

Unbiased inference for discretely observed hidden Markov model diffusions

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Bayesian computation for high-dimensional models

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Hidden Markov model diffusion

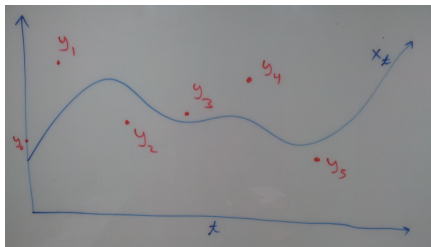
- Hidden process:

$$dX'_t = a_t^{(\theta)}(X'_t)dt + b_t^{(\theta)}(X'_t)dW_t.$$

- Observations:

$$Y'_t | (\theta, X'_t) \sim g_t^{(\theta)}(Y'_t | X'_t).$$

We set $(X_p, Y_p) := (X'_{t_p}, Y'_{t_p})$, consider observations at times $\{t_p\}_{p=0}^n$.



Goal

Bayesian inference over joint posterior

$$\begin{aligned}\pi^{(\infty)}(\theta, x_{0:n}) &\propto \text{pr}(\theta) p_u^{(\theta, \infty)}(x_{0:n}) \\ &= \text{pr}(\theta) L^{(\infty)}(\theta) p^{(\theta, \infty)}(x_{0:n}),\end{aligned}$$

with $\text{pr}(\theta)$ a prior density on model parameters, and

$$\begin{aligned}p^{(\theta, \infty)}(x_{0:n}) &= \mathbb{P}_\theta[X_{0:n} = x_{0:n} | Y_{0:n} = y_{0:n}] \\ &= \frac{1}{L^{(\infty)}(\theta)} \left(\prod_{p=0}^n \underbrace{G_p^{(\theta)}(x_p)}_{:= g_{t_p}^{(\theta)}(y_p | x_p)} \right) \underbrace{\eta_0^{(\theta)}(x_0)}_{\eta_0^{(\theta)} \in \text{Prob}(\mathbf{X})} \prod_{p=1}^n \underbrace{M_p^{(\theta, \infty)}(x_{p-1}, x_p)}_{\text{Markov kernel on } \mathbf{X}}.\end{aligned}$$

- Challenges for unbiased, efficient and user-friendly inference
 - $M_p^{(\theta, \infty)}$ can not be evaluated or simulated.
 - n may be large (and \mathbf{X} high-dimensional).
- Our approach:

Euler approximations + debiased MLMC + IS type correction.

Euler approximations

With $h_\ell = 2^{-\ell}$, $\ell \in \mathbb{N} \cup \{0\}$, new (approximate) hidden Markov chain

$$X'_{t+h_\ell}^{(\ell)} = X_t'^{(\ell)} + a_t'^{(\theta)}(X_t')h_\ell + b_t'^{(\theta)}(X_t')\underbrace{(W_{t+h_\ell} - W_t)}_{\sim \mathcal{N}(0, h_\ell)}$$

\rightsquigarrow (approximate) Markov transition

$$M_p^{(\theta, \ell)}(x_{p-1}, x_p).$$

\rightsquigarrow (approximate) latent probability

$$p^{(\theta, \ell)}(x_{0:n}).$$

\rightsquigarrow (approximate) joint inference over $\pi^{(\theta, \ell)}$ possible (many papers) using particle marginal Metropolis-Hastings (PMMH) (Andrieu, Doucet and Holenstein, “Particle MCMC” *JRSS-B* 2010).

Also: (Jasra, Kamatani, Law and Zhou, “Bayesian static parameter estimation...” *SIAM*, 2018).

Multilevel Monte Carlo via a coupling

MLMC approach used here: let $\phi : \mathbf{X}^{n+1} \rightarrow \mathbb{R}$ be a function.

- With $p_u^{(\theta, \ell)}(\phi) := L^{(\ell)}(\theta) p^{(\theta, \ell)}(\phi)$ approximate multilevel increment

$$p_u^{(\theta, \ell)}(\phi) - p_u^{(\theta, \ell-1)}(\phi)$$

of *unnormalised* latent probability expectations \rightsquigarrow “ Δ PF.”

Δ PF in turn based on “approximate coupling” approach, at the Feynman-Kac model level, of (Jasra, Kamatani, Law, and Zhou, “Bayesian static parameter estimation...” *SIAM*, 2018):

- With $\check{X}_p := (X_p^{(\ell)}, X_p^{(\ell-1)})$, set e.g.

$$\check{M}_p^{(\theta, \ell)}(\check{x}_{p-1}, \check{x}_p) := M_p^{(\theta, \ell)}(x_{p-1}^{(\ell)}, x_p^{(\ell)}) M_p^{(\theta, \ell-1)}(x_{p-1}^{(\ell-1)}, x_p^{(\ell-1)})$$

and set e.g.

$$\check{G}_p^{(\theta)}(\check{x}_p) = \frac{1}{2} \left(G_p^{(\theta)}(x_p^{(\ell)}) + G_p^{(\theta)}(x_p^{(\ell-1)}) \right).$$

- Then run standard particle filter (PF) for $(\check{M}_p, \check{G}_p)$.

Recall: particle filter for (M_p, G_p) with N particles

With $i \in \{1, \dots, N\}$, do:

- For $p = 0$, draw $X_0^{(i)} \sim \eta_0(\cdot)$.
Set $V_0^{(i)} := \frac{1}{N} G_0(X_0^{(i)})$ and $V_0^* := \sum_{i=1}^N V_0^{(i)}$.
- For $1 \leq p \leq n$, draw $X_p^{(i)} \sim \sum_{j=1}^N \frac{G_{p-1}(X_{p-1}^{(j)}) M_p(X_{p-1}^{(j)}, \cdot)}{\sum_{k=1}^N G_{p-1}(X_{p-1}^{(k)})}$.
Set $V_p^{(i)} := (V_{p-1}^*)^{-1} \frac{1}{N} G_p(X_p^{(i)})$ and $V_p^* := \sum_{i=1}^N V_p^{(i)}$.

Output: $(X_{0:n}^{(i)}, V_n^{(i)})_{i=1}^N$.

The PF output satisfies for $\phi : \mathbf{X}^{n+1} \rightarrow \mathbb{R}$ (θ is fixed),

$$\mathbb{E} \left[\sum_{i=1}^N V_n^{(i)} \phi(X_{0:n}^{(i)}) \right] = p_u^{(\theta)}(\phi) = L(\theta) p^{(\theta)}(\phi)$$

and

$$\mathbb{E}[V_n^*] = L(\theta).$$

The Δ PF for unnormalised level difference estimation

Δ PF algorithm is as follows:

1. Run the PF for $(\check{M}_p^{(\theta,\ell)}, \check{G}_p^{(\theta,\ell)})$, outputting $(\check{X}_{0:n}^{(i)}, V_n^{(i)})_{i=1}^N$.
2. Set

$$\Delta_\ell(\phi) := \sum_{i=1}^N V_n^{(i)} \left(\overline{w}_\ell(\check{X}_{0:n}^{(i)}) \phi(\check{X}_{0:n}^{(\ell,i)}) - \underline{w}_\ell(\check{X}_{0:n}^{(i)}) \phi(\check{X}_{0:n}^{(\ell-1,i)}) \right)$$

where

$$\overline{w}_\ell(\check{X}_p) := \frac{\prod_{p=0}^n G_p^{(\theta)}(\check{X}_p^{(\ell)})}{\prod_{p=0}^n \check{G}_p^{(\theta)}(\check{X}_p)} \quad \text{and} \quad \underline{w}_\ell(\check{X}_p) := \frac{\prod_{p=0}^n G_p^{(\theta)}(\check{X}_p^{(\ell-1)})}{\prod_{p=0}^n \check{G}_p^{(\theta)}(\check{X}_p)}.$$

Then

$$\mathbb{E}[\Delta_\ell(\phi)]$$

$$\begin{aligned} &= \int \phi(\check{x}_{0:n}^{(\ell)}) \left(\prod_{p=0}^n G_p(\check{x}_p^{(\ell)}) \right) \eta_0^{(\theta)} \prod_{p=1}^n \check{M}_p(\check{X}_{p-1}, d\check{X}_p) - \int \text{'}(\ell-1)\text{'-version'} \\ &= p_u^{(\theta,\ell)}(\phi) - p_u^{(\theta,\ell-1)}(\phi). \end{aligned}$$

Debiased MLMC

McLeish (2011), Rhee and Glynn (2015), also cf. Vihola (2018).

We use single-term debiased MLMC estimator, i.e.

We randomise the running level of the Δ PF, i.e.

$$\Delta_\ell(\phi) \leftrightarrow p_L^{-1} \Delta_L(\phi)$$

That is,

- $(p_\ell)_{\ell \in \mathbb{N}}$ probability on \mathbb{N} with $p_\ell > 0$ for all ℓ .
- Let $L \sim (p_\ell)$. Then if $\text{var}(\Delta_L) < \infty$,

$$\mathbb{E} \left[\frac{1}{p_L} \Delta_L(\phi) \right] = p_u^{(\theta, \infty)}(\phi) - p_u^{(\theta, 0)}(\phi).$$

\implies We can target $p_u^{(\theta, \infty)}(\phi)$ by using

$$\bar{\Delta}_L^{(\theta)}(\phi) := p_L^{-1} \Delta_L(\phi) + \hat{p}_u^{(\theta, 0)}(\phi),$$

where the term $\hat{p}_u^{(\theta, 0)}(\phi) := \sum_{i=1}^N V_n^{(i)} \phi(X_{0:n}^{(\theta, 0, i)})$ is simply formed from output of basic PF run for zeroth level model $(M_p^{(\theta, 0)}, G_p^{(\theta)})$.

Unbiased joint inference

- The above implies unbiased (latent) inference over $p^{(\theta, \infty)}(x_{0:n})$.
- Recall: we want, more generally, unbiased joint inference over

$$\pi^{(\infty)}(\theta, x_{0:n}) \propto \text{pr}(\theta) p_u^{(\theta)}(x_{0:n}) = \text{pr}(\theta) L^{(\infty)}(\theta) p^{(\theta, \infty)}(x_{0:n}).$$

→ we use an IS type correction of approximate MCMC, as suggested in (Vihola, Helske and F, “Importance sampling type estimators...” *arXiv* 2016): with $f : \Theta \times \mathbf{X}^{n+1} \rightarrow \mathbb{R}$, $\epsilon \geq 0$ arbitrarily chosen,

(Phase 1) PMMH type chain $(\Theta_k, X_{0:n,k}^{(\Theta_k, 0, i)})_{k \geq 1}^{i \in 1:N}$, with likelihood type estimates $(V_{n,k}^* + \epsilon)_{k \geq 1}$, targeting $\text{pr}(\theta)(\hat{p}_u^{(\theta, 0)}(x_{0:n}) + \epsilon)$.

(Phase 2) IS type correction based on debiased MLMC: $L_k \sim (p_\ell)$ and

$\xi_k(\phi) := \frac{\bar{\Delta}_{L_{k,k}}^{(\Theta_k)}(\phi)}{(V_{n,k}^* + \epsilon)}$ for all $k \in 1:m$. The resulting estimator is

$$E_m^{IS}(f) = \frac{\sum_{k=1}^m \xi_k(f^{(\Theta_k)})}{\sum_{k=1}^m \xi_k(1)} \xrightarrow{m \rightarrow \infty} \pi^{(\infty)}(f),$$

with $f^{(\theta)}(x_{0:n}) := f(\theta, x_{0:n})$; consistency guaranteed if $\epsilon > 0$, PMMH ψ -irreducible, 1 and $f \in L^2(\pi^{(\infty)})$, and $\text{pr}(p_L^{-1} \Delta_L(\phi)) < \infty$ for $\phi \in \{1, f^{(\cdot)}\}$.

Variance bound for the Δ PF

...suffices for the last condition to show uniform boundedness in θ of $s_\phi(\theta) := \sum_{\ell \geq 1} \frac{\mathbb{E}[\Delta_\ell^2(\phi)]}{\rho_\ell}$. \implies we need a decay of Δ PF variance.

Theorem

Under standard conditions on the

- *diffusion (i.e. ellipticity, Lipschitz, bounded moments), and*
- *HMM/Feynman-Kac model (i.e. upper and lower bounded potentials, Lipschitz potentials and dynamics),*

for a function $\phi : \mathbf{X}^{n+1} \rightarrow \mathbb{R}$, bounded and Lipschitz, there is a constant $C = C(\phi, n)$ not depending on N , ℓ or θ , such that

$$\text{var}(\Delta_\ell(\phi)) \leq C \frac{2^{-\beta\ell}}{N}$$

with $\beta = 1$ (Euler) or $\beta = 2$ (Milstein). Moreover,

$$\mathbb{E}[(\Delta_\ell(\phi))^2] \leq C \left(\frac{2^{-\beta\ell}}{N} + 2^{-2\ell} \right).$$

Debiased MLMC cost and optimal allocations

How to choose (p_ℓ) ? Answer more involved if consider computational costs too. We follow Glynn and Whitt (1992), Rhee and Glynn (2015).

\rightsquigarrow Cost to run IS- Δ PF algorithm with m chain iterations:

$$\mathcal{C}(m) = \sum_{k=1}^m \tau_{\Theta_k, L_k}$$

Assume $\{\tau_{\Theta_k, L_k}\}_{k \geq 1}$ \mathbb{R}_+ -random variables, conditionally independent given $\{\Theta_k\}$, satisfying for some $\gamma > 0$ (with constant $C > 0$ like before)

$$\mathbb{E}[\tau_{\Theta_k, L_k} | \Theta_k = \theta, L_k = \ell] \leq C 2^{\gamma \ell}.$$

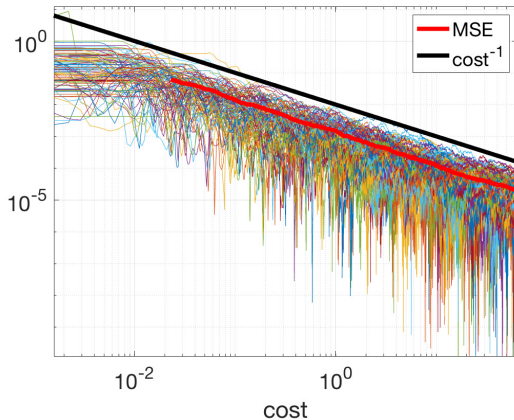
Recommended allocations for particles N_ℓ and probability (p_ℓ) :

- ($1 < \beta \leq 2$, e.g. Milstein $\beta = 2$) Use $(N_\ell, p_\ell) \propto (1, 2^{-r\ell})$ for some $r \in (\gamma, \beta)$.
 - \rightarrow canonical \sqrt{m} -convergence rate.
 - \rightarrow e.g. with $(\beta, \gamma) = (2, 1)$ (typical 1D Milstein), use $p_\ell \propto 2^{-1.5\ell}$.
- ($\beta = 1$, Euler) for $\rho \in [0, 1]$, use $N_\ell \propto 2^{\rho\ell}$ and $p_\ell \propto 2^{-(1+\rho)\ell}$.
 - \rightarrow Complexity $O(\epsilon^{-2}(\log \epsilon)^{2+\delta})$, $\delta > 0$ arbitrary.
 - \rightarrow e.g. $(N_\ell, p_\ell) \propto (1, 2^{-\ell})$ or $\propto (2^\ell, 2^{-2\ell})$.

Ornstein-Uhlenbeck process (with Milstein)

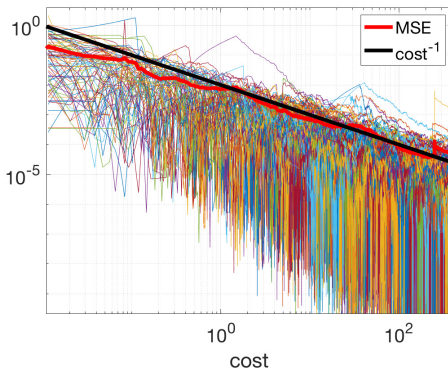
$$dX_t = \theta_1 X_t dt + \theta_2 dW_t$$

$$Y_p = \mathcal{N}(X_p, 1), \quad p = 1, \dots, n = 5.$$



Drift-alternating geometric Brownian motion (with Euler)

$$dX_{t+p} = \begin{cases} \theta^2 X_{t+p} dt + \theta X_{t+p} dW_{t+p}, & \text{if } p \text{ is even,} \\ \theta X_{t+p} dW_{t+p}, & \text{else,} \end{cases} \quad \text{for } t \in (0, 1),$$
$$Y_p \sim \mathcal{N}(\log(X_p), 1) \quad p = 1, \dots, n = 5.$$



Conclusion and further work

The IS algorithm for HMM diffusions:

- more broadly applicable, relying on Euler type approximations
- can provide unbiased/(asymptotically) exact inference
- efficient, achieving debiased MLMC complexity but in joint inference setting
- parallelisable (other IS efficiency enhancements possible)
- straightforward and easy to implement, and
- does not require tailoured solutions

A few ideas for possible investigations:

- extension to Lévy jump-diffusions, as in (Jasra, Law, Osei 2018)
- use of other approximate MCMC besides PMMH
- applying IS-debiasing technique outside diffusion context
- further efficiency considerations in practical situations and with limited computational resources, considering tail behaviour
- further stability and optimisation results for Δ PF and IS algorithm
- comparison of benefit of IS-debiasing with existing algorithms

Short literature list



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