

## Estimating Conditional Moments of a Survival Curve from Interval-Censored Data

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## Outline

1. A willingness-to-pay (WTP) experiment
2. Conditional survival curves
3. Interval-censored data and examples
4. Survival models and specializations
5. Regularity and design assumptions
6. Nonparametric estimators
7. Semiparametric estimators
8. Monte Carlo evidence
9. Application

## Willingness to Pay for Seabirds

Green, Jakowitz, Kahneman, McFadden (1997)

What value would your household place on saving about 50,000 seabirds each year from offshore oil spills?

- Several million seabirds live out of sight off Pacific coast
- Small oil spills kill estimated 50,000+ seabirds per year
- Usually not possible to force tanker companies to pay
- Public money would have to be spent yearly to save the birds, extra funds required

## Contingent Valuation Experimental Design

- Control subjects asked open-ended WTP
- In what is termed referendum format, treatment subjects were asked if  $WTP \geq v$ , where bid  $v$  was set by experimental design
- In the GJKM study, bids were set at quantiles of the controls' WTP distribution
- Questions:
  - What are median and mean WTP?
  - Does the format (open-ended vs. referendum) matter?

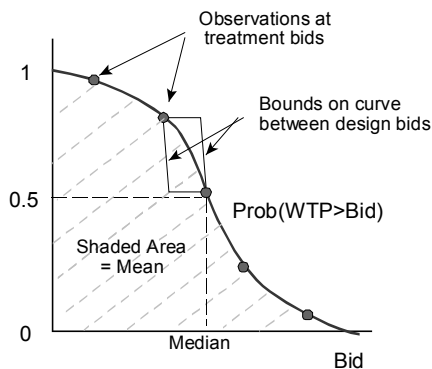
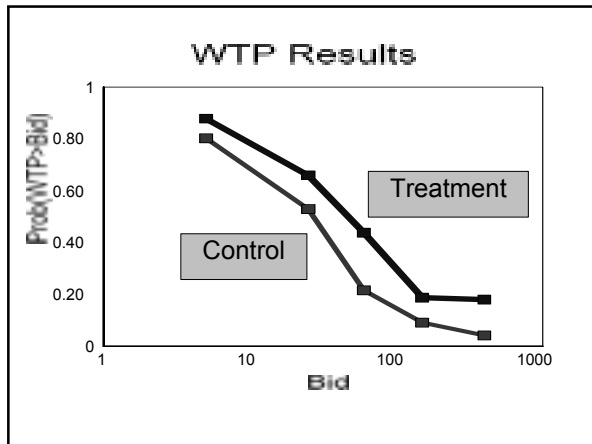


Table 1. Willingness-to-Pay to Save 50,000 Off-Shore Seabirds per Year

Distribution	Open-Ended		Starting Point Bid			
		\$5	\$25	\$60	\$150	\$400
\$0-4.99	19.8%	12.2%	8.5%	0.0%	8.3%	12.0%
\$5-24.99	27.3%	67.4%	25.5%	41.7%	29.2%	22.0%
\$25-59.99	31.4%	12.2%	53.2%	14.6%	27.1%	20.0%
\$60-149.99	12.4%	8.2%	8.5%	41.7%	16.7%	18.0%
\$150-399.99	5.0%	0.0%	2.1%	2.1%	18.8%	10.0%
\$400+	4.1%	0.0%	2.1%	0.0%	0.0%	18.1%
Sample size	121	49	47	48	48	50
P(Open-Ended Response > Bid) (Std. Error)	80.2%	52.9%	21.5%	9.1%	4.1%	2.8%
P(Anchored Response > Bid) (Std. Error)	87.8%	66.0%	43.8%	18.8%	18.0%	5.4%
Median Response (Std. Error)	\$25.00 \$6.03	\$10.00 \$2.33	\$25.00 \$1.16	\$25.00 \$14.04	\$43.00 \$10.87	\$50.00 \$23.41
Mean Response (a) (Std. Error)	\$64.25 \$13.22	\$20.30 \$3.64	\$45.43 \$12.61	\$49.42 \$6.51	\$60.23 \$8.59	\$143.12 \$28.28
		Coefficient	Std. Error			
Marginal effect of starting point bid		0.284	0.32			
K-J Interquartile Anchoring Index		0.273	0.136			
Nonparametric referendum mean (b)		\$167.33	\$73.90			
Referendum multiplier		2.60	1.31			
Parametric referendum mean		\$265.59	\$138.96			
Referendum multiplier		4.13	2.32			

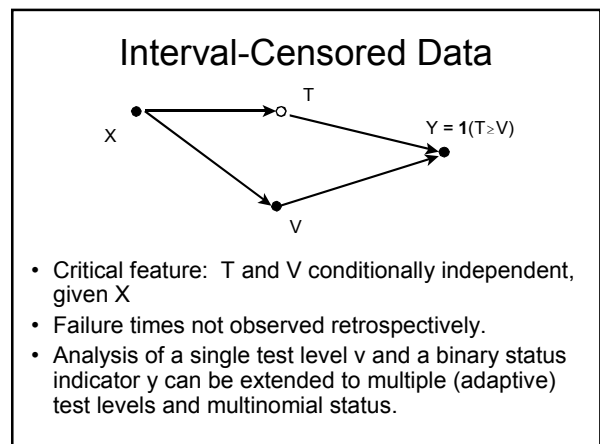


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  - 2. Conditional survival curves**
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- ### Survival Curves
- Let  $T$  denote a random failure time, and  $G(t|x) = \text{Prob}(T \geq t|x)$ ,  $t \geq 0$ , denote the survival curve conditioned on a  $d$ -vector of (time-invariant) covariates  $x$ .
  - In most applications,  $t$  is time. Alternately:
    - $t$  is the administered dose of a toxin,  $T$  is lethal dose, and  $G$  is the dose-response curve
    - $t$  is a bid in referendum Contingent Valuation and  $T$  is the subject's Willingness-to-Pay (WTP).

- ### Survival Data
- Survival analysis often assumes a size  $N$  sample of i.i.d. observations  $(x_n, t_n)$ , where  $x_n$  is a  $d$ -vector of covariates and  $t_n$  is completed (or censored) duration.
  - Some applications provide interval-censored data:  $T_n$  is latent and one observes  $(x_n, v_n, y_n)$ , where  $v_n$  is a test level in the  $t$  dimension set by experimental design, and independent of  $T_n$  given  $x_n$ .  $y_n = \mathbf{1}(T_n \geq v_n)$  is a binary indicator for the event  $T_n \geq v_n$ . The conditional mean of  $y_n$  given  $x_n$  is  $G(v_n|x_n)$ .

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## Interval-Censored Data Examples

- Animal experiments: At time  $v$ , the animal is sacrificed,  $y$  is one iff abnormality is present
- Materials Testing: At treatment level  $v$ ,  $y$  is one iff material meets requirement; e.g., crash test at speed  $v$ .
- Dose-Response: At treatment level/dose  $v$ ,  $y$  is one iff lethal dose exceeds  $v$ .
  - Referendum contingent valuation has the dose-response form, testing if willingness-to-pay (WTP) exceeds a bid  $v$ .

## Longitudinal Interval-Censored Data

- Panels with periodic waves yield interval-censored data if retrospective data on  $T$  is unavailable or unreliable when failure occurs between waves.
- Statistical issue: If  $x$  is not time-invariant, then even if  $x(s)$ ,  $0 \leq s \leq t$ , is predetermined for  $T$  given  $T \geq t$ , intra-wave feedbacks may nevertheless make  $x(v)$  endogenous.
- Statistical issue: If the failure time  $T$  interacts with interview scheduling, then the inter-wave duration ( $v$ ) becomes endogenous, biasing conditional hazard rate estimates.
  - Measured hazard rates in the Health and Retirement Study depend on interview timing within a wave

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## Alternative Formulation of Survival Model

- If  $T = \exp(m^*(x, \eta))$ , with  $m^*$  decreasing in a disturbance  $\eta$  that has a continuous CDF  $F(\cdot|x)$ , then  $G(t|x) = F(M^*(x, \log t)|x)$ , where  $M^*$  is the inverse of  $m^*$  in its 2<sup>nd</sup> argument.
- Normalization: Define  $\xi = F(\eta|x)$  and  $T = \exp(m(x, \xi)) \equiv \exp(m^*(x, F^{-1}(\xi|x)))$ . Then  $\xi$  is uniform  $[0, 1]$  and  $G(t|x) = M(x, \log t)$ , where  $M$  is the inverse of  $m$  in its 2<sup>nd</sup> argument.

## Specializations

- $T = \Lambda(m(x, \theta_0) - \eta)$   
 $\rightarrow G(t|x) = F(m(x, \theta_0) - \Lambda^{-1}(t)|x)$   
 a semiparametric model when  $F$ ,  $\theta_0$  unknown,  $m$ ,  $\Lambda$  known  
 –  $T = \exp(m(x, \theta_0) - \eta) \rightarrow G(t|x) = F(m(x, \theta_0) - \log t|x)$
- $T = \exp(x \cdot \theta_0 - \eta) \rightarrow G(t|x) = F(x \cdot \theta_0 - \log t|x)$   
 – Type 1 extreme value  $F(\eta) = \exp(-\exp(-\alpha\eta))$  gives the parametric Weibull proportional hazards model,  
 $G(t|x) = \exp(-t^\alpha \exp(-x \cdot \theta_0 \alpha))$

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## Assumptions to set the problem

- **A.1.** Covariate vectors  $x$  are distributed in the population with a CDF  $H_x$  that has a compact support in a  $d$ -dimensional space. The survival curve  $G$  has a continuously differentiable positive density  $g(t|x)$  with a compact support.
- **A.2.** The generalized moment function  $r(t,x)$  is continuous in  $(t,x)$ , and for each  $x$  is twice continuously differentiable in  $t$ .

## Experimental Design Assumption

- **A.3.** There is an asymptotic distribution  $H(v,x) = \int_{w \leq v} \int_{z \leq x} h(w|z) dw H_x(dz)$  of the treatments and covariates, where  $h(t|x)$  is a continuous density that for each  $x$  is strictly positive on a compact interval containing the support of  $G(t|x)$ . The experimental design is described by an empirical CDF  $H_N(v,x)$  such that  $N^{1/2}[H_N(v,x) - H(v,x)]$  converges weakly to a Gaussian process.
- For some nonparametric estimators, a rate less than  $N^{1/2}$  suffices and Gaussianity is not required
- A.3 implies  $\sup_{v,x} |H_N(v,x) - H(v,x)| \rightarrow 0$  a.s.

## Experimental Design Examples

- $H_N(v,x)$  is a random sample from  $H(v,x)$ .
  - A.3 holds by Shorack-Wellner on convergence of triangular arrays of empirical processes, and a.s. convergence holds by Glivenko-Cantelli.
- At  $N$ ,  $x_n$  is sampled randomly from  $H_x$ . A fixed design for  $v$  with  $J_N$  possible values of  $v$  is selected.  $v_n$  is drawn randomly from a density  $h_N(v|x)$  on this finite support that for each  $x$  converges weakly to a positive continuous density  $h(v|x)$ .
  - Sufficient:  $J_N/N^{1/2} \rightarrow \infty$ , max gap of order  $1/J_N$ , and CDF's of  $h_N$  and  $h$  coinciding at design points

## Inference Problems

- Survival curve features of interest are moments, quantiles, and percentiles (unconditional, or conditional on  $x$ ).
- The generalized moment problem to estimate  $\mu(x) = E_{T|x}r(T,x)$ , for a  $C^2$  function  $r(t,x)$  approximates many cases of interest.
- The estimation problem is semiparametric when unknown  $G$  depends on  $x$  through a known function  $m(x, \theta_0)$  of an unknown parameter vector  $\theta_0$ ; e.g., the index  $x \cdot \theta_0$ .

## Mathematical elements

- $\int r(v)G(dv) = r(0) + \int r'(v)G(v)dv$
- If  $Z$  is an importance random variable with a positive density  $q$  on the support of  $G$ , then
 
$$\int r'(v)G(v)dv = \int [r'(z)G(z)/q(z)]q(z)dz = E_Z r'(Z)G(Z)/q(Z)$$
- If  $V$  is a design random variable with a positive density  $h$  on the support of  $G$ , and  $Y$  is a status indicator with  $E_{Y|V} Y = G(V)$ , then
 
$$\int r'(v)G(v)dv = E_V r'(V)G(V)/h(V) = E_{V,Y} r'(V)Y/h(V)$$

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## Estimating $\mu(x) = \mathbf{E}_{T|x} r(T, x)$ ,

- $Y = \mathbf{1}(T \geq v)$  satisfies  $G(v|x) = \mathbf{E}_{Y|v,x} Y$ .
- Plug estimate  $\hat{G}^*(t|x)$  into  $\mu(x) = \int_{t \geq 0} r(t, x) G(dt|x)$  to get an estimator  $\hat{\mu}_0(x)$
- Parametric problem is standard.
- In semiparametric or nonparametric problem
  - The curse of dimensionality applies -- undersmooth  $\hat{G}^*$  to get a best rate for  $\mu(x)$ .
  - For practical estimation of  $\mu(x)$ , avoid explicit computation of  $\hat{G}^*$  if possible

## Estimators

Uncon- ditional	Con- ditional	Known	Unknown
$\hat{\mu}_0$	$\hat{\mu}_0^*(x)$	$H(v x)$	$G(t x)$
$\hat{\mu}_1$	$\hat{\mu}_1^*(x)$	$H(v x)$	$G(t x)$
$\hat{\mu}_2$	$\hat{\mu}_2^*(x)$	---	$H(v x), G(t x)$
$\theta^*$	---	$m, \Lambda$	$F(\eta), \theta_0$
$\hat{\mu}_3$	$\hat{\mu}_3^*(x)$	$H(v x), m, \Lambda$	$F(\eta)$
$\hat{\mu}_4$	$\hat{\mu}_4^*(x)$	$m, \Lambda$	$H(v x), F(\eta)$
$\hat{\mu}_5$	$\hat{\mu}_5^*(x)$	$H(v x), m, \Lambda$	$F(\eta)$

Estimators  $\hat{\mu}_j^*$  are nonparametric for  $j \leq 2$ , semiparametric for  $j > 2$ .  
Estimator  $\hat{\mu}_5^*$  requires moment  $r(t, x) = [\Lambda(t)^{-1}]^k$ ,  $k$  a positive integer.

## Estimator descriptions

- Nonparametric
  - $\hat{\mu}_0^*(x)$  plug-in estimator
  - $\hat{\mu}_1^*(x)$  ragged integrand, design density
  - $\hat{\mu}_2^*(x)$  smooth integrand, any importance density
- Semiparametric
  - $\theta^*$  nonlinear least squares
  - $\hat{\mu}_3^*(x)$  ragged integrand, design density
  - $\hat{\mu}_4^*(x)$  smooth integrand, uniform importance
  - $\hat{\mu}_5^*(x)$  special ragged integrand, design density

## Integration-by-parts formulation of $\mu(x)$

- Notation:  $r'(t, x) = \partial r(t, x) / \partial t$
- Define  $s(x, v, y) = yr'(v, x) / h(v|x)$   

$$\tau(x, v) = G(v|x)r'(v, x) / h(v|x) = \mathbf{E}_{Y|x} s(x, v, Y)$$
- Integrating by parts,  

$$\begin{aligned} \mu(x) &= \int_{t \geq 0} r(t, x) g(t|x) dt = r(0, x) + \int_{t \geq 0} G(t|x) r'(t, x) dt \\ &= r(0, x) + \int_{v \geq 0} \tau(x, v) H(dv|x) \\ &= r(0, x) + \mathbf{E}_{v|x} \tau(x, v) && \text{smooth} \\ &= r(0, x) + \mathbf{E}_{Y, v|x} s(x, v, Y) && \text{ragged} \end{aligned}$$

## Example: Unconditional Moment Estimator McFadden (1994), Lewbel (1997)

- Target:  $\mu = \mathbf{E}_X \mu(X)$   

$$= \mathbf{E}_X r(0, X) + \mathbf{E}_{Y, v, X} s(X, v, Y)$$
- Estimate  $\mu$  by a sample average

$$\hat{\mu}_1 = N^{-1} \sum_{n \leq N} \{r(0, x_n) + s(x_n, v_n, y_n)\}$$

- Assumptions 1-3 imply  $\hat{\mu}_1$  is root-N CAN (elementary)
- If  $x_n, v_n$  are sampled from  $H(v, x)$ ,  $\hat{\mu}_1$  is unbiased

## Estimators $\hat{\mu}_0^*(x)$ and $\hat{\mu}_1^*(x)$

- Nonparametric estimator  $\hat{G}^*(v|x)$  from, say, nearest neighbor regression of  $Y$  on  $v, x$ , is plugged into formula for  $\mu(x)$  to get  $\hat{\mu}_0^*(x)$ . Estimator will have an IRMSE determined by  $\hat{G}^*(v|x)$ .
- Let  $K_b(\cdot)$  denote a kernel of dimension  $d$  with bandwidth  $b$ . For each  $x$ , regress  

$$s(x_n, v_n, y_n) = \alpha_0(x) + (x_n - x)\alpha(x),$$
 weighting the observations by  $K_b(x - x_n)^{1/2}$ .  

$$\hat{\mu}_1^*(x) = r(0, x) + \alpha_0(x)$$
- The large sample properties of  $\hat{\mu}_1^*(x)$  are those of the local regression estimator of  $\alpha_0(x)$

## Estimator $\mu^{\wedge}_2(x)$

- Base estimator on smooth integrand

$$\mu(x) = r(0,x) + \mathbf{E}_{V|x} \tau(x,V)$$

- Replace  $G(v|x)$  by a local linear smooth of  $Y$
- Replace  $h(v|x)$  by a uniform importance density

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## Semiparametric problem

- **A.4.** Assume

$$T = \Lambda(m(x, \theta_0) - \eta)$$

$$\rightarrow G(t|x) = F(m(x, \theta_0) - \Lambda^{-1}(t)|x)$$

with  $F$  and  $\theta_0$  unknown,  $\Lambda$  and  $m$  known,  $\Lambda$  invertible and continuously differentiable,  $F$  a  $C^2$  CDF independent of  $x$  with compact support containing 0

- $\mathbf{E}_{T|x} \Lambda^{-1}(T) = \alpha_0 + m(x, \theta_0)$ , with  $\alpha_0 = -\mathbf{E} \eta$
- Targets: The finite parameter vector  $\theta_0$  and the generalized conditional moment  $\mu(x)$

## Definitions

(location-adjusted design)

- $U = m(x, \theta_0) - \Lambda^{-1}(V)$  and  $u_n = m(x_n, \theta_0) - \Lambda^{-1}(v_n)$
- $\Psi_N(u)$  empirical CDF of  $U$ , with weak limit  $\Psi(u)$  that has a positive continuous density  $\psi$  on a support that contains the support of  $G$ 
  - This property of  $\Psi_N(u)$  follows from A.3., but may hold without A.3. if some components of  $x$  are continuously distributed
- $s^*(x, u, y) = r'(\Lambda(m(x, \theta_0) - u), x) \Lambda'(m(x, \theta_0) - u) \cdot (y-1(u>0))/\psi(u)$
- $\tau^*(x, u) = \mathbf{E}_{Y|x} s^*(x, u, Y)$

## Corollary 1

If A1-A4, then

$$\mathbf{E}_{Y|u} Y = F(u)$$

$$\mu(x) = r(\Lambda(m(x, \theta_0)), x) + \int s^*(x, u) \psi(du)$$

$$\psi_N(u) = N^{-1} \sum_{n \leq N} h(\Lambda(m(x_n, \theta_0) - u) | x_n - u | x_n) \cdot \Lambda'(m(x_n, \theta_0) - u) \rightarrow \psi(u)$$

## Estimator $\theta^{\wedge}$

- Define  $s^{\#}(x, v, y) = y(d\Lambda^{-1}(v)/dv)/h(v|x)$
- $\Lambda^{-1}(0) + \mathbf{E}_{Y, V|x} s^{\#}(x, v, y) = \alpha_0 + m(x, \theta_0)$
- A nonlinear regression of  $s^{\#}(x_n, v_n, y_n)$  on  $\alpha_0 + m(x_n, \theta)$  provides a root-N CAN estimator of  $\theta_0$  if identification conditions are met

### Estimator $\mu^{\wedge}_3(x)$

- When  $\theta_0$  is known:  
Replace  $\psi(u)$  by  $\psi_N(u)$  in  $s^*(x,u,y)$   
 $\mu^{\wedge}_3(x) = r(\Lambda(m(x,\theta_0)),x) + N^{-1} \sum_{n \leq N} s^*(x,u_n,y_n)$
- When  $\theta_0$  is unknown, plug the estimator  $\theta^{\wedge}$  into the definition of  $U$  and the formula  $\mu^{\wedge}_3(x)$
- Theorem 3. The estimator  $\mu^{\wedge}_3(x)$ , with  $\theta_0$  either known or replaced by the plug in estimator  $\theta^{\wedge}$ , is root-N CAN

### Estimator $\mu^{\wedge}_4(x)$

- When  $\theta_0$  is known:  
Form a kernel estimator  $\psi^-_N(u)$  from the empirical density at the points  $u_n = m(x_n, \theta_0) - \Lambda^{-1}(v_n)$ .  
Replace  $\psi(u)$  by  $\psi^-_N(u)$  in  $s^*(x,u,y)$ ,  
$$\mu^{\wedge}_4(x) = r(\Lambda(m(x,\theta_0)),x) + N^{-1} \sum_{n \leq N} s^*(x,u_n,y_n)$$
- When  $\theta_0$  is unknown, plug the estimator  $\theta^{\wedge}$  into the definition of  $U$  and the formula  $\mu^{\wedge}_4(x)$
- Theorem 4. The estimator  $\mu^{\wedge}_4(x)$ , with  $\theta_0$  either known or replaced by the plug in estimator  $\theta^{\wedge}$ , is root-N CAN

### Estimator $\mu^{\wedge}_5(x)$

- $r(v,x) = [\Lambda^{-1}(v)]^k$ ,  $k$  a positive integer
- $E_{T|x} [\Lambda^{-1}(T)]^k = E_{T|x} [m(x,\theta_0) - \eta]^k$   
 $= \sum_{j \leq k} (-1)^j {}_n C_j m(x,\theta_0)^{k-j} E_{\eta} \eta^j$   
 $= \sum_{j \leq k} m(x,\theta_0)^j \alpha_j$
- Regress  $s(x,v,y)$ , defined for this special  $r$ , on  $m(x,\theta_0)^j$  for  $j \leq k$  to estimate the  $\alpha_j$ , and plug these into the formula above.

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### Monte Carlo Study

- $\log T = \beta_1 + \beta_2 X - \sigma \eta$
- $X$  uniformly distributed on  $[-30,30]$
- $\eta$  standard normal
- $\beta_1 = 100, \beta_2 = 2$
- Treatments:
  - 5-bid design at  $\{25, 50, 75, 125, 175\}$
  - Continuous design uniform on  $[25,175]$
- Bandwidths chosen using Silverman's thumb
- 10,000 repetitions

Table 1. Conditional Mean in 5-bid design, 10,000 repetitions

		$\sigma = 5$		
		$n=100$	$n=300$	$n=500$
IRMSE	$\hat{\mu}_1$	14.56	12.63	12.21
	$\hat{\mu}_3$	17.59	16.04	15.74
	$\hat{\mu}_4$	12.74	10.41	9.89
	$\hat{\mu}_5$	11.74	10.33	10.02
	IMAE	$\hat{\mu}_1$	10.96	10.16
$\hat{\mu}_3$		14.42	13.36	13.13
$\hat{\mu}_4$		10.08	8.50	8.22
$\hat{\mu}_5$		9.23	8.44	8.31

Table 3. Conditional Mean in continuous design, 10,000 repetitions

		$\sigma = 5$		
		n=100	n=300	n=500
IRMSE	$\hat{\mu}_1$	12.30	7.54	6.02
	$\hat{\mu}_3$	12.65	8.05	6.98
	$\hat{\mu}_4$	9.22	5.12	3.93
	$\hat{\mu}_5$	8.91	5.13	4.00
IMAE	$\hat{\mu}_1$	8.81	5.41	4.33
	$\hat{\mu}_3$	9.99	6.46	5.70
	$\hat{\mu}_4$	7.14	3.95	3.02
	$\hat{\mu}_5$	6.87	3.97	3.08

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- ### Application
- WTP to protect California wetlands
  - “Double Referendum” contingent valuation format: first bid drawn from design, second bid half if “No”, double if “Yes”
  - Covariates: Age, years in California, education, income bracket, sex, race, membership in environmental organization
  - N = 530
  - 14 bid levels total (number of first bid levels = ?)
  - Data collected by Hanemann *et al*
  - Model:  $\log T = x \cdot \theta - \eta$

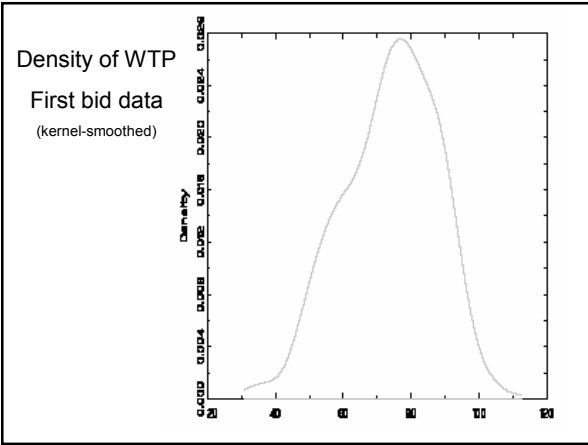


Table 5. Estimates Of Mean WTP

	Log Linear	
	bid1	bid2
$\hat{\mu}_3$	62.0320 (4.4683)	306.0211 (411.4603)
$\hat{\mu}_3(\bar{X})$	61.5918 (4.2751)	302.4752 (328.7766)
$\hat{\mu}_4$	64.6992 (5.0823)	369.2809 (394.6291)
$\hat{\mu}_4(\bar{X})$	63.7869 (4.4995)	472.5140 (328.2098)
$\hat{\mu}_5$	99.1164 (4.1348)	141.5369 (9.0742)
$\hat{\mu}_5(\bar{X})$	98.7726 (6.6526)	134.0196 (21.4996)

Table 6

	Log Linear	
	bid1	bid2
YEARCA	0.0021 (0.0022)	0.0131 (0.0062*)
SEX	-0.0460 (0.0632)	0.2579 (0.1740)
ln(AGE)	-0.2040 (0.1088)	-0.4801 (0.2563)
EDUC	0.0119 (0.0154)	0.0307 (0.0404)
WHITE	0.1338 (0.0797)	0.2164 (0.2173)
ENVORG	-0.1085 (0.0792)	0.0946 (0.2331)
ln(INCOME)	0.0972 (0.0500*)	0.3796 (0.1474*)