

Equivalence of Stochastic and Deterministic Mechanisms

Yi-Chun Chen (NUS) Wei He (CUHK) Jiangtao Li (UNSW)
Yeneng Sun (NUS)

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Optimal Auction Design (*Myerson (1981)*)

- The optimal auction is **deterministic** in Myerson's setting.

Multidimensional Screening

- *McAfee and McMillan (1988)*
 - The optimality of deterministic mechanisms generalizes to multi-dimensional environments?
- This has been proved wrong with **one agent**; see, for example,
 - *Thanassoulis (2004)*
 - *Manelli and Vincent (2006, 2007)*
 - *Hart and Reny (2015)*
 - *Rochet and Thanassoulis (2015)*

In This Paper

We show

the optimality of deterministic mechanisms

in remarkably general environments with [multiple agents](#).

Preview of Result

General social choice environment that has multiple agents, a finite set of alternatives, and independent and dispersed information

- For any BIC mechanism, there exists a deterministic mechanism that
 - i) BIC;
 - ii) the same interim expected allocation probabilities for all agents;
 - iii) the same interim expected utilities for all agents;
 - iv) the same ex ante social surplus.
- In environments with monetary transfers, the deterministic mechanism also guarantees
 - v) the same ex post transfers;
 - vi) the same expected revenue.

Preview of Result

- Besides the standard social choice environments with linear utilities and independent, one-dimensional, private types,
 - a richer class of utility functions
 - multi-dimensional types
 - interdependent valuations
 - where monetary transfers are not feasible
- Example, *Jehiel and Moldovanu (2001)*.

The Optimality of Deterministic Mechanism

- Sharp contrast with the results in the screening literature.
- This is also surprising in view of the extant literature that studies the benefit of randomness (with multiple agents).
 - *Chawla, Malec, and Sivan (2015)* establish a constant factor upper bound for the benefit of randomness when the agents' values are independent. In the special case of multi-unit multi-item auctions, the revenue of any randomized mechanism is at most 33.75 times the revenue of the optimal deterministic mechanism.

Deterministic Implementation of Stochastic Mechanisms

- The mechanism design literature essentially builds on the assumption that a mechanism designer can credibly commit to any outcome of a mechanism.
- Stochastic mechanism
 - A randomization device might not be available.
 - Imperfect commitment of the mechanism designer.

Deterministic Implementation of Stochastic Mechanisms

“Ensuring this verifiability is a more difficult problem than ensuring that a deterministic mechanism is enforced, because any deviation away from a given randomization can only be statistically detected once sufficiently many realizations of the contracts have been observed. . . . The enforcement of such stochastic mechanisms is thus particularly problematic.”

Laffont and Martimort (2002)

Our result \implies

any mechanism, including any optimal mechanism (in terms of efficiency or revenue), can in fact be deterministically implemented,
and thereby irons out the conceptual difficulties associated with stochastic mechanisms.

Mechanism Equivalence

- Dominant-strategy mechanisms; see
 - *Manelli and Vincent (2010)*
 - *Gershkov, Goeree, Kushnir, Moldovanu, and Shi (2013)*).
- Symmetric auctions
 - See *Deb and Pai (2017)*.
- Deterministic mechanisms
 - This paper: Our result \implies
the requirement of deterministic mechanisms is not restrictive in itself.

Notation

- $\mathcal{I} = \{1, 2, \dots, I\}, \mathcal{K} = \{1, 2, \dots, K\}$.
- $v_i \in V_i$, closed convex subset of finite dimensional Euclidean space.
- $V = V_1 \times V_2 \times \dots \times V_I$ with generic element $v = (v_1, v_2, \dots, v_I)$.
- $v_{-i} \in V_{-i} = \prod_{j \neq i} V_j$.
- λ : common prior distribution on V .
 - Types are independent
 - λ_i atomless

Mechanism

- Restrict attention to direct mechanisms characterized by $K + I$ functions, $\{q^k(v)\}_{k \in \mathcal{K}}$ and $\{t_i(v)\}_{i \in \mathcal{I}}$.
 - where $q^k(v) \geq 0$ is the probability that alternative k is implemented,
 - $t_i(v)$ is the transfer agent i makes to the mechanism designer.
- Agent i 's gross utility in alternative k is $u_i^k(v_i, v_{-i})$.

Mechanism

- Write $Q_i^k(v_i) = E_{v_{-i}}(q^k(v_i, v_{-i}))$ and $T_i(v_i) = E_{v_{-i}}(t_i(v_i, v_{-i}))$.
- Agent i 's interim expected utility is

$$\begin{aligned}
 U_i(v_i) &= \int_{V_{-i}} \left[\sum_{1 \leq k \leq K} u_i^k(v_i, v_{-i}) q^k(v_i, v_{-i}) - t_i(v_i, v_{-i}) \right] \lambda_{-i}(dv_{-i}) \\
 &= \int_{V_{-i}} \left[\sum_{1 \leq k \leq K} u_i^k(v_i, v_{-i}) q^k(v_i, v_{-i}) \right] \lambda_{-i}(dv_{-i}) - T_i(v_i)
 \end{aligned}$$

Deterministic Mechanism

Definition

A mechanism (q, t) is deterministic if for all type profiles, the mechanism implements some alternative k for sure. That is, for all $v \in V$, $q^k(v) = 1$ for some $1 \leq k \leq K$.

Mechanism Equivalence

Definition

Two mechanisms (q, t) and (\tilde{q}, \tilde{t}) are equivalent if and only if they deliver

- 1 the same interim expected allocation probabilities;
- 2 the same interim expected utilities for all agents; and
- 3 the same ex ante expected social surplus for the mechanism designer.

Illustrating Example

- A single-unit auction with two bidders.
- (v_1, v_2) uniform distributed on the square $[0, 1]^2$.
- Consider the following stochastic mechanism (q, t) , where

$$q_1(v_1, v_2) = v_1, \quad q_2(v_1, v_2) = 1 - q_1(v_1, v_2).$$

Illustrating Example

The interim expected probability of bidder 1 getting the object is

$$\int_0^1 q_1(v_1, v_2) dv_2 = \int_0^1 v_1 dv_2 = v_1$$

for all v_1 , and the interim expected probability of bidder 2 getting the object is

$$\int_0^1 q_2(v_1, v_2) dv_1 = \int_0^1 (1 - v_1) dv_1 = \frac{1}{2}$$

for all v_2 .

Illustrating Example

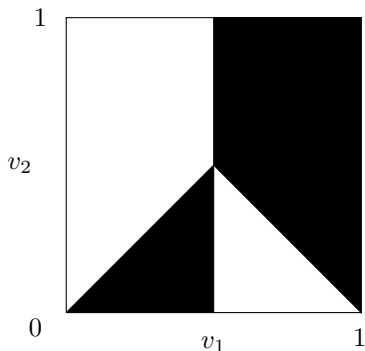


Figure: Bidder 1 is allocated the object in the shaded region, and bidder 2 is allocated the object in the unshaded region.

Interim Expected Allocation Probabilities

Theorem

For any allocation rule q , there exists a deterministic allocation rule \hat{q} such that q and \hat{q} induce the same interim expected allocation probabilities for all agents; that is, for all $i \in \mathcal{I}$ and all $v_i \in V_i$,

$$\mathbb{E}(\hat{q}|v_i) = \mathbb{E}(q|v_i). \quad (1)$$

Mutual Purification

Theorem

Let h be a function from V to \mathbb{R}_{++}^N for some positive integer N . For any allocation rule q , there exists a deterministic allocation rule \hat{q} such that for all $i \in \mathcal{I}$ and all $v_i \in V_i$,

$$\mathbb{E}(\hat{q}h_j|v_i) = \mathbb{E}(qh_j|v_i) \quad (2)$$

for all $1 \leq j \leq N$.

Separable Payoff

Definition

For all $i \in \mathcal{I}$, agent i is said to have separable payoff if for any $k \in \mathcal{K}$ and type profile $v \in V$,

$$u_i^k(v) = \sum_{1 \leq m \leq M} w_{i,m}^k(v_i) r_{i,m}^k(v_{-i}).$$

Main Result

Theorem

Suppose that for each agent $i \in \mathcal{I}$, her payoff function is separable. For any BIC mechanism (q, t) , there exists a deterministic mechanism (\hat{q}, t) such that

- (1) the same interim expected allocation probability;
- (2) the same ex ante expected social surplus;
- (3) the same interim expected utilities; and
- (4) (\hat{q}, t) is BIC.

Assumptions: Counterexamples

- The requirement of multiple agents
- Independence across agents
- Atomless distribution
- Separable payoff

Remarks

Implications:

- Ex post payment, which further implies revenue
- No monetary transfers
- Coalitional version of the result

What else:

- Symmetric mechanism
- Construction of approximately equivalent mechanisms

Conclusion

- For any BIC mechanism, there exists an equivalent deterministic mechanism
- Implications
 - The optimality of deterministic mechanisms.
 - Deterministic implementation of stochastic mechanisms.
 - The requirement of deterministic mechanisms is not restrict in itself.

Sketch of Proof: Step 1

The proof proceeds in three steps.

For any $q \in \Upsilon$, let

$$\Upsilon_q = \{q' \in \Upsilon : \mathbb{E}(q'|v_i) = \mathbb{E}(q|v_i) \text{ for all } i \in \mathcal{I} \text{ and } \lambda_i\text{-almost all } v_i \in V_i\}.$$

- 1 The set Υ_q is nonempty, convex, and weakly compact.
- 2 Υ_q admits an extreme point.

Sketch of Proof: Step 2

- 1 The aim is to show that all the extreme points of Υ_q are deterministic allocation rules.
- 2 We shall show that if an allocation q' is not deterministic, then $\exists \bar{q}, \bar{\bar{q}} \in \Upsilon_q$ such that

$$q' = \frac{1}{2}(\bar{q} + \bar{\bar{q}}).$$

$\implies \exists$ a deterministic allocation rule $\tilde{q} \in \Upsilon_q$.

Sketch of Proof: Step 2

If an allocation q' is not deterministic, then there exists

- (1) $0 < \delta < 1$;
- (2) a Borel measurable set $D \subseteq V$ with $\lambda(D) > 0$; and
- (3) indices j_1, j_2

such that

$$\delta \leq q'^{j_1}(v), q'^{j_2}(v) \leq 1 - \delta$$

for any $v \in D$.

Sketch of Proof: Step 2

- ① Consider the following system of equations where $\alpha \in L_\infty(D, \mathbb{R})$ are the unknown:

$$\int_{D_{-i}(v_i)} \alpha(v_i, v_{-i}) \lambda_{-i}(dv_{-i}) = 0. \quad (3)$$

for all $i \in \mathcal{I}$ and $v_i \in D_i$, where $D_{-i}(v_i) = \{v_{-i} : (v_i, v_{-i}) \in D\}$.

- ② λ_i is atomless for all $i \in \mathcal{I} \implies$ a nontrivial bounded solution α with $|\alpha| \leq \delta$.
- ③ Since α is defined on D , we extend the domain of α to V by setting $\alpha(v) = 0$ whenever $v \notin D$.

Construct \bar{q} and $\bar{\bar{q}}$ as follows: for all $v \in V$,

$$\begin{aligned} \bar{q}(v) &= q'(v) + \alpha(v)(e_{j_1} - e_{j_2}); \\ \bar{\bar{q}}(v) &= q'(v) + \alpha(v)(e_{j_2} - e_{j_1}). \end{aligned}$$

where e_{j_1} and e_{j_2} are the standard basis vectors.

Sketch of Proof: Step 3

- 1 Step (1) and Step (2) together imply that there exists $\tilde{q} \in \Upsilon_q$ that is deterministic at λ -almost all $v \in V$. Note that \tilde{q} is not necessarily deterministic at all $v \in V$.
- 2 Furthermore, such \tilde{q} induces the same interim expected allocation probabilities for all $i \in \mathcal{I}$ and λ -almost all $v_i \in V_i$, but not for all $v_i \in V_i$.
- 3 In this step, we construct a deterministic allocation rule \hat{q} such that

$$\mathbb{E}(q'|v_i) = \mathbb{E}(q|v_i)$$

for all $i \in \mathcal{I}$ and $v_i \in V_i$, by modifying \tilde{q} on sets of measure zero.