# Weak Choice Principles in the Weihrauch Degrees 

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## Dagstuhl Problems (Sep. 2015)

(1) (Pauly 2012) $(\exists k \in \omega)$ AoUC $\star$ AoUC $\leq w$ AoUC $^{k}$ ? Here, AoUC is the all-or-unique choice principle.
(2) (Le Roux-Pauly 2015) $(\exists k \in \omega) X C \star X C \leq w X^{k}$ ? Here, $\mathbf{X C}$ is the convex choice principle.

It is easy to see that LLPO $<_{w}$ AoUC $<w$ XC $<w$ WKL (any recursion theorist can separate them).

## Main Theorem (K. and Pauly)

(1) Problem 1 is false: LLPO $\star$ AoUC $\not \Varangle_{w}$ AoUC ${ }^{\boldsymbol{k}}$ for all $\boldsymbol{k}$.
(2) Problem 2 is false: XC $\star$ AoUC $\not \mathbf{z}_{w} \mathrm{XC}_{\boldsymbol{k}}$ for all $\boldsymbol{k}$. Here, $\mathbf{X C}_{\boldsymbol{k}}$ is the $\boldsymbol{k}$-dimensional convex choice principle.
(3) However, it is true that

$$
\text { AoUC } \star \operatorname{AoUC} \star \operatorname{AoUC} \leq w \text { AoUC }{ }^{4} \star \text { AoUC }^{3} .
$$

A $\Pi_{2}$-principle is non-uniformly computable if any $\boldsymbol{x}$-computable instance has an $\boldsymbol{x}$-computable solution.

Equivalently, it has a $\boldsymbol{\sigma}$-computable realizer, where $\boldsymbol{f}$ is $\boldsymbol{\sigma}$-computable if it is decomposable into countably many computable functions. (this is an effective version of $\sigma$-continuity in the sense of Nikolai Luzin).

## Non-uniformly Computable Principles (below WKL)

(1) LLPO: de Morgan's law for $\boldsymbol{\Sigma}_{1}^{0}$-formulas.
(2) $\mathrm{C}_{n}$ : Given nonempty closed $F \subseteq\{1, \ldots, n\}$, choose $i \in F$.
(3) $\mathrm{C}_{[0,1], \# \leq n}$ : Given nonempty closed $F \subseteq[0,1]$, if $\boldsymbol{F}$ has at most $\boldsymbol{n}$ many elements, choose $\boldsymbol{x} \in \boldsymbol{F}$.
(4) AoUC: Given nonempty closed $F \subseteq[0,1]$, if $F=[0,1]$ or $F$ is singleton, choose $x \in F$.
(5) XC: Given nonempty convex closed $F \subseteq[0,1]$, choose $x \in F$.

Clear: LLPO $\equiv{ }_{w} \mathrm{C}_{2}<{ }_{w} \mathrm{C}_{[0,1], \# \leq 2}<{ }_{w} \mathrm{AoUC}<{ }_{w} \mathrm{XC}<{ }_{w} \mathrm{WKL}$.

## Definition (Weihrauch Reducibility)

$\boldsymbol{f} \leq w \boldsymbol{g}$ iff there are computable $\boldsymbol{H}, \boldsymbol{K}$ such that for any realizer $\boldsymbol{G}$ of $\boldsymbol{g}, \boldsymbol{K}(\mathbf{i d}, \mathbf{G H})$ realizes $\boldsymbol{f}$.
(Brattka-Gherardi-Marcone) Classify $\boldsymbol{\Pi}_{\mathbf{2}}$-theorems in the Weihrauch lattice.

There are some challenges to connect the Weihrauch lattice with intuitionistic linear logic:

- Yoshimura (submitted in 2013; still unpublished?): Some partial result using fibration in categorical logic.
- Kuyper: Some relationship with $E L_{0}$ plus Markov's principle ( $\Sigma_{1}^{0}$-DNE) via realizability.
$E L_{0}=$ Heyting Arithmetic HA restricted to quantifier-free induction QF-IND
with the axiom $\lambda$-convesion, the axiom of recursor, and the quantifier-free axiom of choice QF-AC ${ }_{00}$

Note that $\mathbf{R C A}_{\mathbf{0}}=\mathrm{EL}_{0}+$ "the law of excluded middle".

## Constructive Reverse Mathematics

(1) $E L_{0}$ proves the equivalence of the following:

- BE: every real number has a binary expansion. (a real number is represented by a rapid Cauchy sequence)
- $\mathrm{C}_{[0,1], \# \leq 2}$ : for any infinite binary tree $\boldsymbol{T}$, if every level of $\boldsymbol{T}$ has at most 2 nodes, then $\boldsymbol{T}$ has an infinite path.
(2) $E L_{0}$ proves the equivalence of the following:
- IVT: the intermediate value theorem.
- XC: every infinite binary convex tree has an infinite path.
(3) (Pauly 2010; Brattka-Gherardi-Hölzl 2015) NASH $\equiv_{w}$ AoUC*: Does $\mathrm{EL}_{0}(+\mathrm{MP})$ prove the equivalence of the following?
- NASH: every bi-matrix game has a Nash equilibrium.
- AoUC: every infinite binary all-or-unique tree has an infinite path.
(1) and (2) are confirmed by Berger-Ishihara-K.-Nemoto (we need some nontrivial work on eliminating Markov's principle).
There are a huge number of works in constructive reverse math...


## Definition

For $\boldsymbol{f}: \subseteq X \rightrightarrows \boldsymbol{Y}$ and $\boldsymbol{g}: \subseteq \mathbf{Z} \rightrightarrows W$,
(1) $f \times g(x, z)=f(x) \times g(z)$.
(2) $f \circ g(x)=\bigcup\{f(y): y \in g(x)\}$.
(3) $f \star g=\max _{\leq_{w}}\left\{f_{0} \circ g_{0}: f_{0} \leq_{w} f\right.$ and $\left.g_{0} \leq w g\right\}$.

For $\boldsymbol{X}=\mathbb{N}, \mathbf{2}^{\mathbb{N}}, \mathbb{N}^{\mathbb{N}}, \mathbb{R}$, etc., we have:
(1) $\mathrm{C}_{X} \star \mathrm{C}_{X} \equiv{ }_{w} \mathrm{C}_{X} \times \mathrm{C}_{X} \equiv{ }_{w} \mathrm{C}_{X}$.
(2) $\mathrm{PC}_{X} \star \mathrm{PC}_{x} \equiv_{w} \mathrm{PC}_{x} \times \mathrm{PC}_{x} \equiv{ }_{w} \mathrm{PC}_{x}$.
(3) $\mathrm{C}_{x, \# \leq n} \star \mathrm{C}_{X, \# \leq n} \equiv{ }_{w} \mathrm{C}_{x, \# \leq n} \times \mathrm{C}_{X, \# \leq n}$.
(Brattka-Le Roux-Pauly) XC $<w \mathbf{X C} \times \mathbf{X C}$.
Dagstuhl Problems (Sep. 2015)
(1) (Pauly 2012) $(\exists \boldsymbol{k} \in \omega)$ AoUC $\star$ AoUC $\leq w$ AoUC ${ }^{k}$ ?
(2) (Le Roux-Pauly 2015) $(\exists k \in \omega) \mathrm{XC} \star \mathrm{XC} \leq w \mathrm{XC}^{k}$ ?

## Main Theorem (K. and Pauly)

(1) Problem 1 is false: LLPO $\star$ AoUC $\not \mathrm{K}_{w}$ AoUC $^{\boldsymbol{k}}$ for all $\boldsymbol{k}$.
(2) Problem 2 is false: $\mathbf{X C} \star$ AoUC $\not{ }_{w} \mathbf{X C}_{\boldsymbol{k}}$ for all $\boldsymbol{k}$. Here, $\mathbf{X C}_{\boldsymbol{k}}$ is the $\boldsymbol{k}$-dimensional convex choice principle.
(0) However, it is true that

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\text { AoUC } \star \text { AoUC } \star \text { AoUC } \leq w \text { AoUC }^{4} \star \text { AoUC }^{3} .
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In particular, we have

$$
\text { NASH }<_{w} \text { NASH } \star \text { NASH } \equiv_{w} \text { NASH } \star \text { NASH } \star \text { NASH. }
$$

$\left(P_{e}, \varphi_{e}, \psi_{e}\right)$ : the $\boldsymbol{e}$-th triple constructed by the opponent $\mathbf{O p p}$

- The e-th co-c.e. closed subset of $P_{e} \subseteq[0,1]^{k}$.
- The e-th partial computable $\varphi_{e}: \subseteq \mathbb{N}^{\mathbb{N}} \rightarrow 2^{\mathbb{N}}$.
- The $e$-th partial computable $\psi_{e}: \subseteq \mathbb{N}^{\mathbb{N}} \rightarrow[0,1]$.

The $W$-reduction proceeds as follows:

- We first give an all-or-unique tree $\boldsymbol{T}_{r} \subseteq \mathbf{2}^{<\omega}$ and a map $\boldsymbol{J}_{r}: \mathbf{2}^{\omega} \rightarrow$ \{nonempty intervals\}.
- Opp reacts with a convex $\boldsymbol{P}_{r} \subseteq[0,1]^{k}$, and ensure that
- if $\boldsymbol{z}$ is a name of a point in $\boldsymbol{P}_{r}$,
- then $\varphi_{r}(\boldsymbol{z})=\boldsymbol{x}$ is a path through $\boldsymbol{T}_{r}$,
- and $\psi_{r}(\boldsymbol{z})$ chooses an element of the interval $\boldsymbol{J}_{r}(\boldsymbol{x})$, where Opp can use information on (names of) $\boldsymbol{T}_{r}$ and $\boldsymbol{J}_{r}$ to construct $\varphi_{r}$ and $\psi_{r}$.
- Our purpose is to prevent Opp's strategy.

By the recursion theorem, I know who I am.

- The $\boldsymbol{e}$-th strategy constructs an a.o.u. tree $\boldsymbol{T}_{\boldsymbol{e}}$ and an interval-valued map $J_{e}$.
- The $\boldsymbol{q}$-th substrategy $\boldsymbol{S}_{\boldsymbol{q}}$ :
- $\mathcal{S}_{q}$ acts under the assumption that the substrategies $\left(\mathcal{S}_{p}\right)_{p<q}$ will eventually force the Opp's convex set $\boldsymbol{P}_{\boldsymbol{e}}$ to be at most $(\mathbf{k}-\mathbf{q})$-dimensional.
- The $\boldsymbol{t}$-th action of $\boldsymbol{S}_{q}$ forces the measure $\lambda^{k-q}\left(\tilde{\boldsymbol{P}}_{e}\right)$ of a nonempty open subset $\tilde{\boldsymbol{P}}_{\boldsymbol{e}}$ of $\boldsymbol{P}_{\boldsymbol{e}}$ to be less than or equal to $\mathbf{2}^{q-t} \cdot \varepsilon_{t}$, where $\varepsilon_{t}=\sum_{j=0}^{t+1} \mathbf{2}^{-j}<2$.
- If $\mathcal{S}_{q}$ acts infinitely often, then it forces $\boldsymbol{P}_{\boldsymbol{e}}$ to be at most ( $\boldsymbol{k} \mathbf{- q} \mathbf{- 1}$ )-dimensional (under the assumption that $\boldsymbol{P}_{\boldsymbol{e}}$ is convex).

How can we approximate the value of $\lambda^{k-q}$ by an effective way?
Obvious obstacles:

- Even if we know that a co-c.e. closed $\boldsymbol{X} \subseteq[0,1]^{k}$ is at most $\boldsymbol{d}$-dimensional for some $\boldsymbol{d}<\boldsymbol{k}$, it is still possible that $\boldsymbol{X}[\boldsymbol{s}]$ can always be at least $\boldsymbol{k}$-dimensional for all $\boldsymbol{s} \in \omega$.
Fortunately, however, if a convex closed set $\boldsymbol{X} \subseteq[0,1]^{k}$ is at most $\boldsymbol{d}$-dimensional for some $\boldsymbol{d}<\boldsymbol{k}$ :
- By convexity, $\boldsymbol{X}$ is a subset of $\boldsymbol{d}$-dim. hyperplane $\boldsymbol{L}$.
- By compactness, $\boldsymbol{X}[\boldsymbol{s}]$ for sufficiently large $\boldsymbol{s}$ is eventually covered by a thin $\boldsymbol{k}$-parallelotope $\widehat{\boldsymbol{L}}$ obtained by expanding $\boldsymbol{d}$-hyperplane $\boldsymbol{L}$.
- For instance, if $X \subseteq[0,1]^{3}$ is included in the plane $L=\{1 / 2\} \times[0,1]^{2}$, then for all $\boldsymbol{t} \in \omega$, there is $\boldsymbol{s} \in \omega$ such that $X[s] \subseteq \widehat{L}\left(2^{-t}\right):=\left[1 / 2-2^{-t}, 1 / 2+2^{-t}\right] \times[0,1]^{2}$ by compactness.
- We call such $\widehat{L}\left(2^{-t}\right)$ as the $2^{-t}$-thin expansion of $\boldsymbol{L}$.

The $\boldsymbol{d}$-dim. measure $\lambda^{d}$ is defined on Borel subsets of $\boldsymbol{d}$-hyperplanes in $[0,1]^{k}$ whose values are consistent with the $\boldsymbol{d}$-dim. volume (defined by the wedge product) on $d$-parallelotopes in $[0,1]^{k}$.

- Assume: We know that a convex set $\boldsymbol{X} \subseteq[\mathbf{0 , 1}]^{k}$ is at most $\boldsymbol{d}$-dim., and moreover, a co-c.e. closed $\tilde{\boldsymbol{X}} \subseteq \boldsymbol{X}$ satisfies that $\lambda^{d}(\tilde{\boldsymbol{X}})<\boldsymbol{r}$.
- Given $\varepsilon>0$, there must be a rational closed subset $\boldsymbol{Y}$ of a $\boldsymbol{d}$-hyperplane $L$ such that $\tilde{\boldsymbol{X}}$ is covered by the $\varepsilon$-thin expansion $\widehat{\boldsymbol{Y}}(\varepsilon)$ of $\boldsymbol{Y}$, and moreover, $\boldsymbol{Y}$ is very close to $\tilde{\boldsymbol{X}}$.
- If $\boldsymbol{Y}$ is a rational closed subset of a $\boldsymbol{d}$-hyperplane, one can calculate $\lambda^{d}(\boldsymbol{Y})$.
- Indeed, we can compute the maximum value $m^{d}(Y, \varepsilon)$ of $\lambda^{d}\left(\widehat{Y}(\varepsilon) \cap L^{\prime}\right)$ where $L^{\prime}$ ranges over all $\boldsymbol{d}$-hyperplanes.
- For instance, if $\boldsymbol{Y}=[\mathbf{0}, \boldsymbol{s}] \times\{\boldsymbol{y}\}$, it is easy to see that

$$
m^{1}(Y, \varepsilon)=\sqrt{s^{2}+(2 \varepsilon)^{2}}
$$

- If $\lambda^{d}(\tilde{\boldsymbol{X}})<\boldsymbol{r}$, given $\boldsymbol{n}$, one can effectively find $\boldsymbol{s}, \boldsymbol{Y}, \varepsilon$ such that

$$
\tilde{X}[s] \subseteq \widehat{Y}(\varepsilon) \text { and } m^{d}(Y, \varepsilon)<r+2^{-n} .
$$

- In this way, if the inequality $\lambda^{d}(\tilde{\boldsymbol{X}})<\boldsymbol{r}$ holds for a co-c.e. closed subset $\tilde{\boldsymbol{X}}$ of a $\boldsymbol{d}$-dimensional convex set $\boldsymbol{X}$, then one can effectively confirm this fact.


## $X C \star A_{0} U C \not{ }_{w} X C_{k}$ for all $k$.

Opp: (convex) closed $P_{e} \subseteq[0,1]^{k}$, which helps $\varphi_{e}$ to find a path $p$ of $T_{e}$, and $\psi_{e}$ to find an element of $\boldsymbol{J}_{e}(\boldsymbol{p})$.
The action of the $\boldsymbol{q}$-th substrategy $\mathcal{S}_{\boldsymbol{q}}$ :
(1) Ask whether $\varphi_{e}(\mathbf{z})$ already computes a node of length at least $\boldsymbol{p}+\mathbf{1}$ for any name $\boldsymbol{z}$ of an element of $\boldsymbol{P}_{\mathbf{e}}$.

- Yes $\Rightarrow$ Go next // No $\Rightarrow$ Wait.
(2) Ask whether there is some $\tau \in 2^{q+1}$ such that any point in $\boldsymbol{P}_{\boldsymbol{e}}$ has a name $\boldsymbol{z}$ such that $\varphi_{e}(\boldsymbol{z})$ does not extend $\tau$.
- No $\Rightarrow$ Go next.
- Yes $\Rightarrow$ Let $\boldsymbol{T}_{\boldsymbol{e}}$ be a tree with a unique path $\boldsymbol{\tau}^{\boldsymbol{\sim}} \mathbf{0}^{\boldsymbol{\omega}}$; then we win.
(3) Now $\mathcal{S}_{q}$ believes that $\left(\mathcal{S}_{p}\right)_{p<q}$ eventually forces $\boldsymbol{P}_{e}$ to be at most ( $\boldsymbol{k} \boldsymbol{- q}$ )-dimensional. Under this assumption, $\boldsymbol{S}_{\boldsymbol{q}}$ believes that $\mathcal{S}_{\boldsymbol{q}}$ has forced $\lambda^{k-q}\left(\tilde{P}_{e}\right)<2^{q-t+1} \cdot \varepsilon_{t-1}\left(\tilde{P}_{e}\right.$ is an open subset of $\left.\boldsymbol{P}_{e}\right)$ by $\boldsymbol{S}_{q}$ 's ( $t-1$ )-st action.
(4) Ask whether for any name $\boldsymbol{z}$ of a point of $\boldsymbol{P}_{\boldsymbol{e}}$, whenever $\boldsymbol{\varphi}_{\boldsymbol{e}}(\boldsymbol{z})$ extends $\mathbf{0}^{q} \mathbf{1}$, the value of $\psi_{e}(\boldsymbol{z})$ is already approximated with precision $3^{-t-2}$.
- Yes $\Rightarrow$ Go next // No $\Rightarrow$ Wait.


## $X C \star A_{0} U C \not{ }_{w} X C_{k}$ for all $k$.

The action of the $\boldsymbol{q}$-th substrategy $\boldsymbol{S}_{\boldsymbol{q}}$ (Continued):

- We have a nonempty interval $J_{e}\left(0^{q} 1\right)$ at the current stage.
- $I_{0}, I_{1}$ : sufficiently separated subintervals of $J_{e}\left(0^{q} 1\right)$.
- $V$ : names of points in $P_{e}$ whose $\varphi_{e}$-values extend $0^{q} 1$.
- $\mathcal{S}_{q}$ believes that $\mathcal{S}_{q}$ has already forced $\lambda^{k-q}(\delta[V]) \leq 2^{q-t+1} \cdot \varepsilon_{t-1}$, where $\boldsymbol{\delta}$ is an open representation of $[0,1]^{k}$.
- $Q_{i}$ : the set of all points in $\overline{\delta[V]}$ all of whose names are still possible to have $\psi_{e}$-values in $\boldsymbol{I}_{\boldsymbol{i}}$ with precision $\mathbf{3}^{-\boldsymbol{t - 2}}$. One can show:
- $Q_{i}$ is effectively compact.
- $\lambda^{k-q}\left(Q_{0} \cap Q_{1}\right)=0$ whenever $\boldsymbol{P}_{\boldsymbol{e}}$ is at most $(\boldsymbol{k}-\boldsymbol{q})$-dim.
- Therefore, $\lambda^{k-q}\left(Q_{i}\right) \leq 2^{q-t} \cdot \varepsilon_{t-1}$ for some $i<2$.
- Finally, ask whether there is a witness for the above. That is, ask whether one can find $\boldsymbol{s}, \boldsymbol{Y}, \boldsymbol{\varepsilon}, \boldsymbol{i}$ such that

$$
Q_{i}[s] \subseteq \widehat{Y}(\varepsilon) \text { and } m^{k-q}(Y, \varepsilon)<2^{q-t} \cdot \varepsilon_{t}
$$

- No $\Rightarrow$ Wait.
- Yes $\Rightarrow$ Put $\boldsymbol{J}_{\boldsymbol{e}}\left(\mathbf{0}^{q} \mathbf{1}\right)=\boldsymbol{I}_{\boldsymbol{i}}$ and go to the next action $\boldsymbol{t}+\mathbf{1}$.
- The previous action of $\mathcal{S}_{q}$ forces that $\delta[V] \subseteq Q_{i}$; therefore, $\lambda^{k-q}(\delta[V]) \leq \lambda^{k-q}\left(Q_{i}\right) \leq 2^{q-t} \cdot \varepsilon_{t}$.
- If $\mathcal{S}_{q}$ acts infinitely often, then this forces $\lambda^{\boldsymbol{k}-\boldsymbol{q}}(\delta[V])=\mathbf{0}$; therefore convexity of $\boldsymbol{P}_{e}$ implies $\lambda^{k-q}\left(\boldsymbol{P}_{e}\right)=\mathbf{0}$ since $\delta[V]$ is an open subset of $\boldsymbol{P}_{\boldsymbol{e}}$.

Given ( $\left.\boldsymbol{T}_{r}, J_{r}\right)$, Opp reacts with $\left(P_{f(e)}, \varphi_{f(e)}, \psi_{f(e)}\right)$.
By the Rec. Thm., there is $r$ s.t. $\left(\boldsymbol{P}_{r}, \varphi_{r}, \psi_{r}\right)=\left(\boldsymbol{P}_{f(r)}, \varphi_{f(r)}, \psi_{f(r)}\right)$.
Suppose: Opp wins with this triple ( $P_{r}, \varphi_{r}, \psi_{r}$ )

- Then $\mathcal{S}_{\boldsymbol{q}}$ eventually forces $\boldsymbol{P}_{\boldsymbol{r}}$ to be $(\boldsymbol{k} \boldsymbol{- q} \mathbf{- 1})$-dimensional; therefore, $\left(\mathcal{S}_{q}\right)_{q<k}$ forces $\boldsymbol{P}_{r}$ to be zero-dimensional.
- Since $\boldsymbol{P}_{\boldsymbol{r}}$ is convex (if $\mathbf{O p p}$ wins), $\boldsymbol{P}_{\boldsymbol{r}}$ is a singleton or empty.
- Then, there is some $\tau \in \mathbf{2}^{q+1}$ such that any point in $\boldsymbol{P}_{r}$ has a name $\boldsymbol{z}$ such that $\boldsymbol{\varphi}_{r}(\boldsymbol{z})$ does not extend $\boldsymbol{\tau}$.
- Then $\mathcal{S}_{q}$ ensures that $\boldsymbol{T}_{r}$ has a unique path $\boldsymbol{\tau}^{\wedge} \boldsymbol{0}^{\omega}$.
- Thus, $\varphi_{r}$ fails to choose a path of $\boldsymbol{T}_{\boldsymbol{r}}$; hence Opp loses.


## Proof of LLPO $\star$ AoUC $\not{ }_{\mathbf{L}}$ w AoUC*:

Easy. Use the similar argument

## Lemma

(1) $\mathrm{AoUC}^{m} \star \mathrm{AoUC}^{k} \leq w \mathrm{C}_{2^{k}} \star\left(\mathrm{AoUC}^{m \cdot 2^{k}+k}\right)$. In particular, AoUC $\star$ AoUC $\leq w$ LLPO $\star\left(\right.$ AoUC $\left.^{3}\right)$.
(2) $\mathrm{AoUC}^{\prime} \star \mathrm{C}_{m} \leq w$ AoUC ${ }^{1 \cdot m} \times \mathrm{C}_{m}$.

Corollary
AoUC ${ }^{\prime} \star \mathrm{AoUC}^{m} \star \mathrm{AoUC}^{k} \leq w \operatorname{AoUC}{ }^{(l+1) \cdot 2^{k}} \star \mathrm{AoUC}^{m \cdot 2^{k}+k}$.
In particular,

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