



Moving Interface Problems: Methods & Applications Tutorial Lecture IV

Grétar Tryggvason
Worcester Polytechnic Institute

Moving Interface Problems and Applications in Fluid Dynamics
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Moving Interface Problems—Complex Flows Phase Change

Outline

Flows with phase change

 Solidification

 Boiling

Electrohydrodynamics

Flows with topology changes

 Regime changes in bubbly flows

 Atomization and sprays

Outlook



Moving Interface Problems—Complex Flows Phase Change

The phase change between liquid and solid or between liquid and vapor is the critical step in the processing of most material as well as in energy generation.

Computations will make it possible to predict the small scale evolution of systems undergoing phase change from first principles.

To simulate such flows, it is necessary to solve the energy equation for the temperature distribution and to account for the change of phase at the phase boundary.



Moving Interface Problems—Complex Flows Phase Change

In addition to solving the energy equation and including the phase change, we must

- Account for volume expansion at the interface for boiling
- Accommodate a zero velocity field in the solid, for the solidification problem.

In reality there is a slight volume change for the solidification as well, but this can usually be neglected.



Formation of Microstructure during Solidification



Moving Interface Problems—Complex Flows Phase Change

Early papers on dendritic growth in the presence of flow:

Two-dimensional systems

Tonhardt and Amberg (1998)

Beckermann, et al (1999)

Juric (1998),

Shin and Juric (2000)

Al-Rawhai and Tryggvason (2001)

Three-dimensional system:

Danzig et al (2001)

Al-Rawhai and Tryggvason (2002)





Moving Interface Problems—Complex Flows Solidification

Pure material

$$\frac{\partial cT}{\partial t} + \nabla \cdot \mathbf{u}cT = \nabla \cdot k\nabla T + \int q\delta(\mathbf{x} - \mathbf{x}_f)dA$$

$$T_f = T_m \left(1 + \frac{\kappa}{L} + \dots\right)$$

$$q = LV_n$$

$$\frac{dx_f}{dt} = V_n \mathbf{n}$$

- D. Juric and G. Tryggvason, "A Front Tracking Method for Dendritic Solidification." *J. Comput. Phys.* 123, 127-148, (1996).
- N. Al-Rawahi and G. Tryggvason. Computations of the growth of dendrites in the presence of flow. Part I-Two-dimensional Flow. *J. Comput. Phys.* 180, 471–496 (2002)
- N. Al-Rawahi and G. Tryggvason. "Numerical simulation of dendritic solidification with convection: Three-dimensional flow." *Journal of Computational Physics.* 194 (2004) 677–696

Alloy

In addition to the energy equation, we must solve a species concentration equation

$$(C, D) = \begin{cases} (c_1 / k, kD_1) & \text{in the solid} \\ (c_2, D_2) & \text{in the liquid} \end{cases}$$

$$k = c_1 / c_2$$

$$\frac{\partial C}{\partial t} = \nabla \cdot D \nabla T + \int s \delta(\mathbf{x} - \mathbf{x}_f) dA$$

$$s = C(1 - k)V_n \quad \begin{array}{l} \text{m: slope} \\ \text{of liquidus line} \end{array}$$

$$T_f = T_m \left(1 + \frac{K}{L} - Cm\right)$$



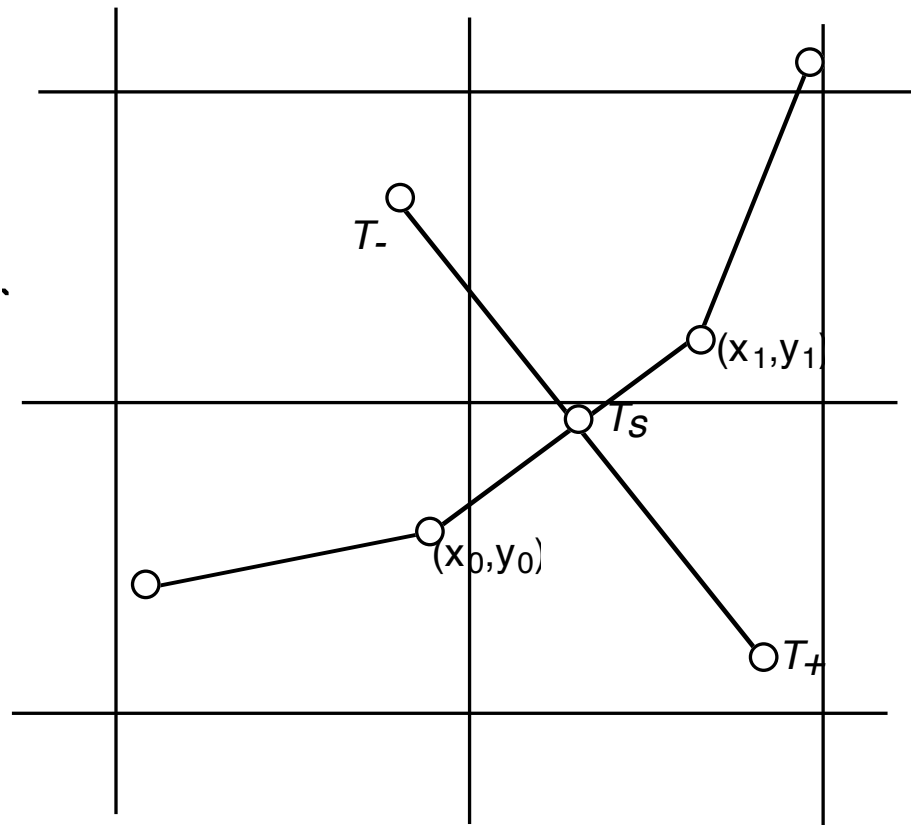


Moving Interface Problems—Complex Flows Solidification

Compute the heat source at the interface

$$\dot{q} = k \left. \frac{\partial T}{\partial n} \right|_l - k \left. \frac{\partial T}{\partial n} \right|_s$$

Originally we found the heat source iteratively such that the interface temperature matched the target value. Currently we use “normal probes,” following Udaykumar et al.





Moving Interface Problems—Complex Flows Solidification

Including the solid:

Simplified Procedure

$$\mathbf{u}^* = \mathbf{u}^n + \Delta t \mathbf{A}(\mathbf{u}^n)$$

$$\mathbf{u}^{**} = \mathbf{u}^* - \Delta t \nabla P$$

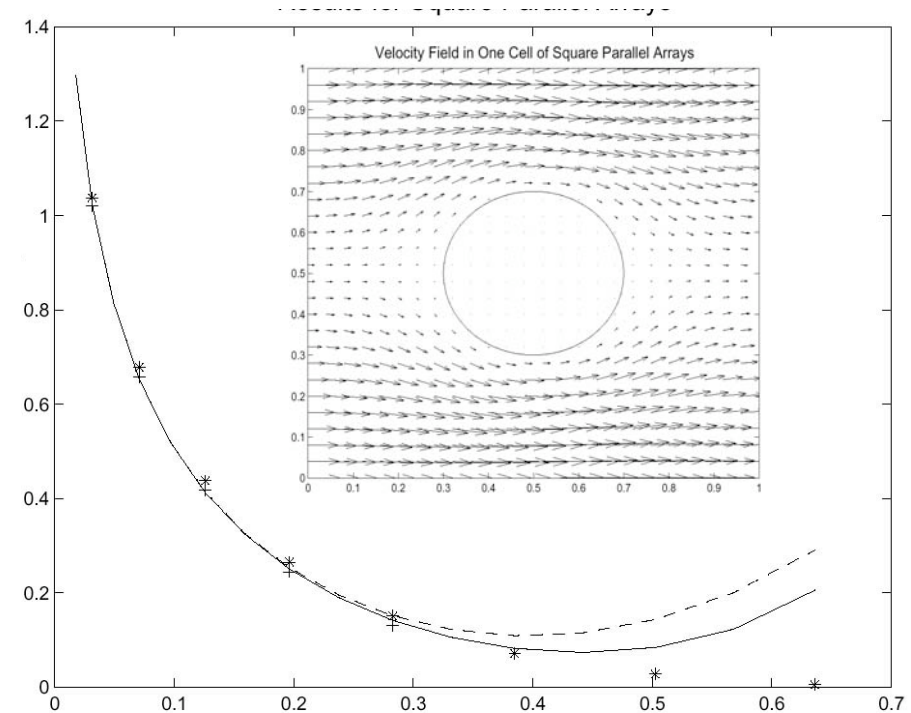
$$\mathbf{u}^{n+1} = \phi \mathbf{u}^{**}$$

$$\nabla \cdot \mathbf{u}^{n+1} = 0$$

Enforcing incompressibility

$$\nabla \cdot \mathbf{u}^{n+1} = \nabla \cdot \phi \mathbf{u}^{**} = \phi \nabla \cdot \mathbf{u}^{**} + \mathbf{u}^{**} \cdot \nabla \phi = 0$$

$$\nabla \cdot \mathbf{u}^{**} = 0$$





Moving Interface Problems—Complex Flows Solidification

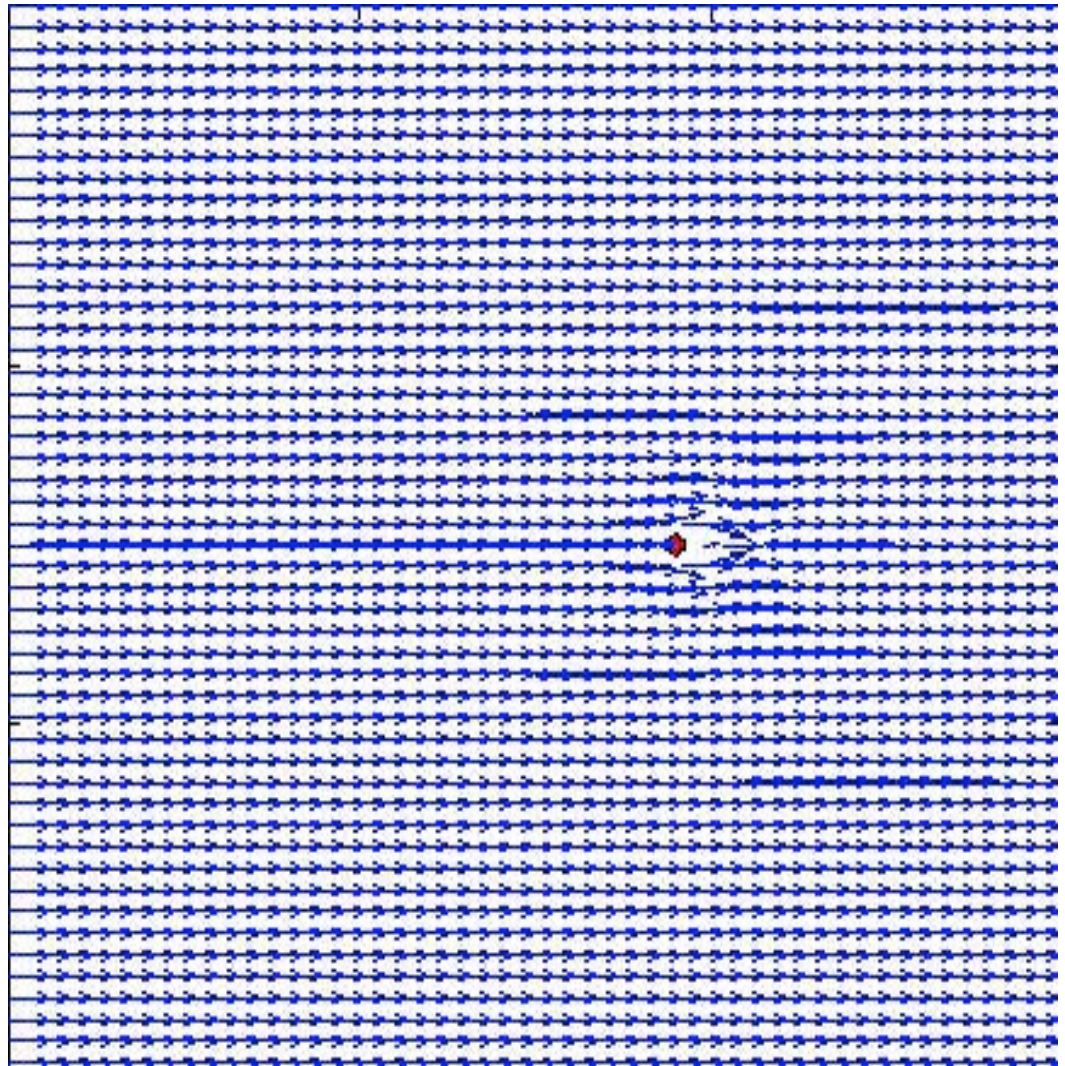
Dendrite growing in a
uniform flow

401 by 401 grid

Anisotropy=0.4

$$\text{St} = \frac{c(T_{\infty} - T_m)}{L} = -0.3$$

$$\text{Re} = \frac{\rho U Z}{\mu} = 600$$



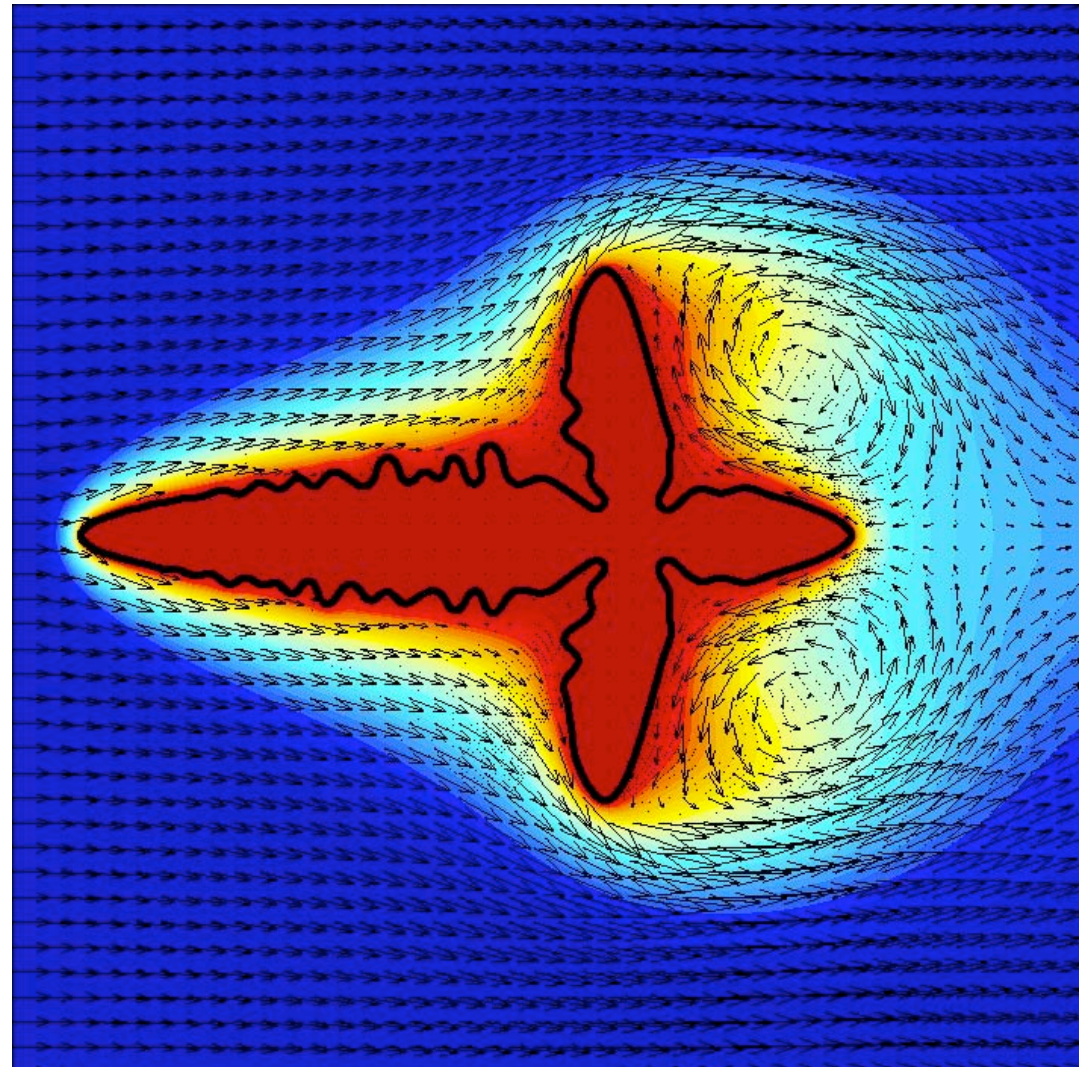
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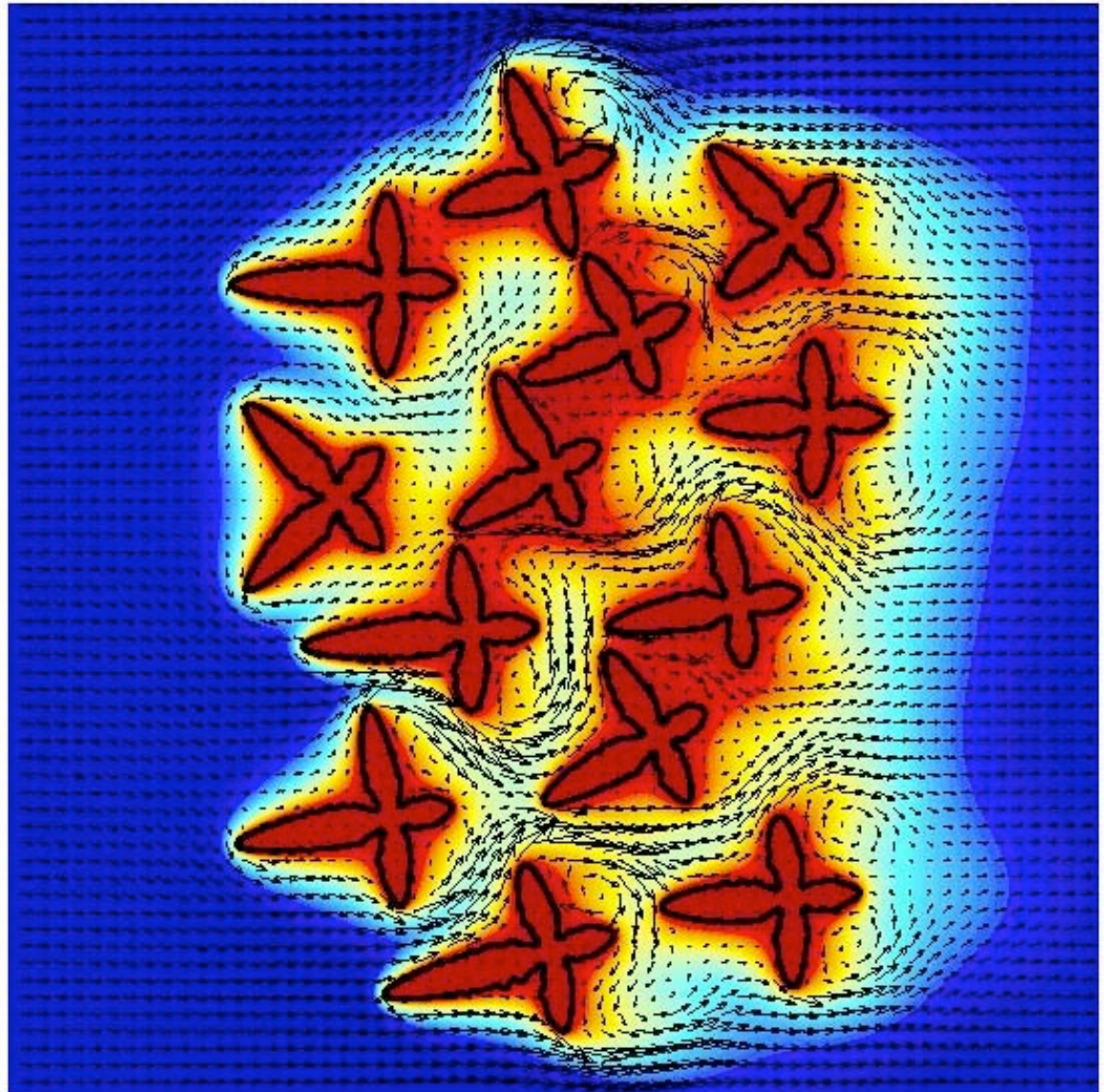
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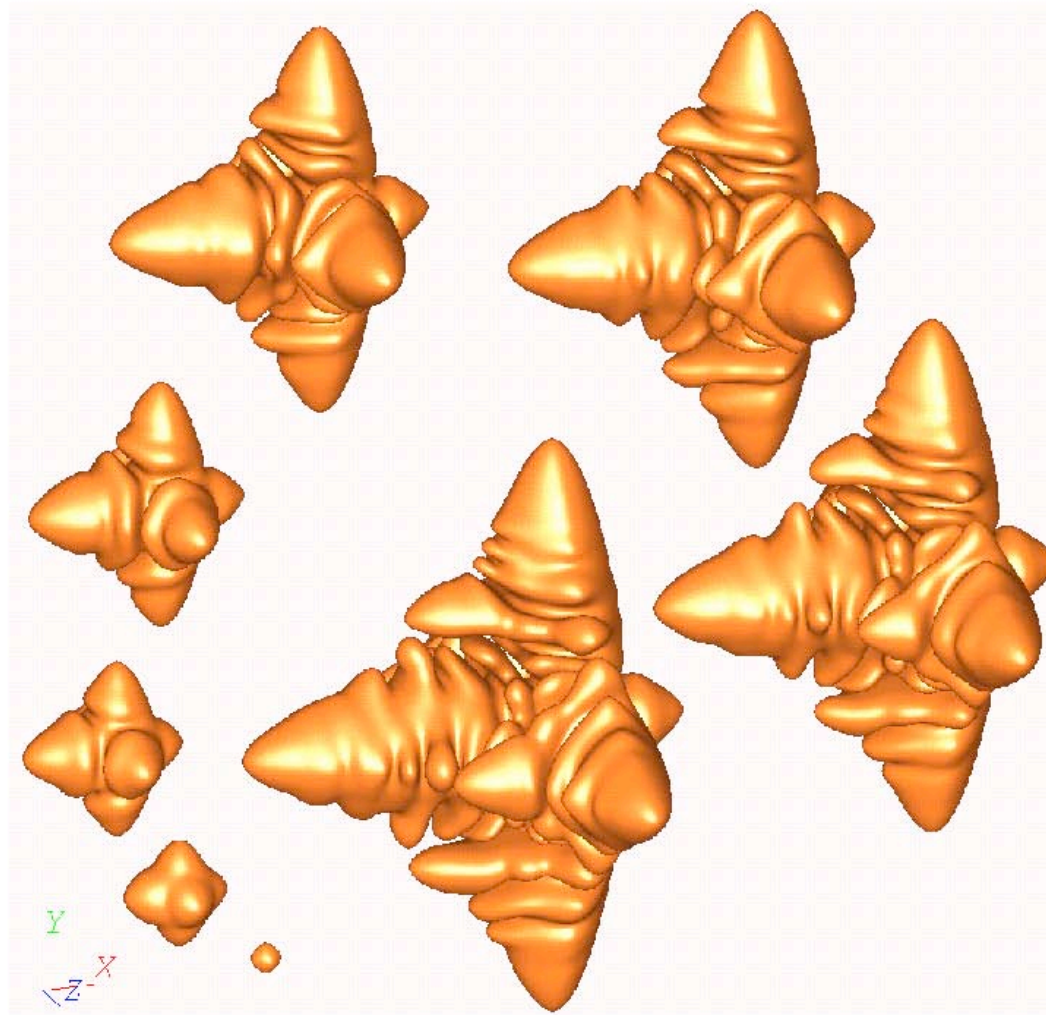
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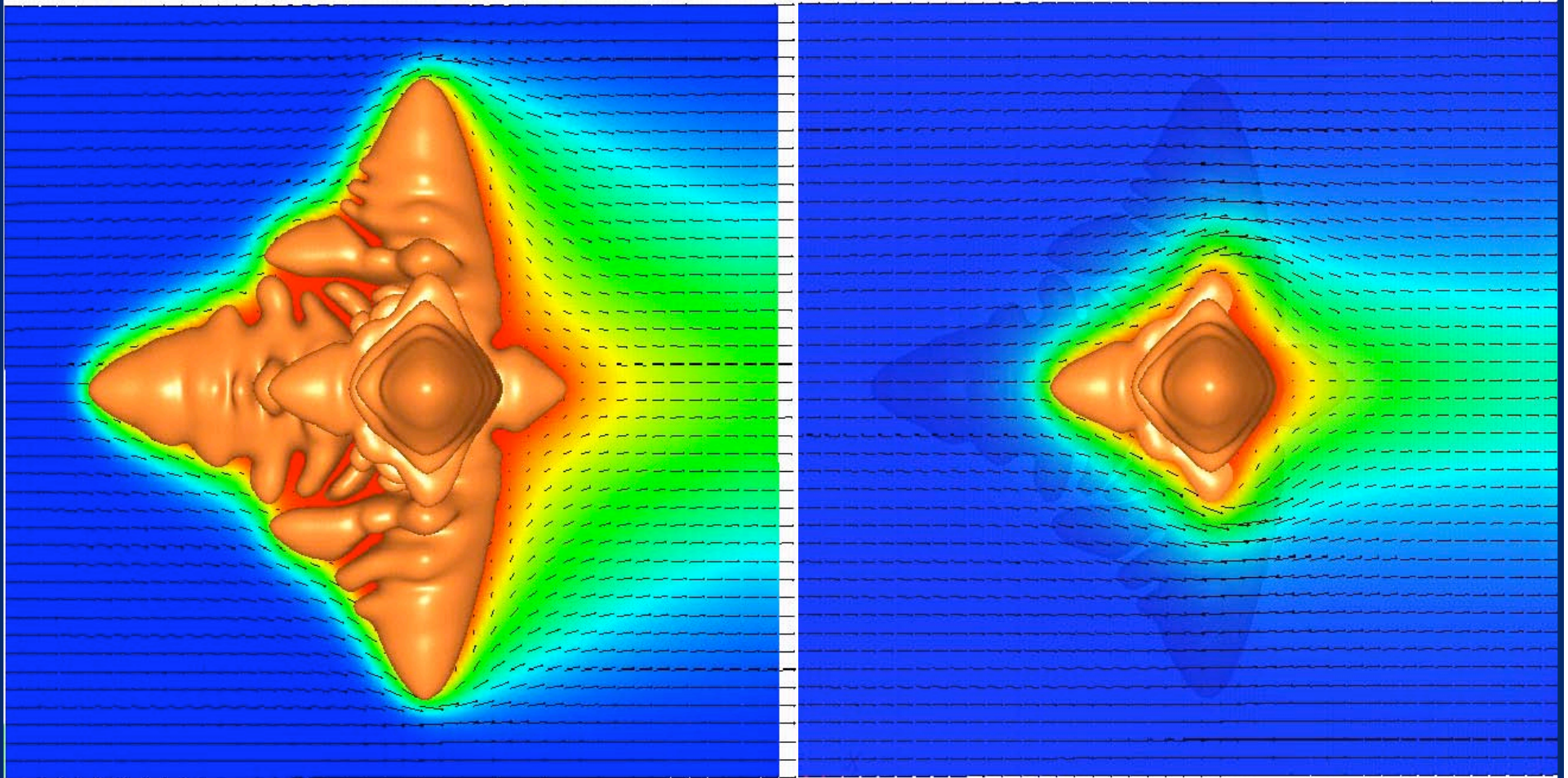




Moving Interface Problems—Complex Flows Solidification

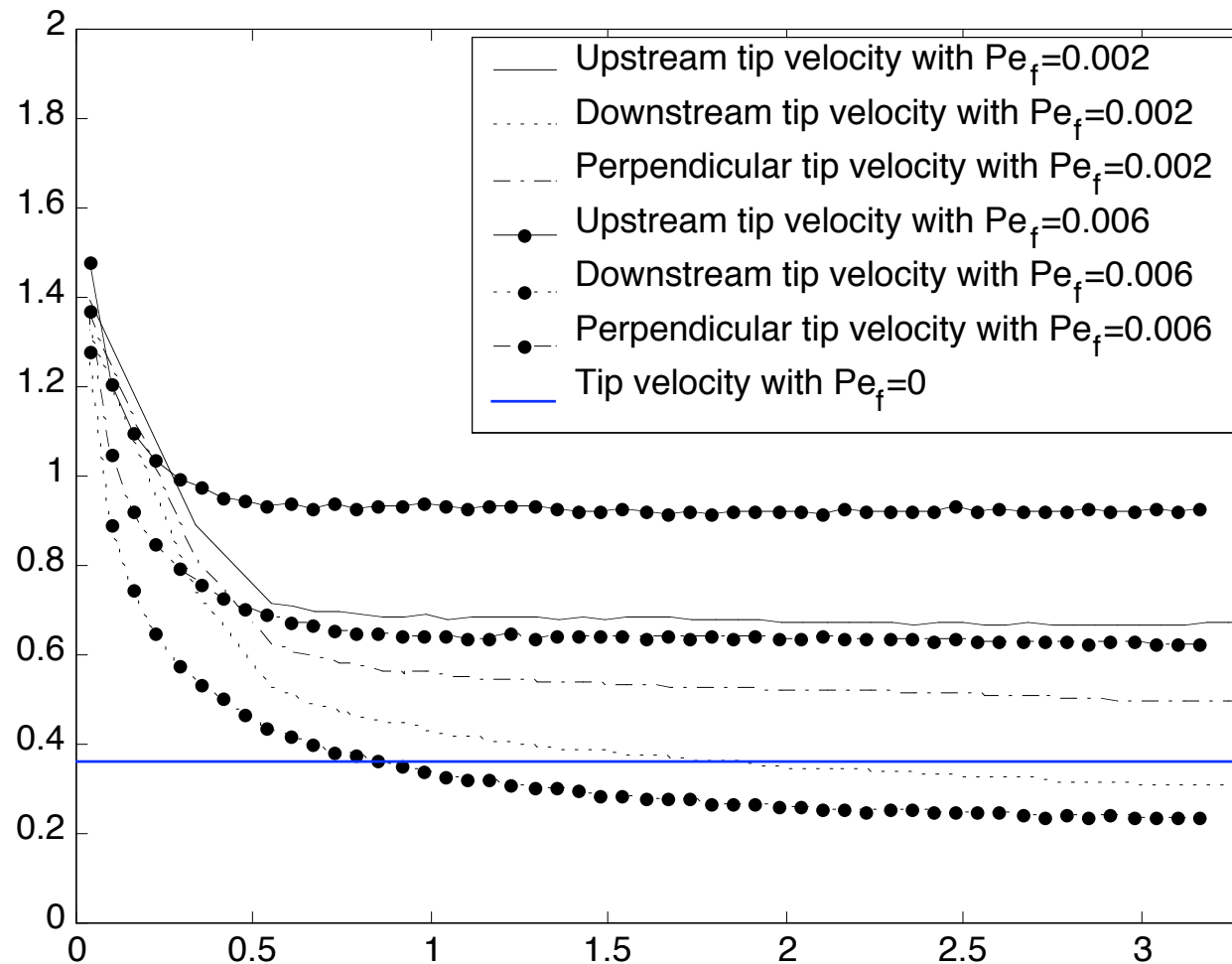


Moving Interface Problems—Complex Flows Solidification





Moving Interface Problems—Complex Flows Solidification



Velocity of the tip of the arms



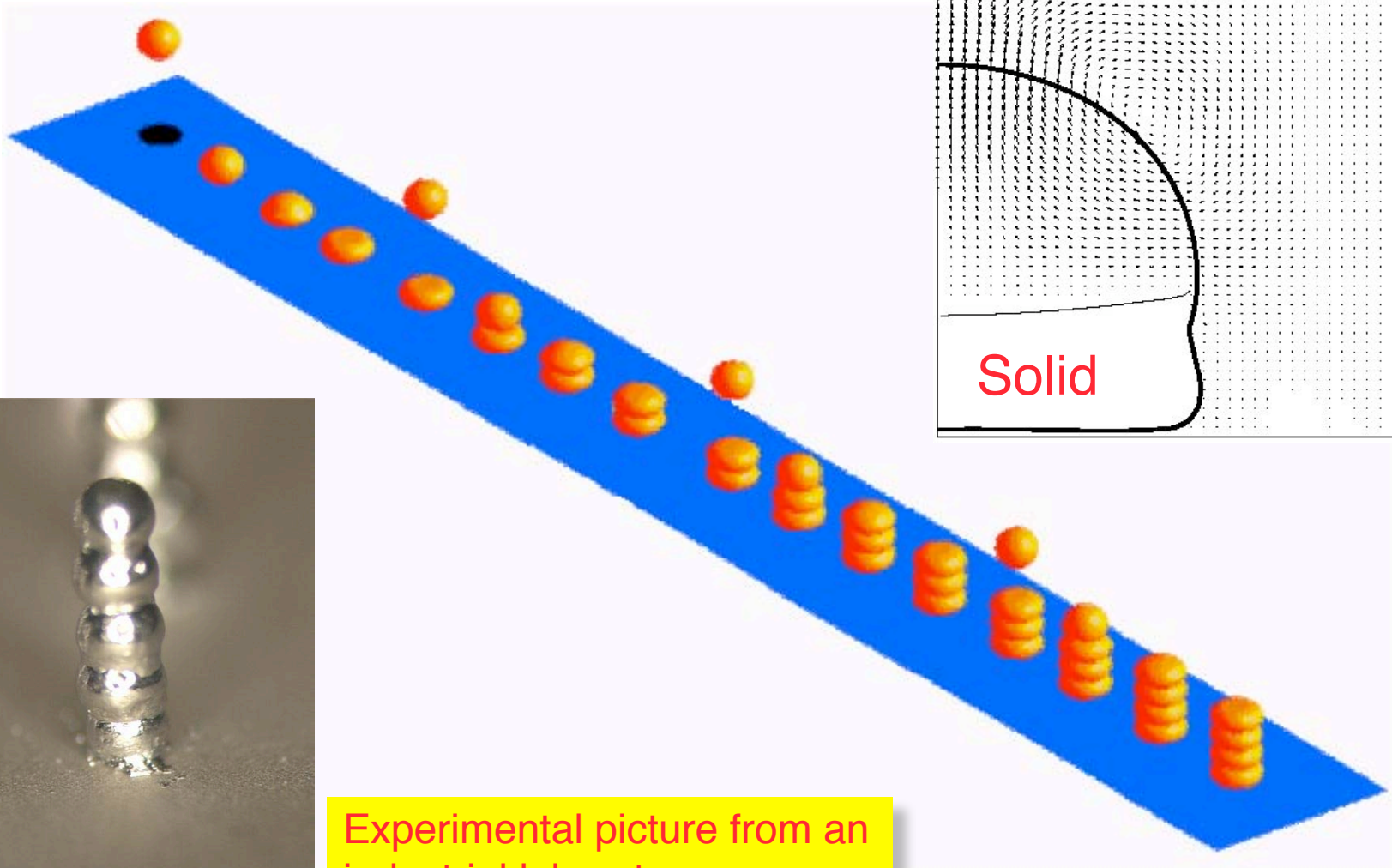
Moving Interface Problems—Complex Flows Solidification

Key challenges include:

- The extension of the numerical methods to alloys
- Inclusion of more complex interfacial effects
- The use of simulations to predict microstructure of fully solidified materials and the bulk properties of the material
- More complex processes, such as solidification of stirred melts

Moving Interface Problems—Complex Flows

Droplet Impingement and Solidification



Experimental picture from an industrial laboratory



Simulations of Boiling Flows



Moving Interface Problems—Complex Flows Boiling Flows

Early papers on boiling

Juric and Tryggvason (1998)

Son and Dhir (1998)

Son, Ramanujapu, and Dhir (2002)

Welch and Wilson (2000)

Song and Juric (2002)

Esmaeeli and Tryggvason (2002)

Kunugi et al., (2001,2002)



Moving Interface Problems—Complex Flows Boiling Flows

Energy equation	$\frac{\partial cT}{\partial t} + \nabla \cdot \bar{\mathbf{u}}T = \nabla \cdot k\nabla T + \int q\delta(\mathbf{x} - \mathbf{x}_f)dA$
Thermodynamic	T_f : Modified Clausius-Clapeyron eq.
Heat source	$q = L(\mathbf{V} - \bar{\mathbf{u}}) \cdot \mathbf{n}$
Velocity of bdry	$\frac{d\mathbf{x}_f}{dt} = V_n \mathbf{n} + \mathbf{u}$
Mass conservation	$\nabla \cdot \bar{\mathbf{u}} = \frac{1}{\rho} \frac{D\rho}{Dt}$

D. Juric and G. Tryggvason. Computations of Boiling Flows. *Int'l. J. Multiphase Flow*. 24 (1998), 387-410.

A. Esmaeeli and G. Tryggvason. Computations of Explosive Boiling in Microgravity. *J. Scient. Comput.* 19 (2003), 163-182



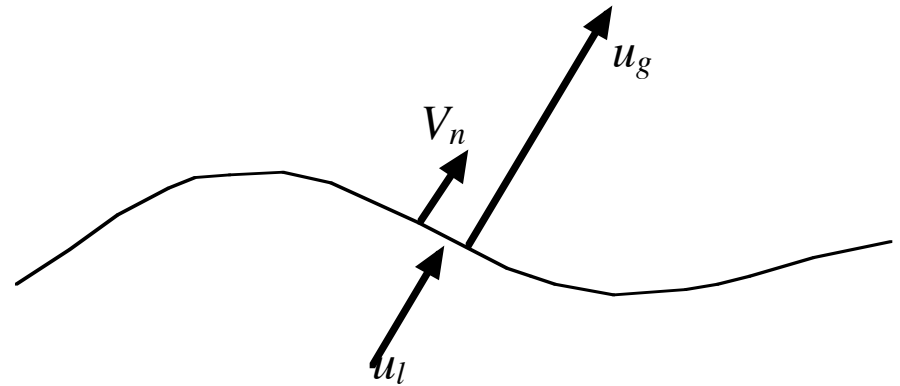
Moving Interface Problems—Complex Flows Boiling Flows

Computing the volume source

$$\dot{m} = \rho_l(u_l - V_n) = \rho_v(u_v - V_n)$$

Volume expansion:

$$u_v - u_l = \dot{m} \left(\frac{1}{\rho_v} - \frac{1}{\rho_l} \right)$$



Normal velocity

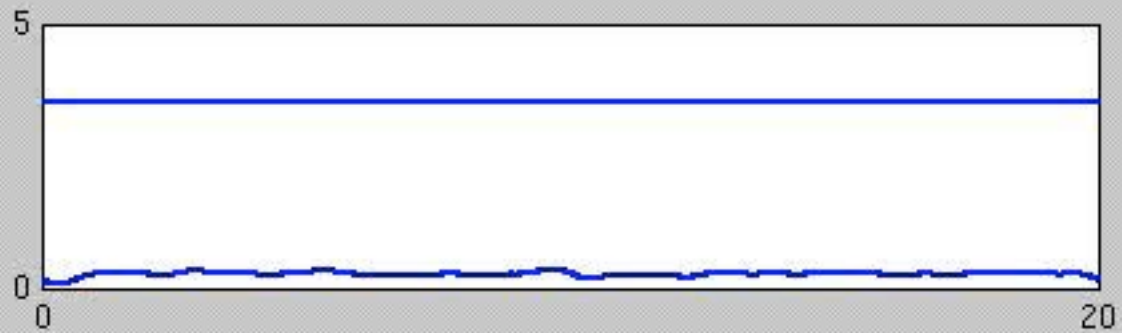
$$V_n = \frac{1}{2}(u_v + u_l) - \frac{\dot{m}}{2} \left(\frac{1}{\rho_v} + \frac{1}{\rho_l} \right)$$

Source term

$$\nabla \cdot \mathbf{u} = \frac{\dot{q}}{L} \left(\frac{1}{\rho_v} - \frac{1}{\rho_l} \right) \int \delta(\mathbf{x} - \mathbf{x}_f) ds$$



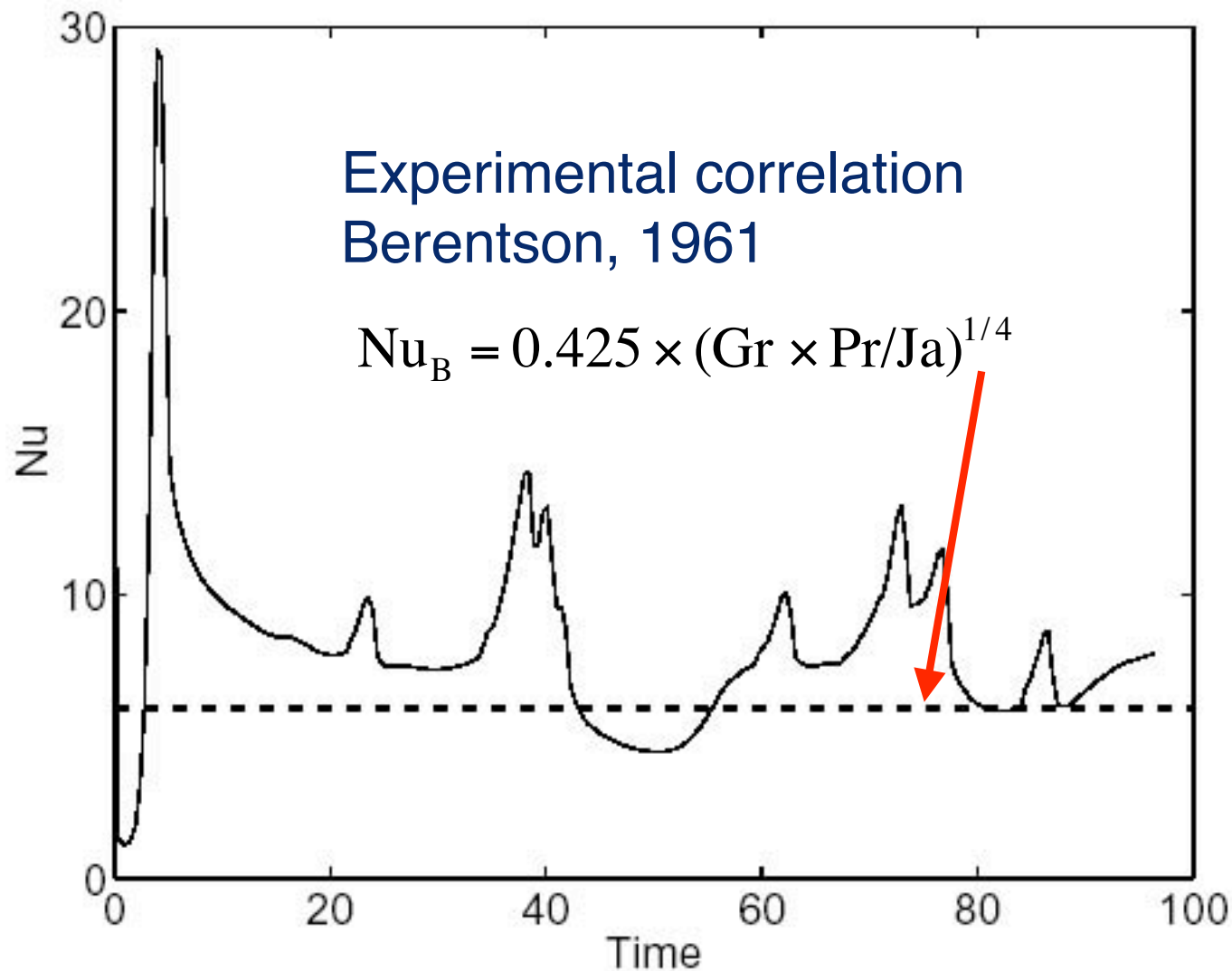
Moving Interface Problems—Complex Flows Boiling Flows





Moving Interface Problems—Complex Flows Boiling Flows

Nusselt number versus time

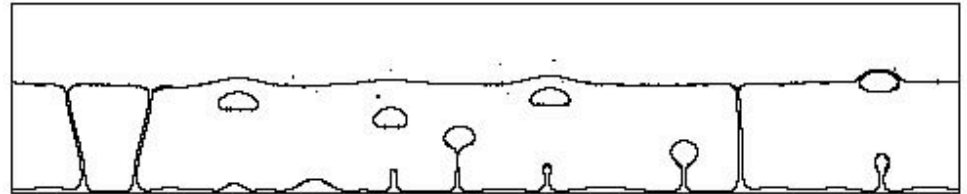




Moving Interface Problems—Complex Flows Boiling Flows

The effect of
the Jacobi
number on
the boiling for
near critical
film boiling

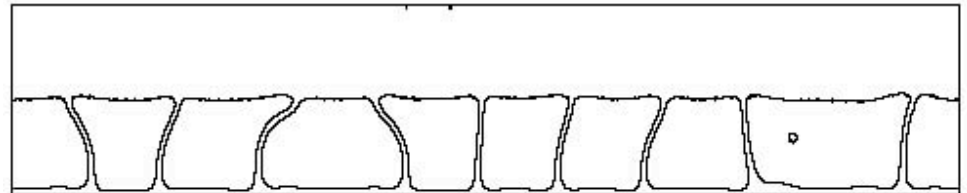
$Ja=0.035$



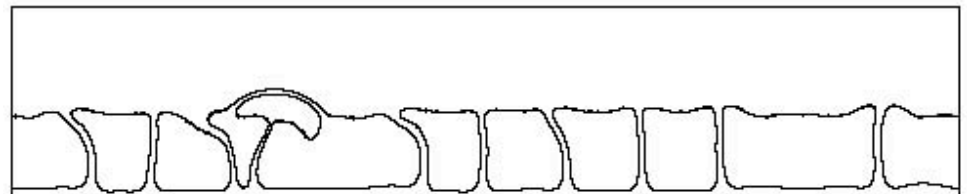
$Ja=0.117$



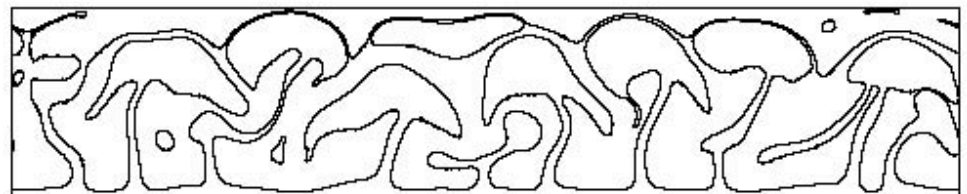
$Ja=0.234$



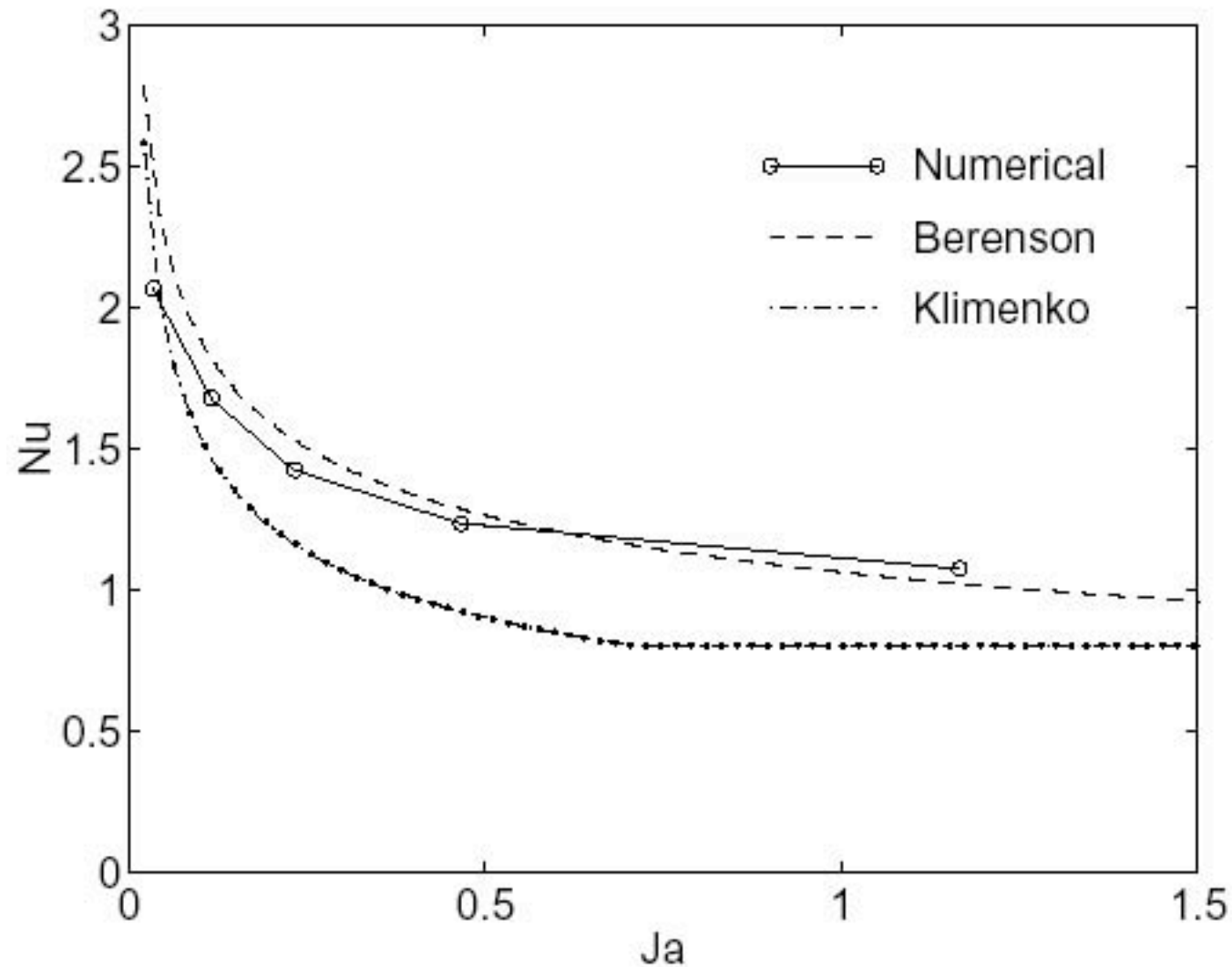
$Ja=0.468$



$Ja=1.167$

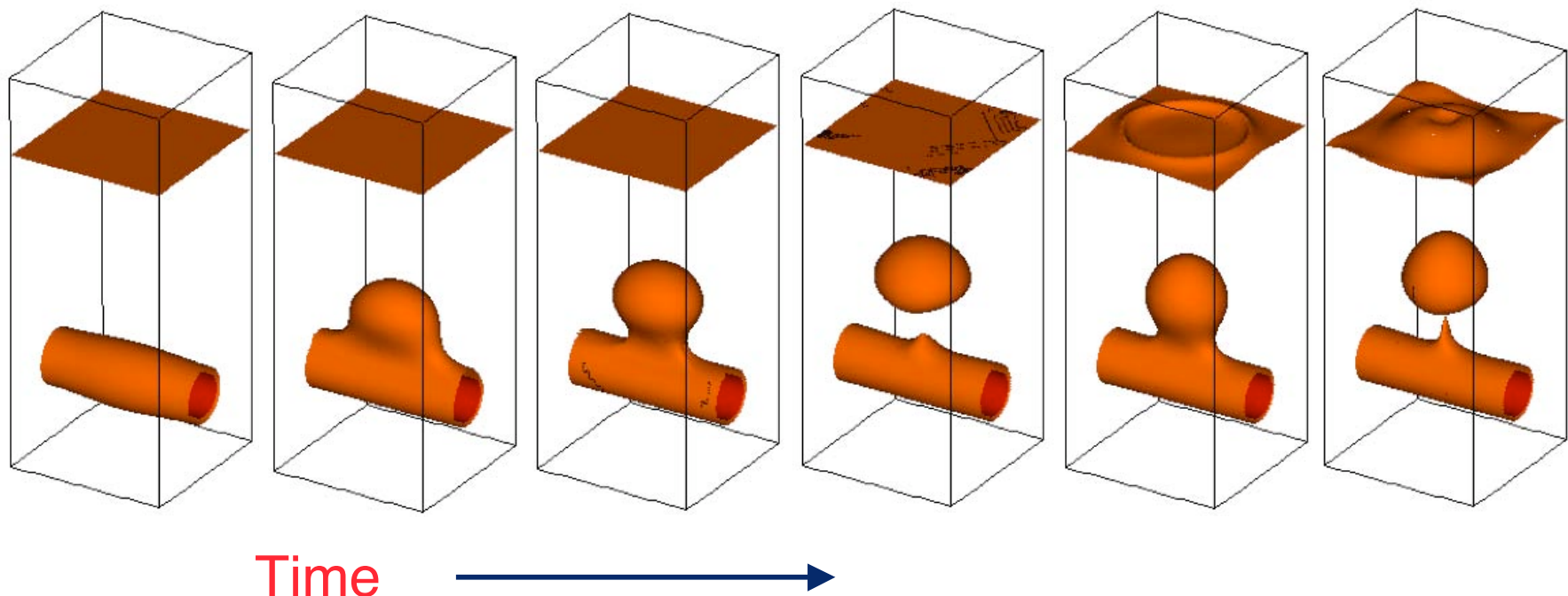


Moving Interface Problems—Complex Flows Boiling Flows

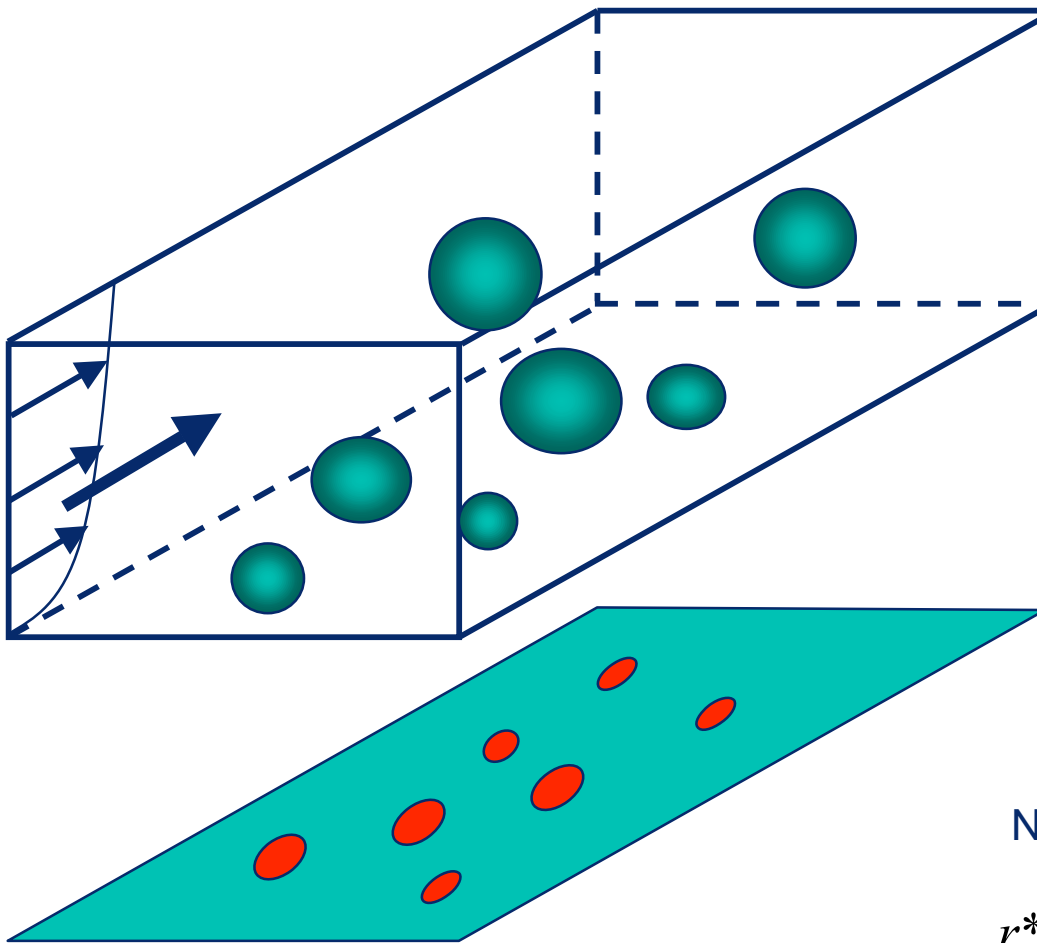


Moving Interface Problems—Complex Flows Boiling Flows

Film boiling from an embedded solid object. A hot solid cylinder is represented by an indicator function on a rectangular structured grid. As the vapor region around the cylinder grows, bubbles periodically break off and rise to the free surface



Nucleate Flow Boiling



Assumption : **Surface nucleation characteristics determined by size distribution of potentially active sites**

- Random spatial site distribution
- Random conical cavity size (mouth radius, r) distribution
- Assume vapor embryo radius = r
- Assume near wall liquid film is stationary

Nucleation site is active if $r_{\min} > r^*$

$$r^* = \frac{2\sigma T_{sat} v_{lv}}{h_{lv} [T_l - T_{sat}]} \quad \text{Carey (1992)}$$



Moving Interface Problems—Complex Flows Boiling Flows

Heat Conduction across Liquid Film

$$\dot{q} = \frac{k_l (T_{wall} - T_{int})}{\delta}$$

Modified Clausius-Clapeyron equation

$$\dot{q} = 2(M / 2\pi \bar{R} T_v)^{1/2} \frac{\rho_v h_{lv}^2}{T_v}$$

$$[T_{int} - T_v + (P_l - P_v) T_v / \rho_l h_{lv}]$$

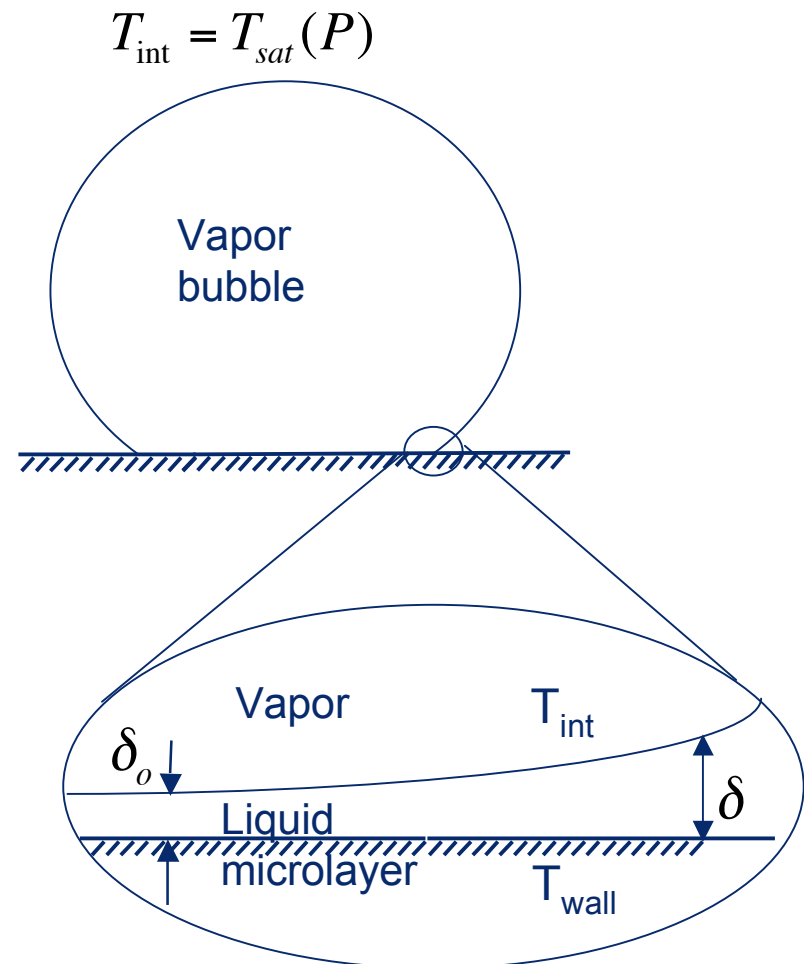
Modified Laplace-Young equation

$$p_l - p_v = -\sigma K - \frac{A}{\delta^3} + \frac{\dot{q}}{\rho_v h_{lv}^2}$$

Combine to find: $\dot{q} = \dot{q}(\delta)$

Model of: Son, Dhir, Ramanujapu (1999)

Microlayer Modeling



Rise of a Steam Bubble in Saturated Water

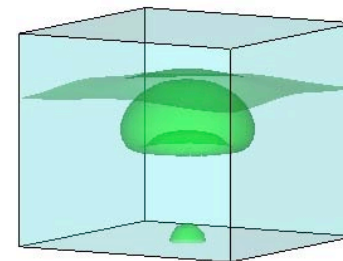
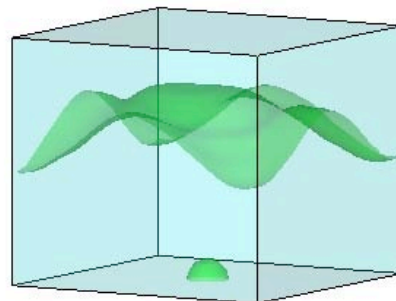
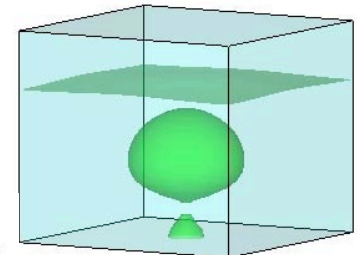
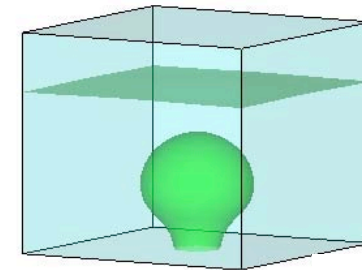
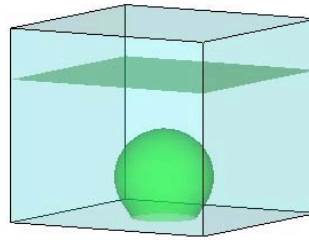
- 15mm³ horizontally periodic box
- Initial bubble radius 2.5 mm
- Cavity radius 1 mm

• Liquid/Vapor:
density ratio = 1605
viscosity ratio = 23
thermal conductivity ratio = 27
specific heat ratio = 1

- Wall superheat = 5K

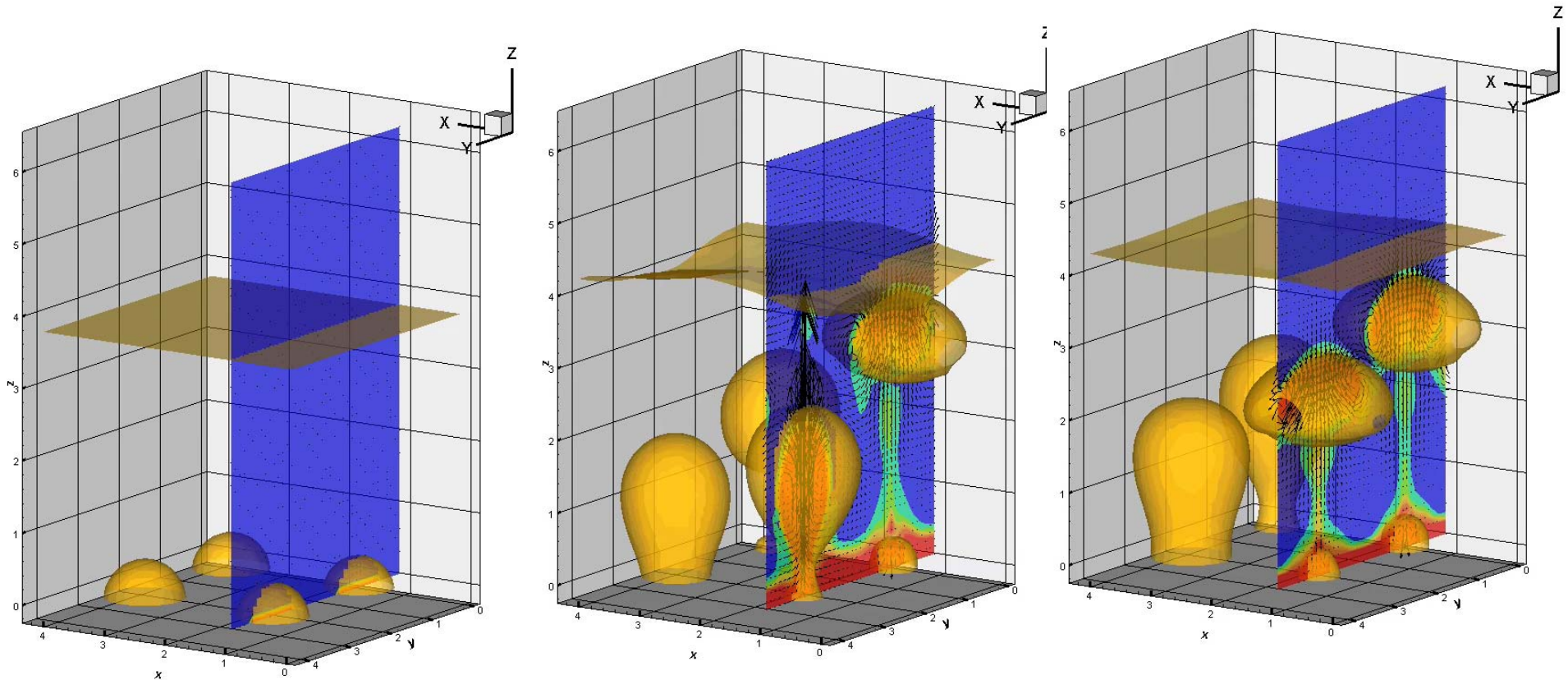
•Front Tracking with Level
Contour Reconstruction

•Staggered grid
MAC/Projection solution of
two-phase
incompressible Navier-
Stokes Equations



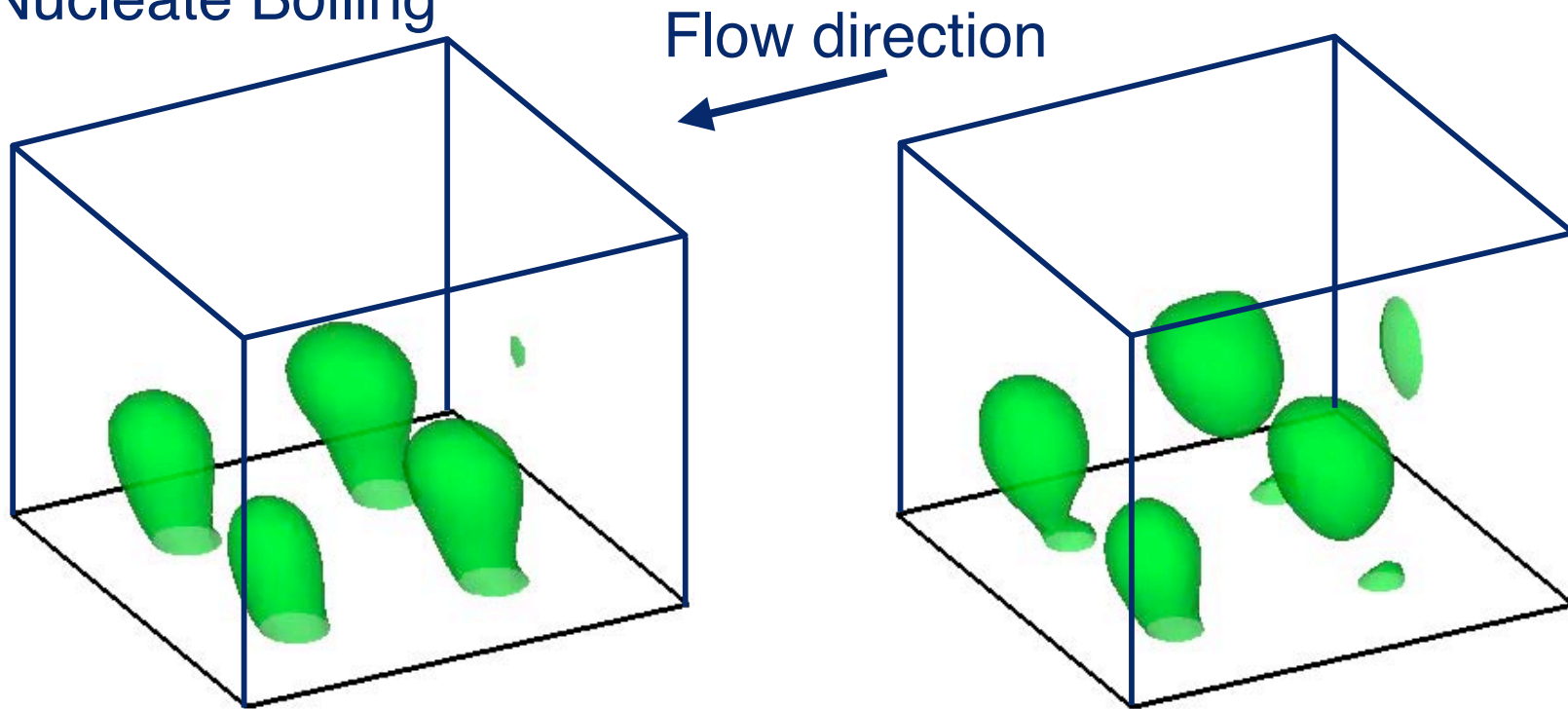
From Damir Juric

- 2nd order ENO advection
- Wall refined grid
- BiCGSTAB solution of pressure
Poisson equation



Water at 1 atm, $T_{\text{sat}}=373.15\text{K}$; liquid/vapor density ratio=1605;
viscosity ratio=23; thermal conductivity ratio=27; specific heat ratio=1;
domain size: 10.5x10.5x15.75 mm; Wall superheat: 18K
40x40x60 grid resolution

Nucleate Boiling



- Liquid/Vapor:
density ratio = 1605
viscosity ratio = 23
thermal conductivity ratio = 27
specific heat ratio = 1
- Wall superheat = 5K

- 15mm³ horizontally periodic box
- Initial bubble radius 2.5 mm
- Cavity radius 1 mm

- 2nd order ENO advection
- Wall refined grid
- BiCGSTAB solution of pressure Poisson equation



Moving Interface Problems—Complex Flows Boiling Flows

There appears to be no significant technical obstacles for conducting large scale simulations of nucleate flow boiling—however, some development works still needs to be done!

Such simulations should allow us to

- Assess the accuracy of the assumptions made in the modeling of the microlayer
- Use the simulations to make predictions about boiling under conditions where experiments are difficult or do not yield the necessary data.



Electrohydrodynamics of Droplet Suspensions



Moving Interface Problems—Complex Flows Electrohydrodynamics

Electrostatic fields are known to have strong influence on multiphase flows:

Breakup of jets and drops

Phase distribution in suspensions

Here, we examine the effect of electrostatic fields on a suspension of drops in channel flows by direct numerical simulations.

For fluids with small but finite conductivity, Taylor and Melcher (1969) proposed the “leaky dielectric” model. This model allows both normal and tangential electrostatic forces on a two fluid interface.



Moving Interface Problems—Complex Flows Electrohydrodynamics

The fluid flow

Momentum (conservative form, variable density and viscosity)

$$\frac{\partial \rho \bar{u}}{\partial t} + \nabla \cdot \rho \bar{u} \bar{u} = -\nabla p + \underbrace{\bar{f}}_{\text{Electric force}} + \nabla \cdot \mu (\nabla \bar{u} + \nabla^T \bar{u}) + \underbrace{\int_F \sigma \kappa \bar{n} \delta(\bar{x} - \bar{x}_f) da}_{\text{Surface tension}}$$

Mass conservation (incompressible flows)

$$\nabla \cdot \bar{u} = 0$$



Moving Interface Problems—Complex Flows Electrohydrodynamics

The electric field is obtained from the equation for the conservation of current:

$$\frac{Dq}{Dt} = \nabla \cdot \sigma \mathbf{E}$$
A red circle is drawn around the term $\frac{Dq}{Dt}$ in the equation. A blue arrow points from the circle to a superscript "0" located above the right-hand side of the equation, $\nabla \cdot \sigma \mathbf{E}$.

neglecting also
convection of
charge

the charge accumulation is found by:

$$q = \nabla \cdot \epsilon \mathbf{E}$$

The force on the fluid is then found by:

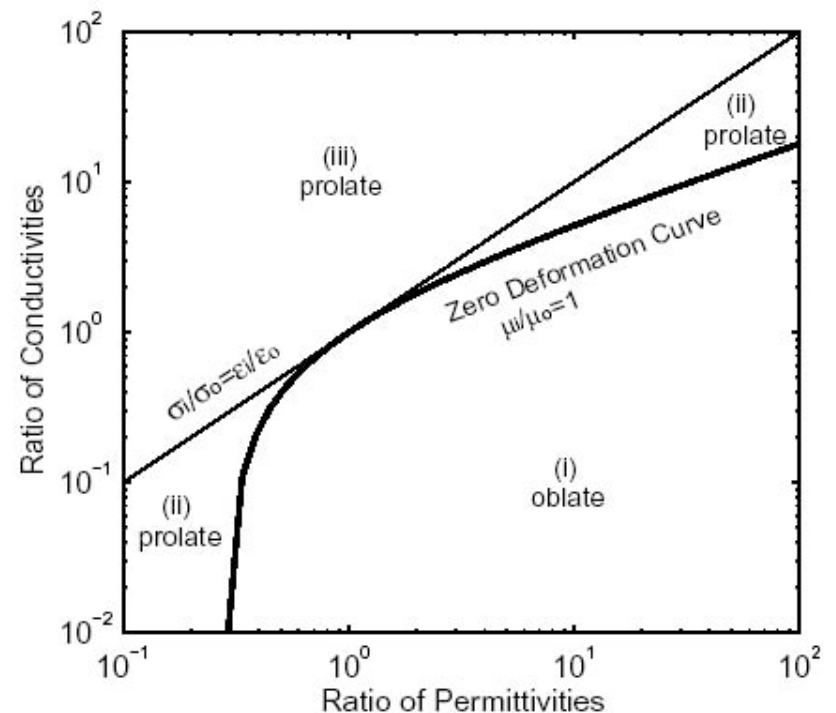
$$\mathbf{f} = q\mathbf{E} - \frac{1}{2}(\mathbf{E} \cdot \mathbf{E})\nabla\epsilon$$

Boundary between prolate and oblate drops

$$\Phi_{3D} = \frac{\epsilon_o}{\epsilon_i} \left(\left(\frac{\sigma_i}{\sigma_o} \right)^2 + 1 \right) - 2 + \frac{3}{5} \left(\frac{\sigma_i}{\sigma_o} \frac{\epsilon_o}{\epsilon_i} - 1 \right) \left(\frac{2 \left(\frac{\mu_o}{\mu_i} + 3 \right)}{\frac{\mu_o}{\mu_i} + 1} \right) \quad \text{Taylor (1966)}$$

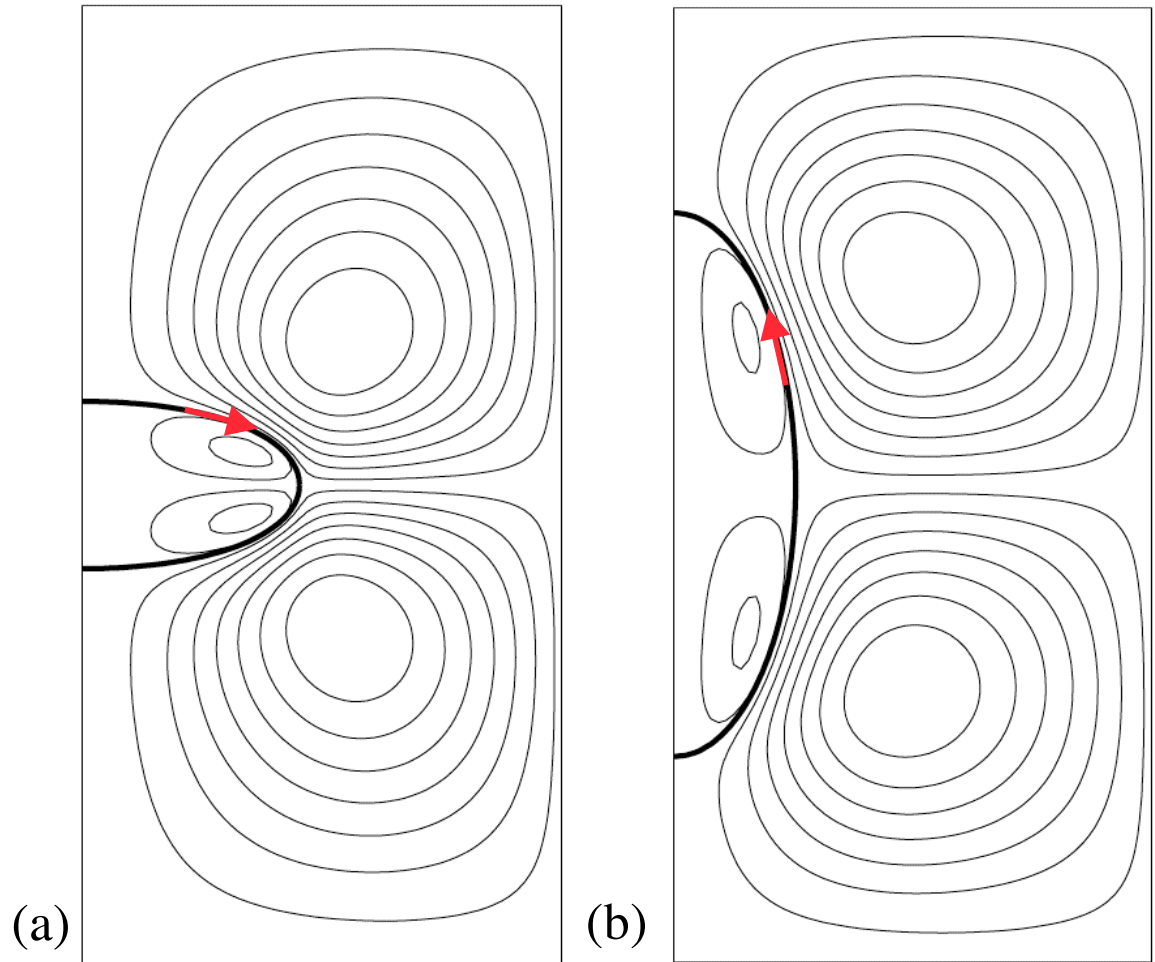
$$\Phi_{2D} = \left(\frac{\sigma_i}{\sigma_o} \right)^2 + \frac{\sigma_i}{\sigma_o} + 1 - 3 \frac{\epsilon_i}{\epsilon_o} \quad \text{Rhodes et al. (1988)}$$

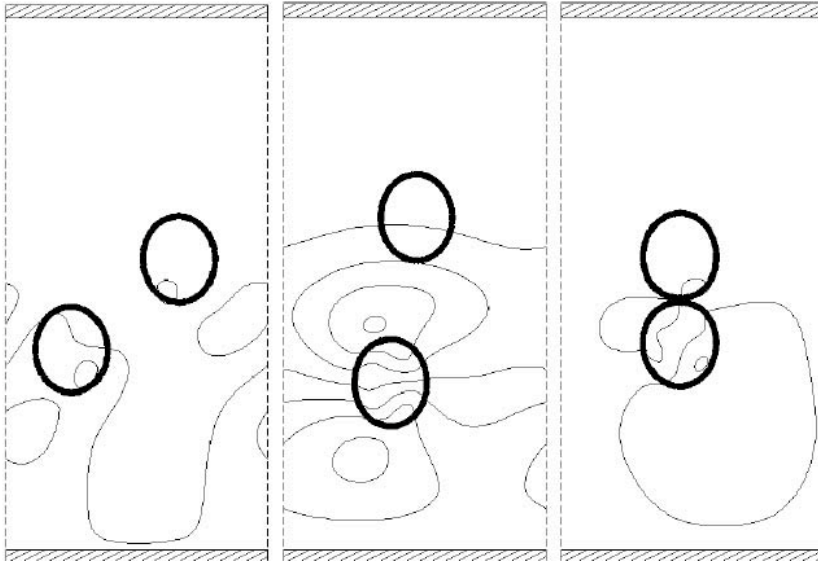
$$\Phi = \begin{cases} > 1 & \text{Prolate} \\ = 0 & \text{Spherical} \\ < 1 & \text{Oblate} \end{cases}$$



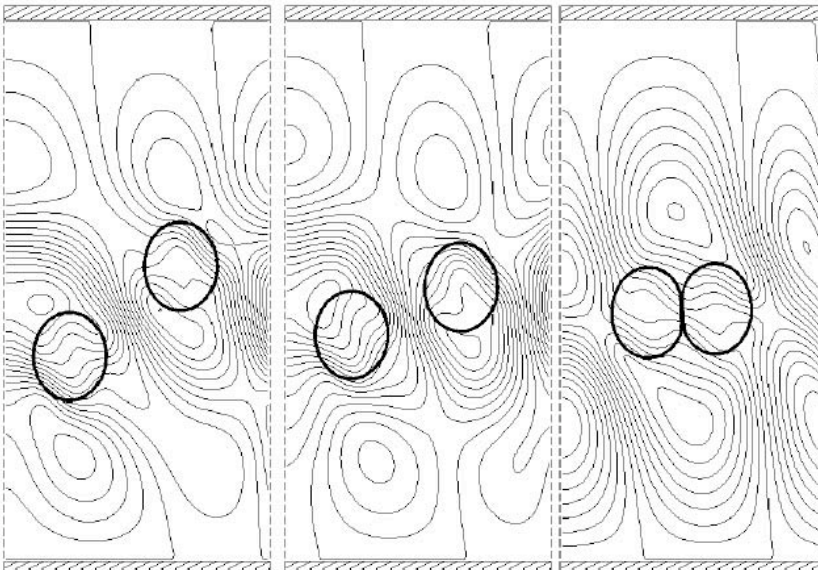
Deformation of a Single Drop

Electrostatic deformation of axisymmetric drops. The steady state obtained after following the transient motion of an initially spherical drop. For the oblate drop in (a) the ratio of the dielectric constant of the drop to the dielectric constant of the suspending fluid is much larger than the conductivity ratio, but for the prolate drop in (b) both ratios are comparable





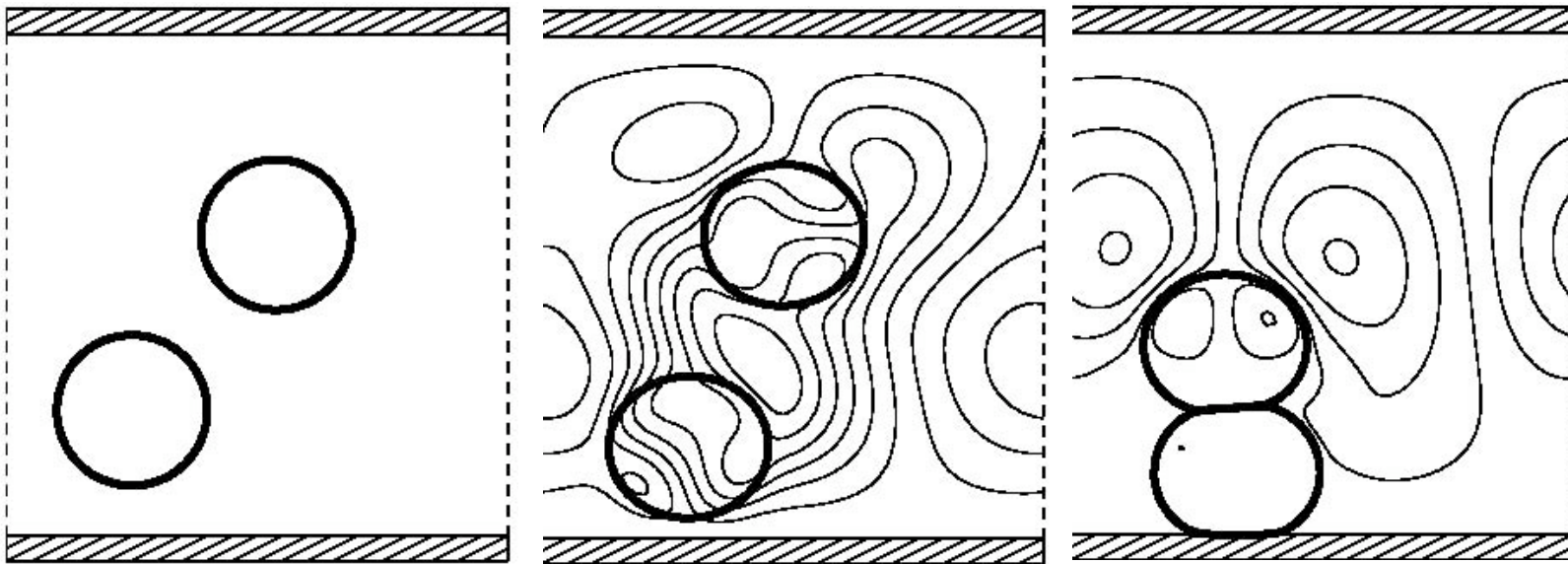
Drop distribution and streamlines for the interaction between two prolate drops. $S^{-1} = 0.01$, $R=0.1$; initial distance between the drops centroids $r_0=3.5$ times the radius



Drop distribution and streamlines for the interaction between two prolate drops. $S^{-1} = 0.01$, $R=1.0$; initial distance between the drops centroids $r_0=3.5$ times the radius

$$R = \frac{\sigma_i}{\sigma_o}; \quad S^{-1} = \frac{\epsilon_i}{\epsilon_o};$$

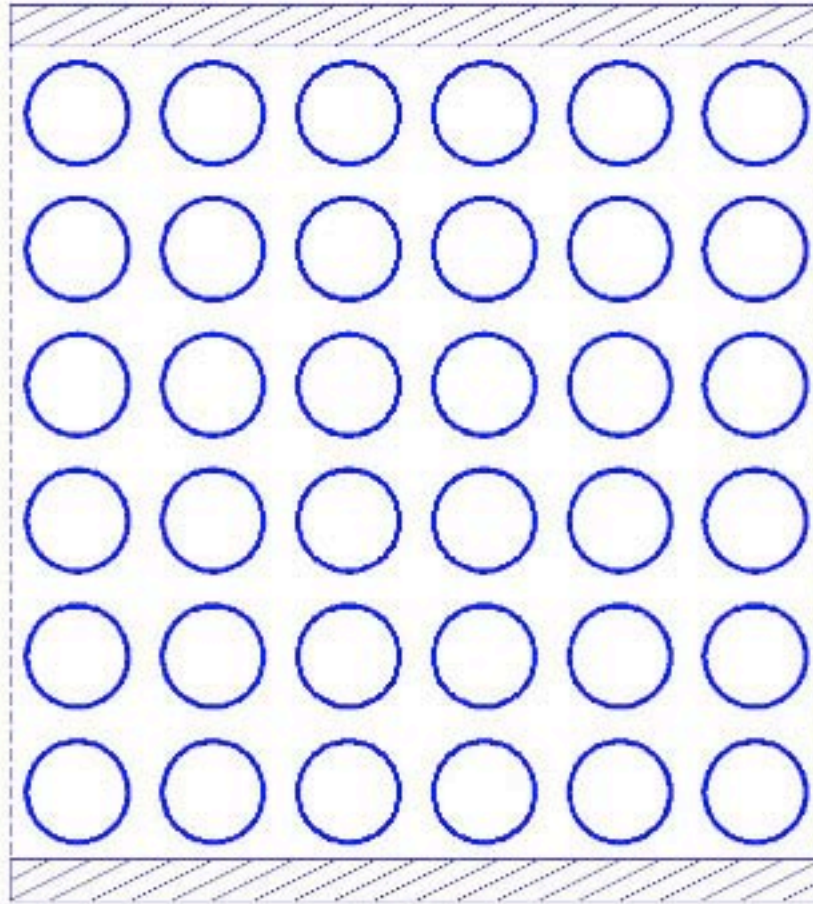
Interaction of Two Drops



The motion of two oblate drops in a quiescent flow. The drops align with the electric field and attract each other. The drops are also attracted to the wall

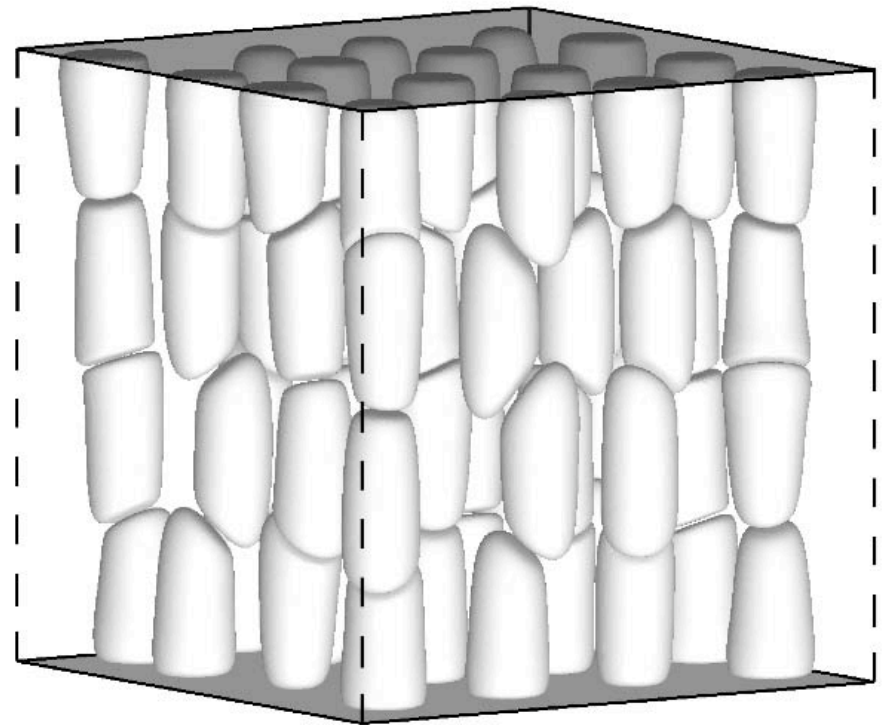
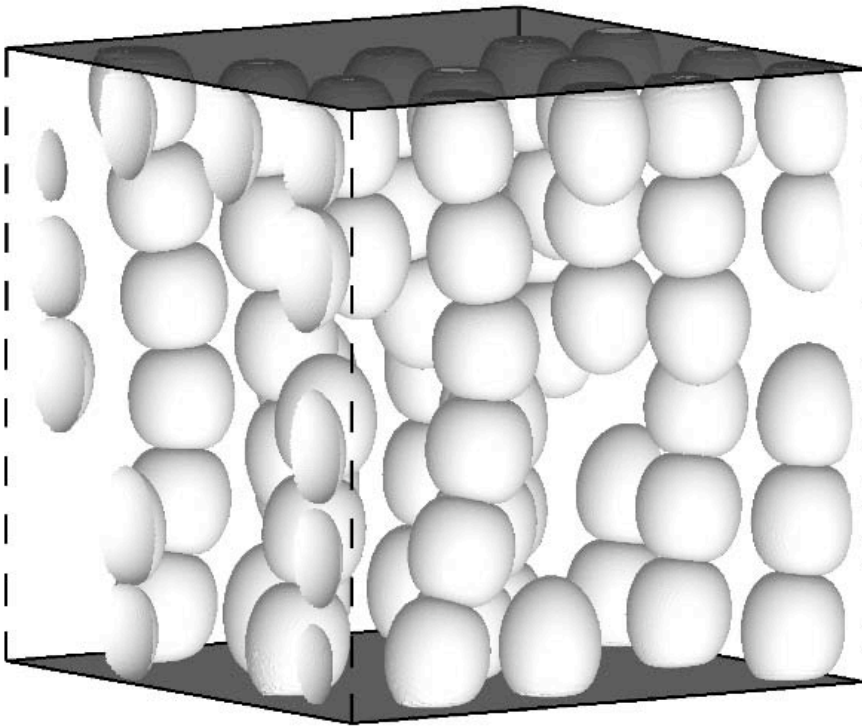


Moving Interface Problems—Complex Flows Electrohydrodynamics



$$\begin{aligned}\sigma_i/\sigma_o &= 0.005 & \text{Re} &= 20 \\ \varepsilon_i/\varepsilon_o &= 0.01 & \text{We} &= 0.0625 \\ \alpha &= 20\% & E^* &= 0.0182\end{aligned}$$

$$\begin{aligned}\sigma_i/\sigma_o &= 0.01 & \text{Re} &= 20 \\ \varepsilon_i/\varepsilon_o &= 0.1 & \text{We} &= 0.0625 \\ \alpha &= 20\% & E^* &= 0.04\end{aligned}$$





Moving Interface Problems—Complex Flows Electrohydrodynamics

The interaction of many drops in channels, with and without flow has been examined.

Oblate drops always fibrilate as the electrohydrodynamically induced fluid motion works with the electric interactions to line up the drops

Fluid shear breaks up the fibers, depositing them on the walls for intermediate flow rate and keeping them in suspension for high enough flow rates

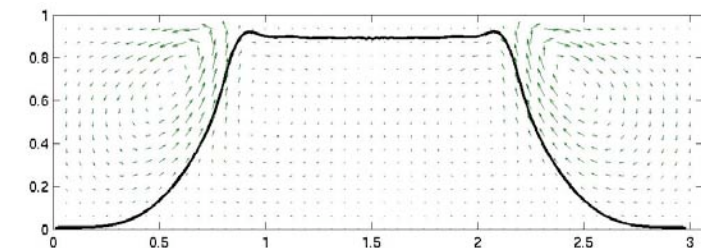
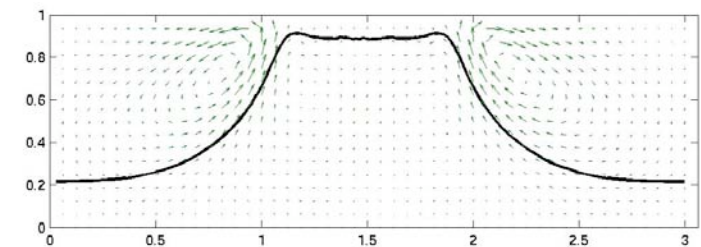
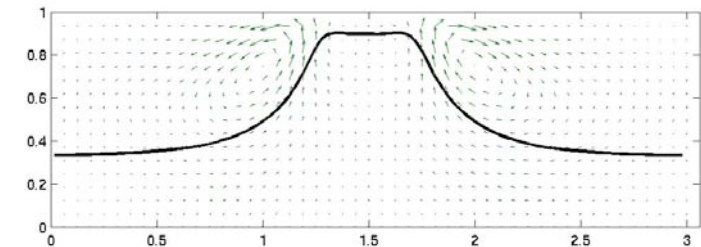
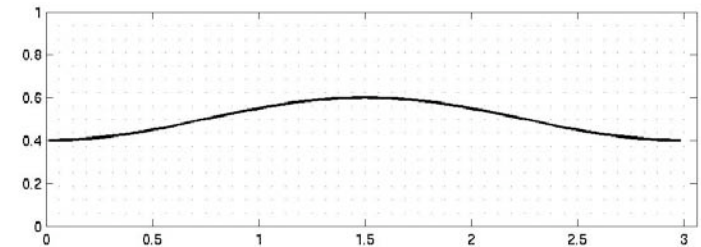
Prolate drops exhibit more complex interaction and form additional structures



Moving Interface Problems—Complex Flows Electrohydrodynamics

The instability of a thin film:

The interface and the
velocity field at time zero
and three subsequent
times for $S=1$ and $R=100$.



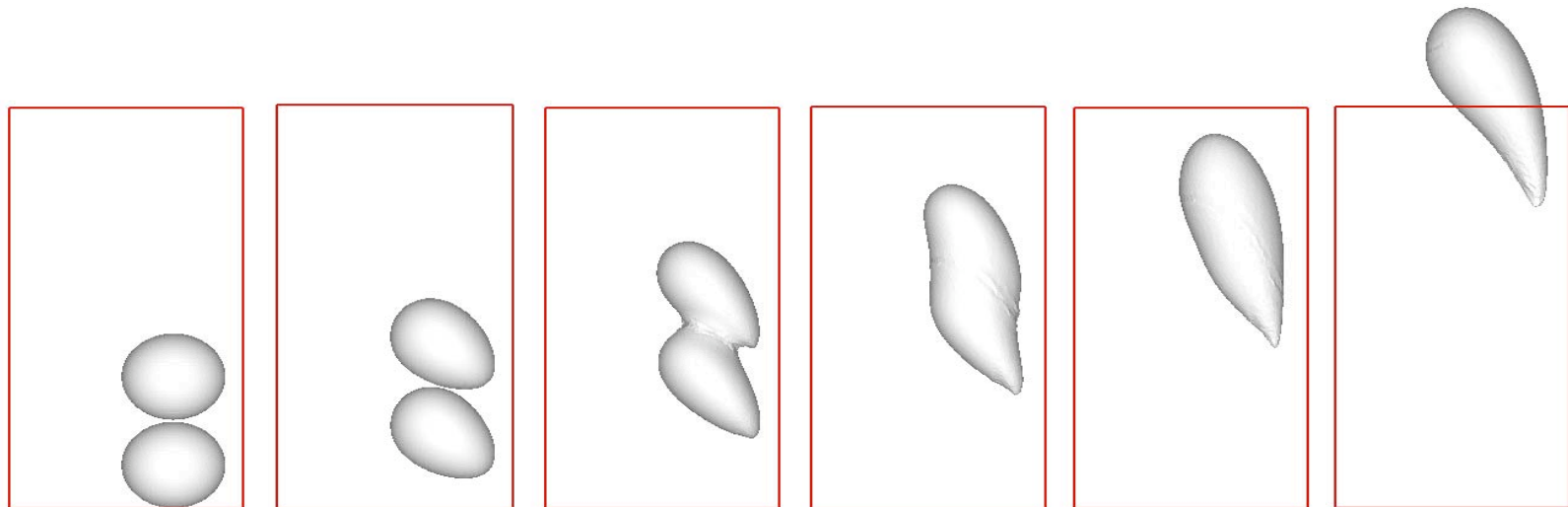


Coalescence induced flow regime transitions



Moving Interface Problems—Complex Flows Coalescence

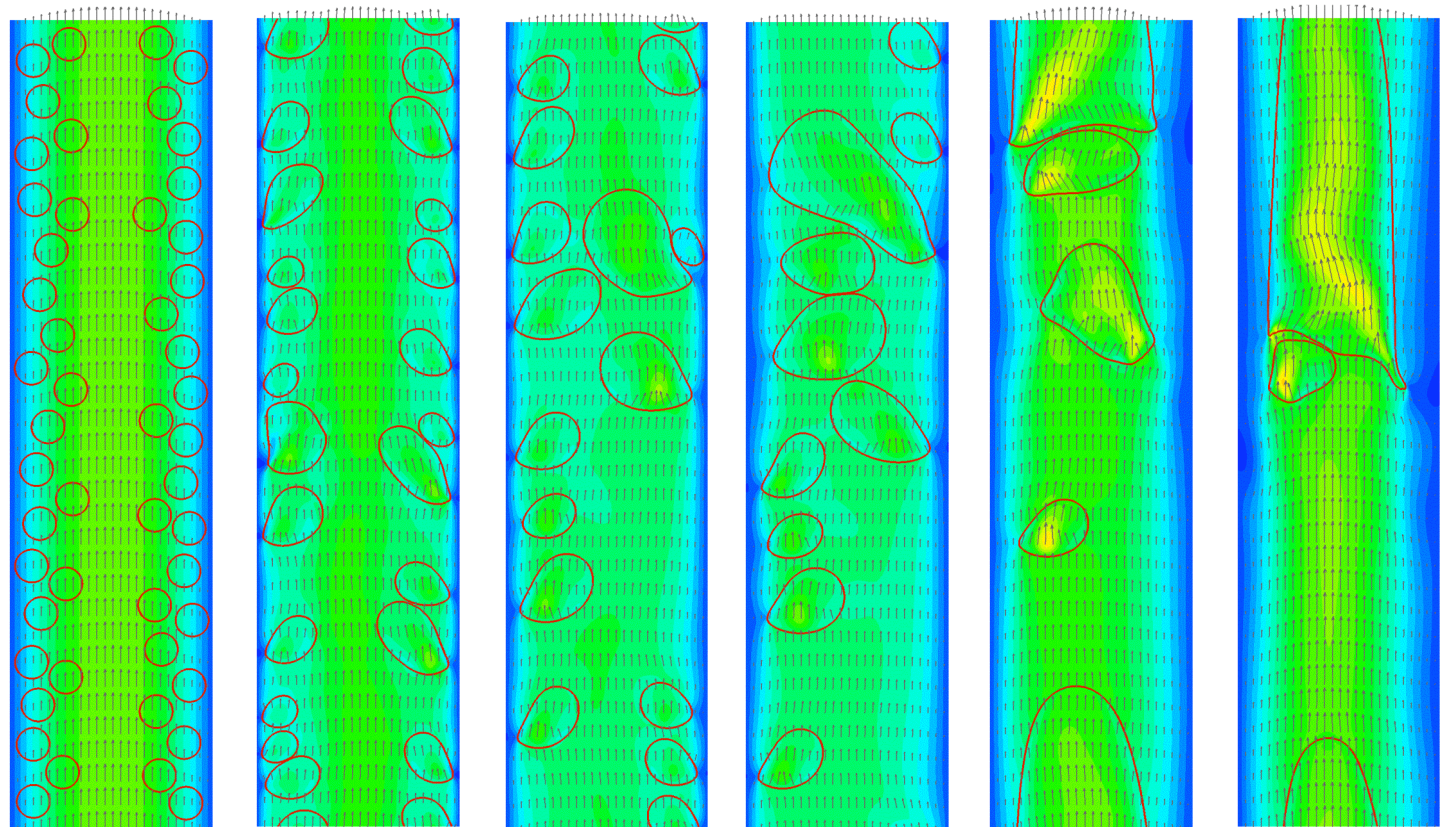
High bubble concentration at the walls is likely to lead to bubble collisions and coalescence. The collision of small and nearly spherical bubbles—which hug the wall—to form large deformable bubbles—that are repelled by the wall—is likely to be one of the major mechanism responsible for changing the void fraction distribution from “wall-peak” to a maximum in the core. The figure shows a simulation of the collision of two nearly spherical bubbles and the evolution of the resulting large bubble.



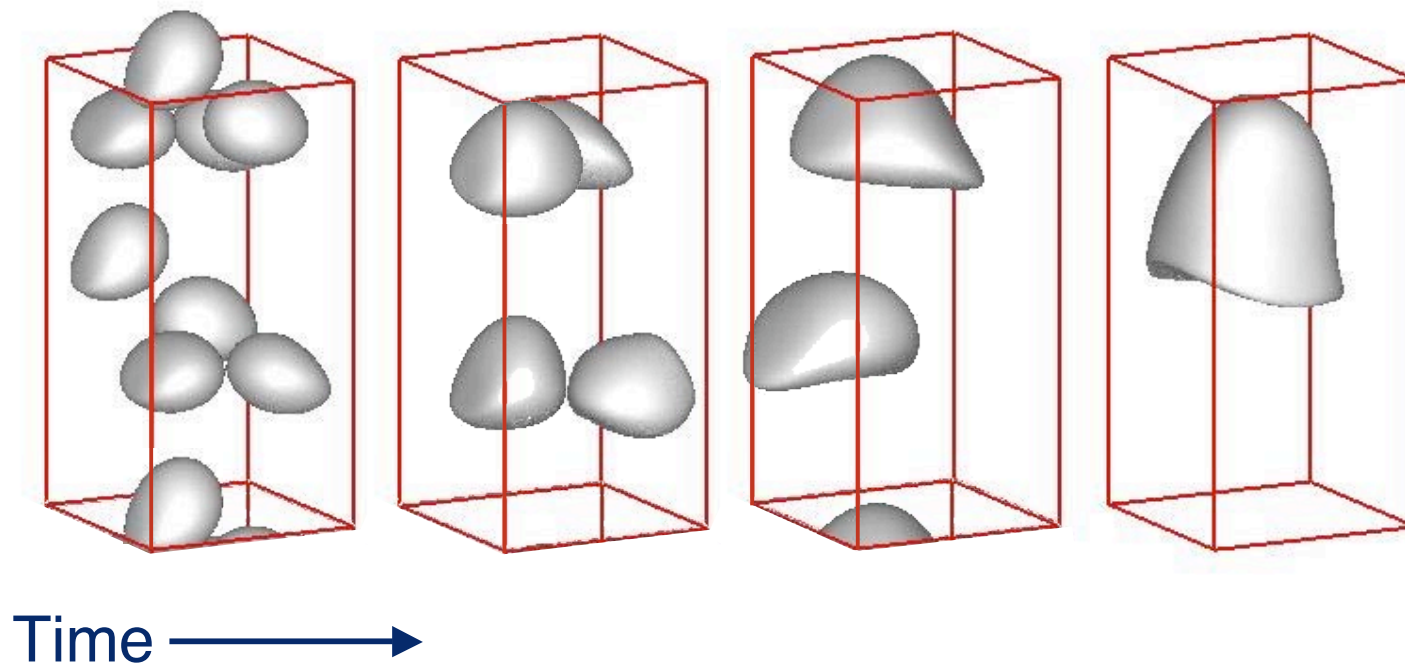
Moving Interface Problems—Complex Flows

Flow regime changes

Coalescence induced flow regime transitions in a laminar bubbly channel flow: The figure shows a preliminary two-dimensional simulation of the transition from a wall peaked distribution of many bubbles to a single large slug in the channels center.

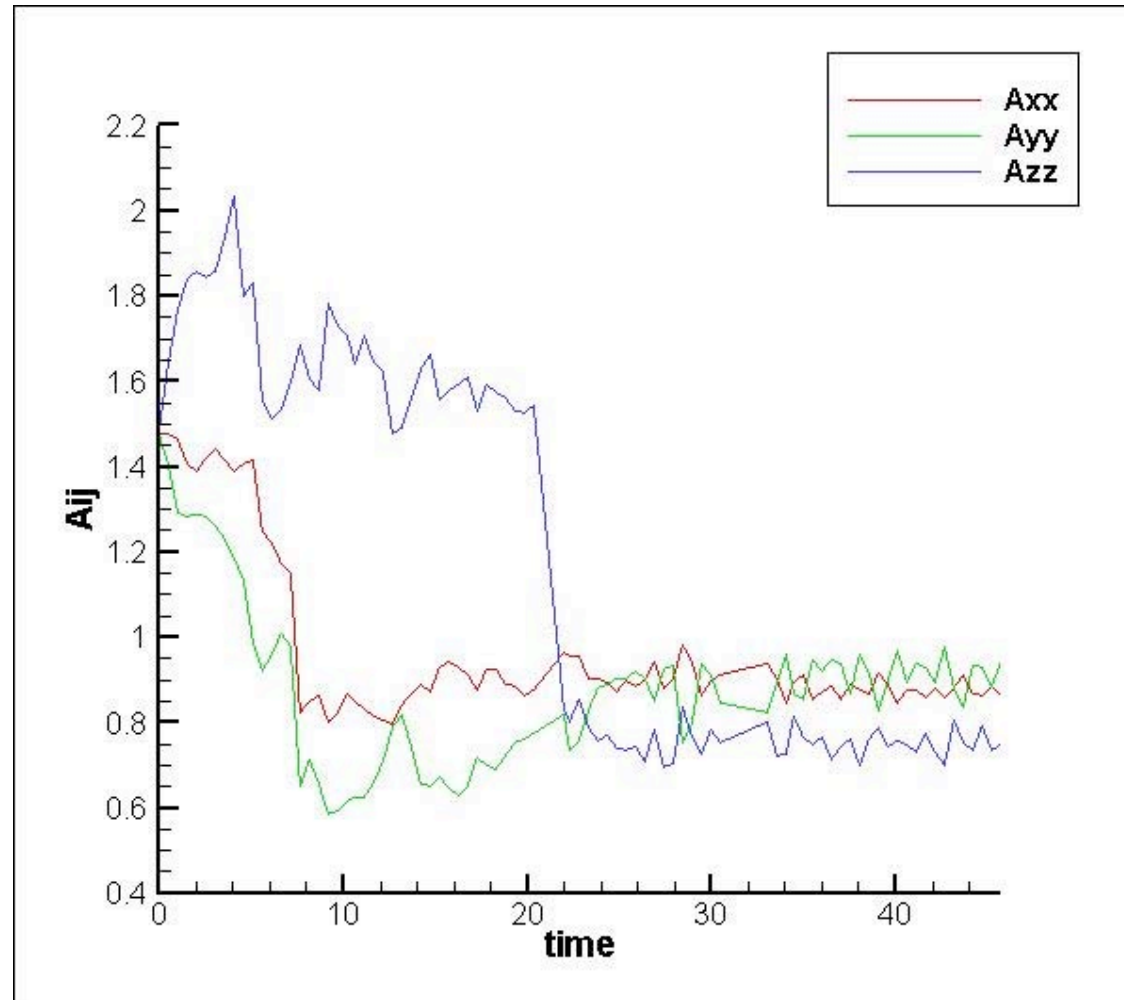


A simulation of a coalescence induced regime transition in a small three-dimensional system



The
components of
the interface
area tensor
versus time

$$\frac{1}{Vol} \int_s \mathbf{nn} da$$





Atomization and droplet breakup

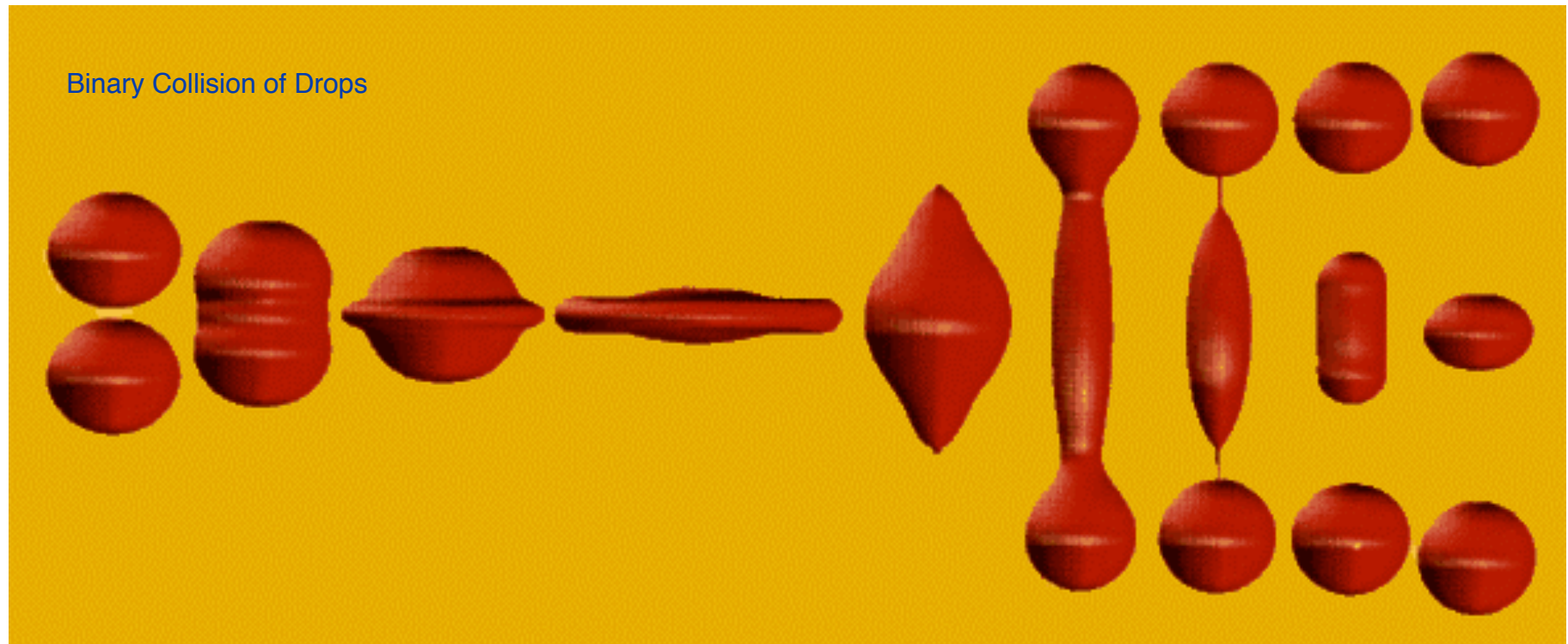


Moving Interface Problems—Complex Flows

In general, the interface separating two fluids will undergo topology changes where two regions of one fluid coalesce, or one region breaks in two. Of those, the coalescence problem appears to be the harder one.

In their simplest implementation, explicit tracking methods never allow coalescence and methods based on a marker function always coalesce two interfaces that are close.

In reality, films between two fluid interfaces take a finite time to drain and rupture only when the thickness is sufficiently small so the film is unstable to non-continuum attractive forces. In general this draining cannot be resolved and must be modeled.



References:

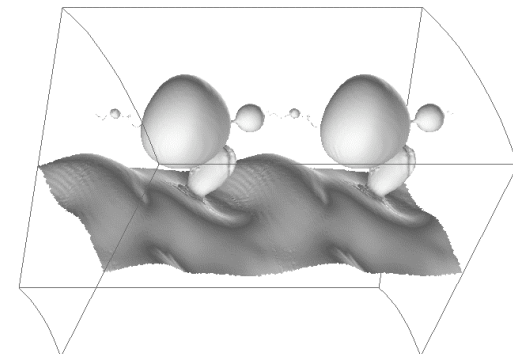
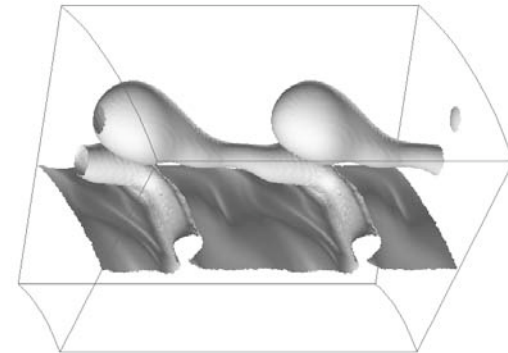
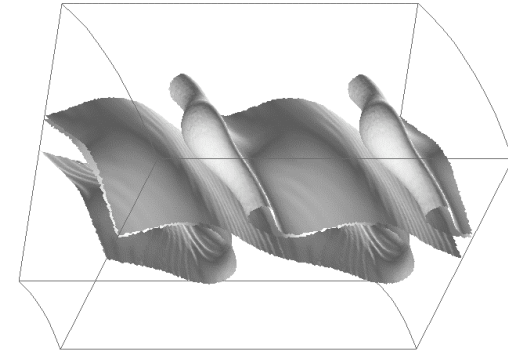
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- M.R.H. Nobari, and G. Tryggvason, "Numerical Simulations of Three-Dimensional Drop Collisions." *AIAA Journal* 34 (1996), 750-755.
- J. Qian, G. Tryggvason, and C.K. Law. An Experimental and Computational Study of Bouncing and Deforming Droplet Collision. Submitted to *Phys. Fluids*



Moving Interface Problems—Complex Flows

Primary breakup of jets

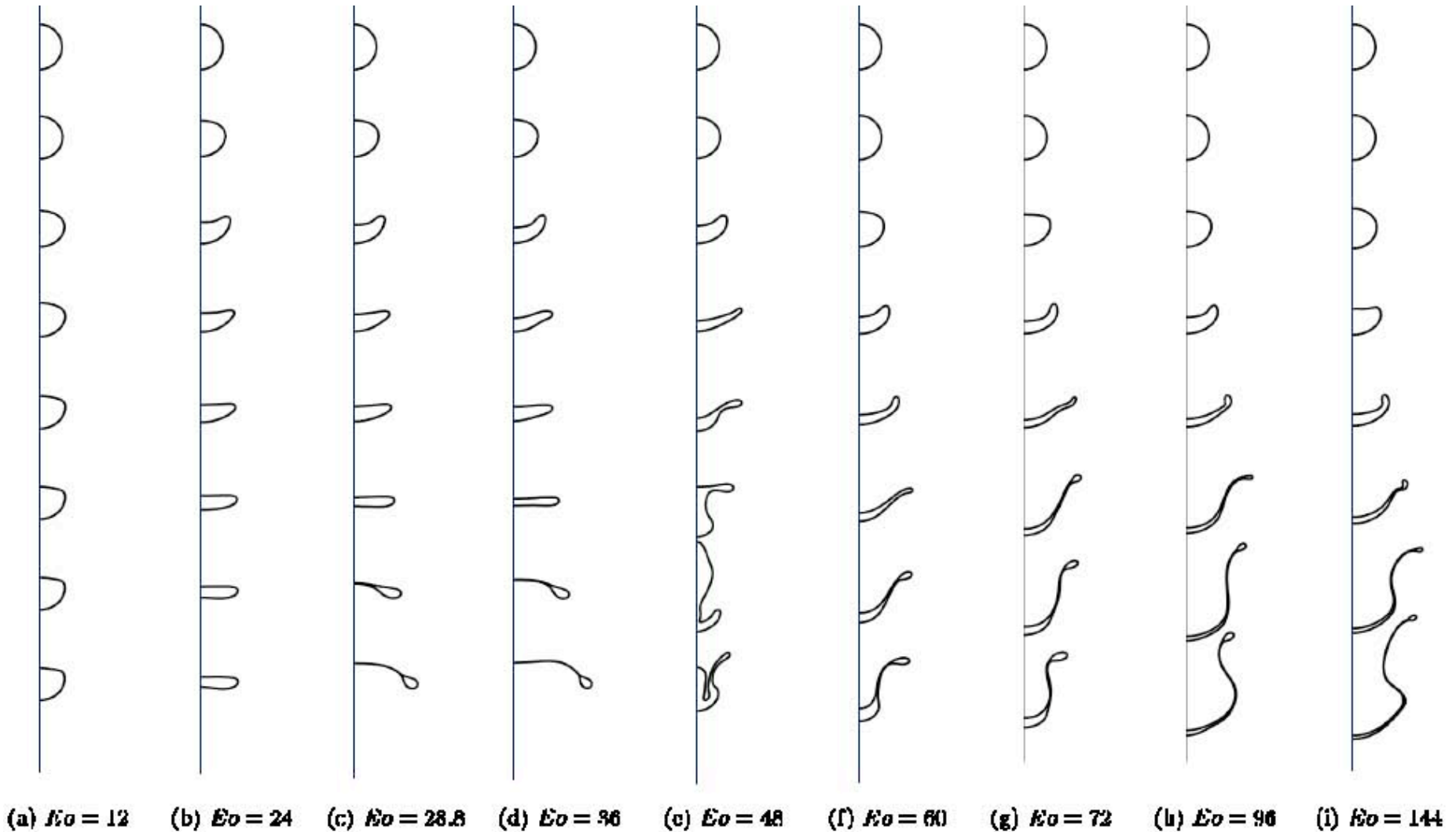
Three frames from a simulation of the three-dimensional breakup of a jet. The initial two-dimensional fold becomes unstable and generates fingers that eventually break into drops. Here, $Re=1000$, $We=5$, and the density ratio is 10. The simulation is done using 72 by 48 by 38 unevenly spaced grid points in the radial, axial, and azimuthal direction, respectively.





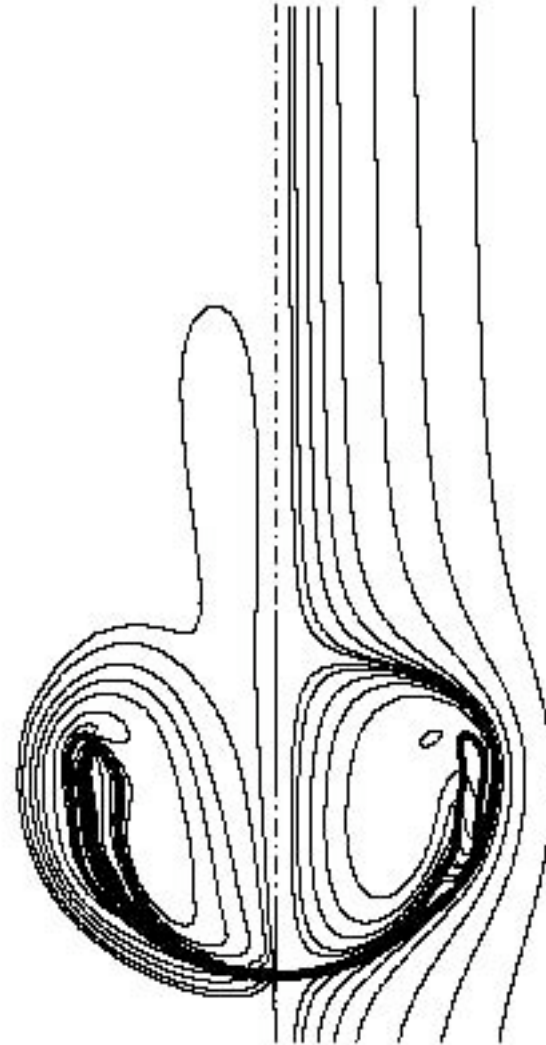
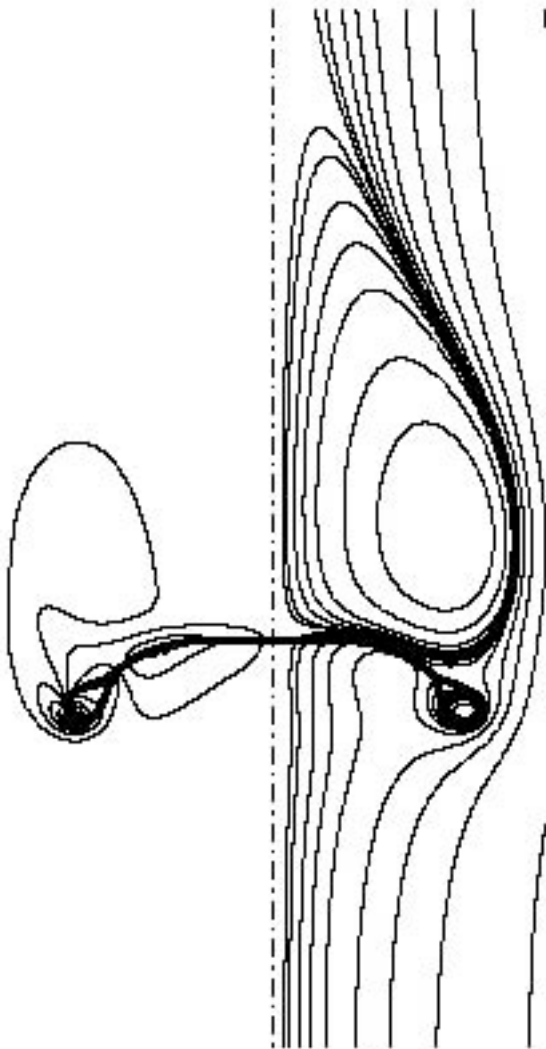
Moving Interface Problems—Complex Flows

Secondary breakup of drops



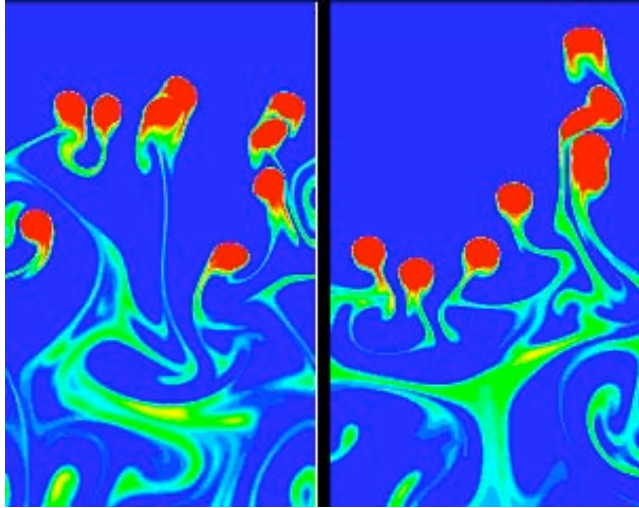
Moving Interface Problems—Complex Flows

Secondary breakup of drops

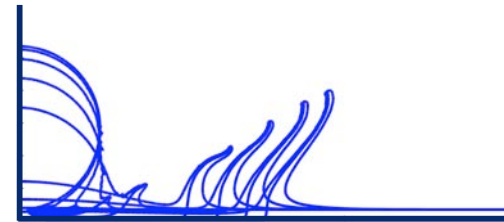


Moving Interface Problems—Complex Flows DNS of Multiphase Systems

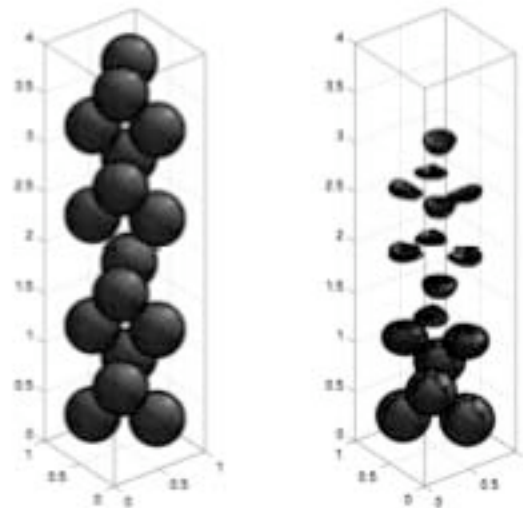
Mass transfer & chemical reactions



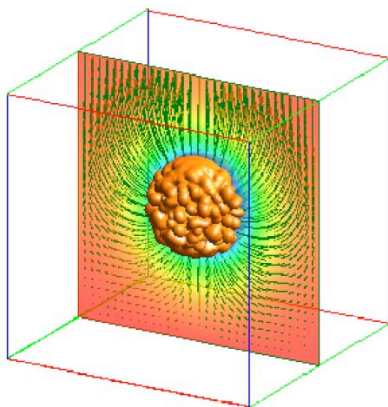
Splatting drops



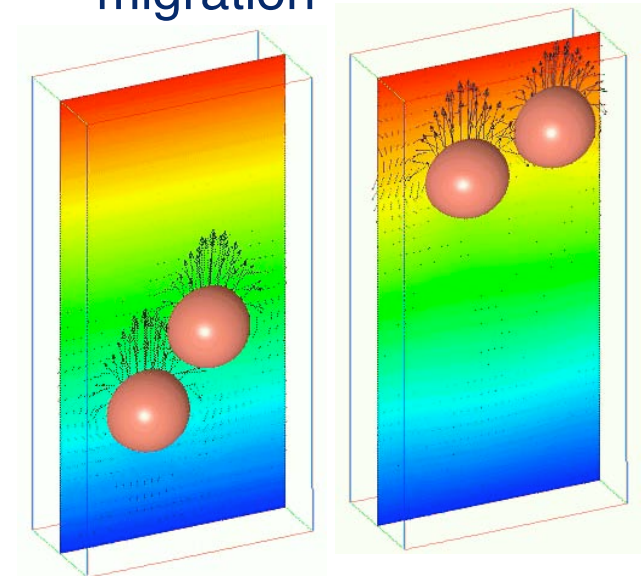
Shocks in
bubbly flows



Explosive
Boiling



Thermocapillary
migration





Moving Interface Problems—Complex Flows Summary

- Multifluid simulations of relatively simple systems are well under control and can be used to understand such systems.
- Large scale three-dimensional simulations are emerging. The challenge is to use the results to produce engineering/scientific knowledge.
- Methods for multiphase flows are in their infancy.

System size:

<1980: Mostly two-dimensional systems

1980: early three-dimensional studies

1990: less than 100^3 grid points

2006 > 1000^3 grid points + new computational techniques