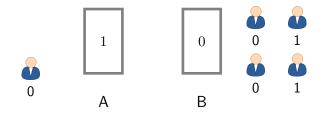
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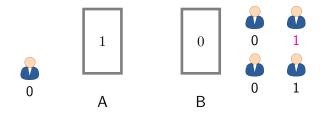
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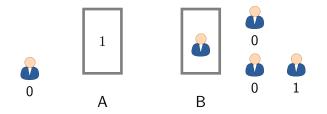
If v@A and v < a, then set v to a and move to B.



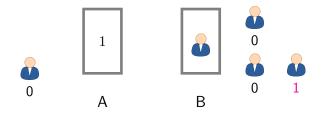
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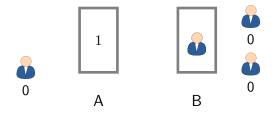
If v@B then v > b, then enter location B.



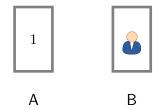
If v@B then v > b, then enter location B.



If v@B and B was chosen, then enter location B.



If v@B and B was chosen, then enter location B.



The protocol terminates with probability $1 - \frac{1}{2^{\frac{M}{2}}}$, where $\Sigma = \{0, \dots, M\}$ is the synchronization alphabet.

Quantitative verification of parameterized systems

Model: probabilistic choice + nondeterminism

State-space: infinite (or weakly finite)

model-checking cannot be applied directly

Property: quantitative

cannot use methods for almost-sure termination

[Esparza, Gaiser, Kiefer @ CAV'12] [Chakarov, Sankaranarayanan @ CAV'13] [Ferrer Fioriti, Hermanns @ POPL'15] [Lin,Rümmer @ CAV'16] A deductive proof system for PCTL^*

quantitative temporal properties yes

nondeterminism yes infinite state space yes

[D., Ferrer Fioriti, Hermanns, Majumdar @ TACAS'16]

A deductive proof system for PCTL^*

Deductive proof systems for **non-probabilistic** systems for CTL* [Kesten,Pnueli] and for ATL* [Slanina,Sipma,Manna] Lyapunov ranking functions for **almost-sure termination** [Bournez, Garnier]

Proof rules for **quantitative temporal** properties

Variables

- ▶ $N \in \mathbb{N}$: number of processes
- ▶ $a, b \in \mathbb{N}$: shared variables at location A (resp. B)
- ▶ $n_{v@A}, n_{v@B} \in \mathbb{N}$: number of processes holding value $v \in \{0, ..., M\}$ outside location A (B)

$$out_A = \sum_{v=0}^M n_{v@A}, \quad out_B = \sum_{v=0}^M n_{v@B}$$

▶ $in_A, in_B \in \mathbb{N}$: number of processes inside location A (resp. B)

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- choose a guarded command of the program to be executed
 Probabilistic transitions
 - ▶ set a to (a+2) or to $\widehat{(a+2)}$ with probability $\frac{1}{2}$ each

probabilistic temporal properties

Starting at any initial state, under every possible scheduler, Rabin's protocol eventually terminates with probability at least $1 - \frac{1}{2^{\frac{M}{2}}}$.

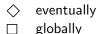
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expressed in Probabilistic Computational Tree Logic (PCTL*)

 $\diamondsuit(out_A = 0 \land out_B = 0)$

LTL operators



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$$\mathbb{P}_{\geq 1-\frac{1}{2^{\frac{M}{2}}}}^{\forall} \left(\diamondsuit(out_A = 0 \land out_B = 0) \right)$$

LTL operators

probabilistic quantifiers

◇ eventually□ globally

 $\mathbb{P}_{\bowtie p}^{\exists}$ \mathbf{e} $\mathbb{P}_{\bowtie p}^{\forall}$ \mathbf{f}

exists a scheduler for all schedulers

probabilistic temporal properties

Starting at any initial state, under every possible scheduler, Rabin's protocol eventually terminates with probability at least $1 - \frac{1}{2^{\frac{M}{2}}}$.

expressed in Probabilistic Computational Tree Logic (PCTL*)

$$\varphi_{init} \to \mathbb{P}_{\geq 1-\frac{1}{2^{\frac{M}{2}}}}^{\forall} \left(\diamondsuit(out_A = 0 \land out_B = 0) \right)$$

LTL operators

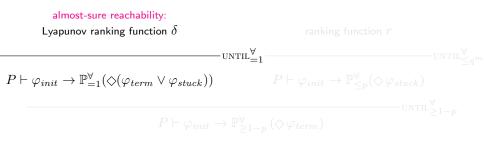
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Outline

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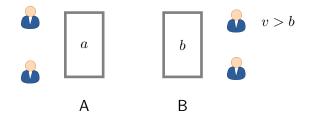


Prove $P \vdash \mathbb{P}_{=1}^{\forall} (\diamondsuit \varphi_{term})$, where $\varphi_{term} \equiv out_A = 0 \land out_B = 0$?

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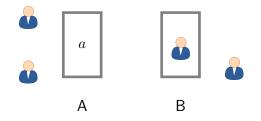
Lyapunov ranking function maps states to $(\mathbb{R}_{\geq 0}, \succ)$, where \succ is well-founded, and $\delta(s) \succ \mathbb{E}(\delta' \mid s)$ when s not in the target set.



Decreases $\delta_1(s) = out_A + out_B$.

Prove $P \vdash \mathbb{P}_{=1}^{\forall} (\diamondsuit \varphi_{term})$, where $\varphi_{term} \equiv out_A = 0 \land out_B = 0$?

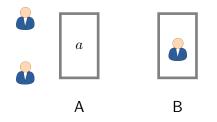
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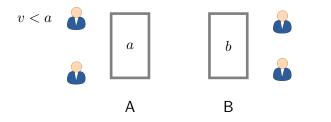
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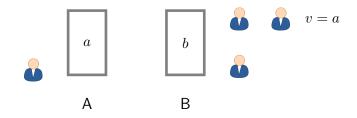
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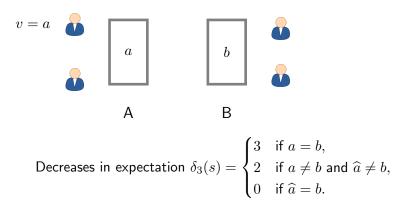
Decreases
$$\delta_2(s) = \sum_{v < a} (n_{v@A} + n_{v@B}) + \sum_{v < b} (n_{v@A} + n_{v@B}).$$

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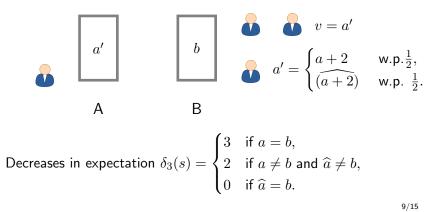


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Rule for almost-sure reachability

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Lyapunov ranking function maps states to $(\mathbb{R}_{\geq 0}, \succ)$, where \succ is well-founded, and $\delta(s) \succ \mathbb{E}(\delta' \mid s)$ when s not in the target set.

Take $\delta(s) = \delta_1(s) + \delta_2(s) + (2N+1) \cdot \delta_3(s)$.

Rule for almost-sure reachability

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We need idle transitions when a = b = M - 1 or a = b = M.

No variable changes, so no Lyapunov ranking function.

Rule for almost-sure reachability

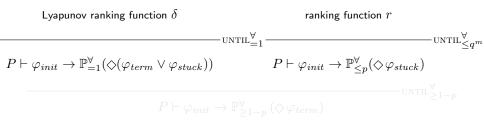
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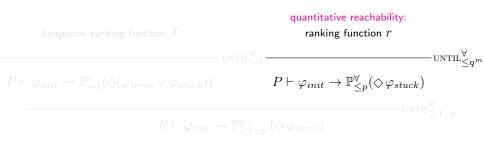
Prove the weaker property

$$\begin{split} P \vdash \mathbb{P}_{=1}^{\forall} (\diamondsuit(\varphi_{term} \lor \varphi_{stuck})), \\ \text{where } \varphi_{stuck} \equiv (a = M - 1 \land b = M - 1 \lor a = M \land b = M). \end{split}$$

Outline



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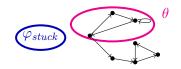


Prove
$$P \vdash \varphi_{init} \to \mathbb{P}_{\leq q^m}^{\forall}(\diamondsuit \varphi_{stuck})$$
 for $q = \frac{1}{2}$, and $m = \frac{M}{2}$.

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auxiliary assertion $\boldsymbol{\theta}$

 $\blacktriangleright P \vdash \theta \to \mathbb{P}_{=1}^{\forall} (\Box \neg \varphi_{stuck})$

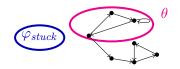


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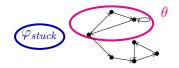
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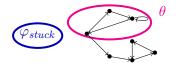
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- for $s \in \varphi_{init}$, $r(s) \ge m$
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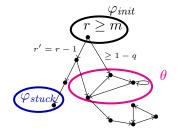
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► for states
$$s \notin \theta$$
, $r(s') \ge r(s)$ or
 $r(s') = r(s) - 1$ with prob. $\le q$
 $s' \in \theta$ with probability $\ge 1 - q$



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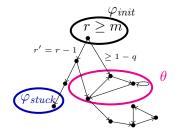
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 $\boldsymbol{r}(\boldsymbol{s})=\boldsymbol{0}$ reached with probability $\leq q^m$



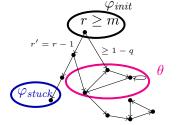
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 $\boldsymbol{r}(\boldsymbol{s})=\boldsymbol{0}$ reached with probability $\leq q^m$

$$\text{Take } \theta \equiv \widehat{a} = b \text{ and } r(s) = \begin{cases} \frac{M}{2} - \min(\lceil \frac{a}{2} \rceil, \lceil \frac{b}{2} \rceil) & \text{if } \widehat{a} \neq b, \\ \frac{M}{2} - \min(\lceil \frac{a}{2} \rceil, \lceil \frac{b}{2} \rceil) + 1 & \text{if } \widehat{a} = b. \end{cases}$$

Outline

Deductive Proof System for PCTL*

Proof rule for nested state formulas

BASIC-STATE

Proof rules for probabilistic LTL properties BASIC-PATH, $\text{REC}_{=1}^{\delta}$, $\text{REC}_{>0}^{\delta}$, $\text{REC}_{>p}^{\delta}$

Proof rules for invariance $INV_{=1}^{\circ}$, $INV_{>0}^{\circ}$, $INV_{\bowtie p}^{\circ}$

 $\begin{array}{l} \begin{array}{l} \text{Proof rules for reachability} \\ \text{UNTIL}_{=1}^{\mathfrak{d}} \text{,} \text{UNTIL}_{>0}^{\mathfrak{d}} \text{,} \text{UNTIL}_{\geq p}^{\mathfrak{d}} \\ \text{UNTIL}_{\geq p^m}^{\mathfrak{d}} \text{,} \text{UNTIL}_{\leq p^m}^{\mathfrak{d}} \text{,} \text{UNTIL}_{\geq 1-p}^{\forall} \end{array}$

Additional proof rules

 $\begin{array}{c} \operatorname{NEXT}_{=1}^{\circlearrowright}, \ \operatorname{NEXT}_{>0}^{\circlearrowright}, \ \operatorname{NEXT}_{\bowtie p}^{\circlearrowright}, \ \operatorname{GEN}, \ \operatorname{MP}, \ \operatorname{AND}, \ \operatorname{OR} \\ \operatorname{UNTIL}_{\geq p_{1} \cdot p_{2}}^{\circlearrowright}, \ \overline{\operatorname{NEV}}_{\geq p}^{\lor}, \ \overline{\operatorname{REC}}_{=1}^{\circlearrowright} \end{array}$

Deductive Proof System for PCTL*

Proof rule for nested state formulas BASIC-STATE

Proof rules for probabilistic LTL properties BASIC-PATH, $\text{REC}_{=1}^{\circ}$, $\text{REC}_{>0}^{\circ}$, $\text{REC}_{\geq p}^{\circ}$

Proof rules for invariance $INV_{=1}^{\circ}$, $INV_{>0}^{\circ}$, $INV_{\bowtie p}^{\circ}$

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Summary

Deductive proof system

- for discrete infinite-state probabilistic systems,
- applicable to quantitative temporal properties,
- sound, and for finite-state systems also complete,
- useful for verification of parameterized systems.

Thank you for your attention!

http://www.mpi-sws.org/~rayna/