

Global weak solutions to a three-dimensional compressible non-Newtonian fluid with vacuum

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outline

- Models
- Motivations
- Main results
- Key points of Proofs

The equations of a compressible viscous barotropic fluid in $(x, t) \in \Omega \times \mathbb{R}^+$ have the following form

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) = \operatorname{div}(\mathbb{P}) + \rho f. \end{cases} \quad (1)$$

ρ -density; $u = (u_1, u_2, u_3)$ -velocity; \mathbb{P} -the stress tensor; f -the vector of external mass forces; the operators div and ∇ act with respect to the space variables x .

The initial data is given by

$$(\rho, \rho u)|_{t=0} = (\rho_0, m_0)(x), \quad x \in \Omega,$$

and the no-slip boundary condition on the velocity

$$u|_{\partial\Omega} = 0.$$

The system (1) must be closed by some constitutive equation for the stresses \mathbb{P} . Taking the Stokes axioms for the (only) criterion of its "physical validity," we restrict ourselves to constitutive relations of the following form

$$\mathbb{P} = \sum_{k=0}^2 \alpha_k(\rho, \operatorname{div}u, |\mathbb{D}u|^2) \mathbb{D}^k u. \quad (2)$$

$\mathbb{D}u$ -the deformation velocity tensor with components

$$D_{ij}u = \frac{1}{2}(\partial_j u_i + \partial_i u_j);$$

$$|\mathbb{D}u|^2 \equiv \mathbb{D}u : \mathbb{D}u = \sum_{i,j=1}^3 (D_{i,j}u)^2.$$

One particular case of equation (3)

$$\mathbb{P} = -p(\rho) + \lambda(|\operatorname{div}u|^2)\operatorname{div}u\mathbb{I} + 2\mu(|\mathbb{D}u|^2)\mathbb{D}u \quad (3)$$

which is a natural generalization of the constitutive relation in the classical fluid model.

The incompressible non-Newtonian fluids

$$\begin{cases} \rho_t + \operatorname{div}(\rho u) = 0, \\ (\rho u)_t + \operatorname{div}(\rho u \otimes u) - \operatorname{div}(\Gamma) + \nabla P = \rho f, \\ \operatorname{div} u = 0 \end{cases}$$

where Γ denotes the viscous stress tensor and

$$\Gamma_{ij} = (\mu_0 + \mu_1 |\mathbb{D}u|)^{r-2} \mathbb{D}_{i,j}u$$

with $\mu_0 > 0, \mu_1 > 0$ are constants.

This form of Γ is proposed by O.A. Ladyzhenskaya 1970.

The incompressible non-Newtonian fluids

—**Existence of weak solutions**

Ladyzhenskaya, Lions, Nečas, Zhikov, Kaniel, Frehse, Málek,
Steinhauer, Boling Guo.....

—**The global attractor**

Boling Guo, Guoguang Lin, Yadong Shang, Caidi Zhao, Yongsheng
Li,.....

The compressible non-Newtonian fluids

$$\begin{cases} \rho_t + \operatorname{div}(\rho u) = 0, \\ (\rho u)_t + \operatorname{div}(\rho u \otimes u) - \operatorname{div}(\Gamma) + \nabla P = \rho f. \end{cases}$$

where Γ denotes the viscous stress tensor and

$$\Gamma_{ij} = (\mu_0 + \mu_1 |\mathbb{D}u|)^{r-2} \mathbb{D}_{i,j}u$$

with $\mu_0 \geq 0, \mu_1 > 0$ are constants.

These models are called :

Newtonian, for $\mu_0 > 0, \mu_1 = 0$;

Rabinowitsch, for $\mu_0, \mu_1 > 0, r = 4$;

Eills, for $\mu_0, \mu_1 > 0, r > 2$;

Ostwald-de Waele, for $\mu_0 = 0, \mu_1 > 0, r > 4$;

Bingham, for $\mu_0, \mu_1 > 0, r = 1$;

For $\mu_0 = 0$, if $r < 2$, it is a pseudo-plastic fluid; if $r > 2$, it is a dilant fluid;

In the view of physics:

$1 < r < 2$: shear thinning fluid

$r > 2$: shear thickening fluid.

◇ **One-dimension**

—Local existence of strong/classical solution

- Hongjun Yuan and his team, Qin Yumin, Guo Zhenhua, Fang Li, Wang Yuxin.....

—Asymptotic stability/Large-time behavior of solution

- Shi-Wang-Zhang (2014): Asymptotic stability
- Guo-Fang (2016): Zero dissipation limit to rarefaction wave with vacuum
- Guo-Dong-Liu (2019): Large-time behavior of solution to an inflow problem on the half space
- Guo-Su-Liu: The existence and limit behavior of the shock layer for 1D steady compressible non-Newtonian fluids
- other results

◇ **Multi-dimension**

—Existence of weak solution

Feireisl, Liao and Málek, Zhikov and Pastukhova, Mamontov,

Feireisl-Liao-Málek considered the following compressible non-Newtonian fluid in $(x, t) \in \Omega \times \mathbb{R}_+$,

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla p(\rho) \\ \quad = \operatorname{div}(2\mu_0(1 + |\mathbb{D}^d u|^2)^{\frac{r-2}{2}} \mathbb{D}^d u + \eta(\operatorname{div} u) \operatorname{div} u \mathbb{I}) \end{cases} \quad (4)$$

where i) $\mathbb{D}^d u = \mathbb{D}u - \frac{1}{3}(\operatorname{tr} \mathbb{D}u) \mathbb{I}$, $\mu_0 > 0$ is a constant, $r \in [\frac{11}{5}, +\infty)$;
 ii) the bulk viscosity coefficient η is a continuous function of $\operatorname{div} u$, $\eta(z) : (-\frac{1}{b}, \frac{1}{b}) \rightarrow [0, +\infty)$ such that there is a convex potential $\Lambda : \mathbb{R} \rightarrow [0, \infty]$

$$\begin{cases} \Lambda(0) = 0, & \Lambda'(z) = z\eta(z), \\ \Lambda(z) \rightarrow \infty & \text{if } z \rightarrow \pm \frac{1}{b}, \\ \Lambda(z) = \infty & \text{if } |z| \geq \frac{1}{b}; \end{cases}$$

iii) the pressure $p = p(\rho)$ and the Helmholtz free energy $\psi = \psi(\rho)$ satisfy

$$p = \rho^2 \psi'(\rho), \quad p \in C[0, \infty) \cap C^1(0, +\infty), \quad p(0) = 0, \quad p'(\rho) > 0 \text{ for } \rho > 0.$$

The definition of weak solution in the work Feireisl-Liao-Málek

A pair of functions (ρ, u) is said to be a weak solution to the problem (4) on $(0, T)$ for any fixed $T > 0$ if the following conditions hold:

- $\rho \in C([0, T]; L^1(\Omega)) \cap L^\infty(\Omega \times (0, T))$,
 $u \in L^r(0, T; W_0^{1,r}(\Omega))$, $\eta(|\operatorname{div}u|)|\operatorname{div}u|^2 \in L^1(\Omega \times (0, T))$;
- The equation of continuity in (4) is satisfied in $\mathcal{D}'(\Omega \times (0, T))$;
- The following weak formulation of the momentum equation

$$\begin{aligned} & \left[\frac{1}{2} \int_{\Omega} \rho |u|^2 dx \right]_0^\tau - \left[\int_{\Omega} \rho u \cdot \varphi dx \right]_0^\tau + \int_0^\tau \int_{\Omega} [\rho u \cdot \partial_t \varphi + \rho u \otimes u : \nabla \varphi] dx dt \\ & + \int_0^\tau \int_{\Omega} |\mathbb{D}u|^{r-1} \mathbb{D}u : \mathbb{D}(u - \varphi) dx dt + \int_0^\tau \int_{\Omega} p(\rho) \operatorname{div}(\varphi - u) dx dt \\ & \leq \int_0^\tau \int_{\Omega} [\Lambda(\operatorname{div}\varphi) - \Lambda(\operatorname{div}u)] dx dt \quad (\text{control the term } \eta(|\operatorname{div}u|)\operatorname{div}u) \\ & \qquad \eta(\operatorname{div}u) : \left(-\frac{1}{b}, -\frac{1}{b}\right) \rightarrow [0, +\infty) \end{aligned}$$

for any $\tau \in [0, T]$ and any test function $\varphi \in C_c^\infty(\Omega \times [0, T])$.

Feireisl-Liao-Málek (2015) showed the large-data existence result of weak solutions to the initial-boundary problem to the system (4) with nonlinear constitutive equations that guarantee that the divergence of the velocity field remains bounded, **provided the initial density is without vacuum.**

Zhikov-Pastukhova (2009) considered a compressible fluid in $(x, t) \in \Omega \times \mathbb{R}_+$, described by

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla \rho^\gamma \\ \quad = \operatorname{div}(|\mathbb{D}u|^{r-2} \mathbb{D}u + \nu |\operatorname{div}u|^{r-2} \mathbb{I}) \end{cases} \quad (5)$$

where $\nu \geq 0$ is a constant, $\gamma > 1$, $r > 1$.

The definition of weak solution in the work Zhikov and Pastukhova

A pair of functions (ρ, u) is said to be a weak solution to the problem (5) on $(0, T)$ for any fixed $T > 0$ if the following conditions hold:

(1) $\rho \in C([0, T]; L^1(\Omega)) \cap L^\infty(0, T; L^\gamma(\Omega)),$

$u \in L^r(0, T; W_0^{1,r}(\Omega)), \rho u \in L^\infty(0, T; L^1(\Omega));$

(2) The equations (5) is satisfied in $\mathcal{D}'(\Omega \times (0, T));$

(3) $\lim_{t \rightarrow 0} \rho = \rho_0$ in $L^1(\Omega),$

$$\lim_{t \rightarrow 0} \int_{\Omega} \rho u \cdot \varphi dx = \int_{\Omega} m_0 \cdot \varphi dx \quad \forall \varphi \in C_0^\infty(\Omega).$$

Zhikov and Pastukhova (2009) proved that the initial-boundary problem to the system (6) admits a weak solution such that

$$\rho u^2 \in L^{\frac{r}{r-1}}(\Omega \times (0, T)), \quad \rho^\gamma \in L^{\frac{r}{r-1}}(\Omega \times (0, T))$$

provided that $\rho_0 \in L^\gamma(\Omega)$, $\frac{m_0}{\rho_0} \in L^1(\Omega)$, $\gamma > \frac{3}{2}$, $r \geq 3$.

Mamontov (1999) considered a compressible fluid in $(x, t) \in \Omega \times \mathbb{R}_+$, described by

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) \\ \quad = \operatorname{div}(2\mu(|\mathbb{D}u|^2)\mathbb{D}u + \lambda(|\operatorname{div}u|^2)\operatorname{div}u\mathbb{I}) \end{cases} \quad (6)$$

where $\mu(s) = \exp(s^{\epsilon_0})$ ($\epsilon_0 > 0$ a constant), $\lambda(s) = \exp(\sqrt{s})$.

Mamontov showed the existence of global solutions of multidimensional equations of motion of a compressible non-Newtonian fluid in Burgers approximation (in the absence of pressure), **on the basis of the techniques of Orlicz spaces.**

Global weak solution to the multi-dimensional compressible Navier-Stokes equations for general initial data with finite energy:
—Lions (Oxford 1998), Feireisl-Novotny-Petzeltová (JMFM, 2001), Jiang-Zhang (CMP, 2001),

Question: For general initial data with finite energy, what about the existence of global weak solution to the multi-dimensional compressible non-Newtonian fluid containing vacuum for the general case $r > 1$?

Consider the initial-boundary value problem for the isentropic compressible non-Newtonian fluid with vacuum

$$\begin{cases} \partial_t \rho + \operatorname{div}_x(\rho u) = 0, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla p \\ \quad = \operatorname{div}(|\mathbb{D}u|^{r-2} \mathbb{D}u + \eta(|\operatorname{div}u|) \operatorname{div}u \mathbb{I}), \end{cases} \quad (7)$$

with the initial data

$$(\rho, \rho u)|_{t=0} = (\rho_0, m_0)(x), \quad x \in \Omega \quad (8)$$

and the no-slip boundary condition on the velocity

$$u|_{\partial\Omega} = 0. \quad (9)$$

Notice: This model can describe the motion of electrons in an electric field.

Definition of weak solution

Definition A pair of functions (ρ, u) is said to be a finite energy weak solutions to the problem (7)-(9) on $(0, T)$ for any fixed $T > 0$ if the following conditions hold:

- $\rho \geq 0$, $\rho \in C([0, T]; L^1(\Omega)) \cap L^\infty(0, T; L^\gamma(\Omega))$,
 $u \in L^r(0, T; W_0^{1,r}(\Omega))$, $\eta(|\operatorname{div} u|)|\operatorname{div} u|^2 \in L^1(\Omega \times (0, T))$;
- The equations (7) hold in $\mathcal{D}'(\Omega \times (0, T))$ and

$$\int_0^\tau \int_\Omega [\rho \partial_t \varphi + \rho u \cdot \nabla \varphi] dx dt = \left[\int_\Omega \rho \varphi dx \right]_0^\tau$$

for any $\tau \in [0, T]$ and any test function $\varphi \in C^\infty(\Omega \times [0, T])$ with $\varphi(x, 0) = \varphi(x, T) = 0$ for $x \in \Omega$;

- The functions ρ and ρu satisfy the initial conditions in the weak sense.

Remark

- Any weak solution in Definition satisfy the equations (7) hold in $\mathcal{D}'(\Omega \times (0, T))$, which is different from the definition of weak solution in the work Feireisl-Liao-Málek.
- Any weak solution in Definition satisfies the following weak formulation of the momentum equation

$$\begin{aligned} & \left[\frac{1}{2} \int_{\Omega} \rho |u|^2 dx \right]_0^{\tau} - \left[\int_{\Omega} \rho u \cdot \varphi dx \right]_0^{\tau} + \int_0^{\tau} \int_{\Omega} [\rho u \cdot \partial_t \varphi + \rho u \otimes u : \nabla \varphi] dx dt \\ & + \int_0^{\tau} \int_{\Omega} |\mathbb{D}u|^{r-1} \mathbb{D}u : \mathbb{D}(u - \varphi) dx dt + \int_0^{\tau} \int_{\Omega} p(\rho) \operatorname{div}(\varphi - u) dx dt \\ & \leq \int_0^{\tau} \int_{\Omega} [\Lambda(\operatorname{div} \varphi) - \Lambda(\operatorname{div} u)] dx dt \end{aligned}$$

for any $\tau \in [0, T]$ and any test function $\varphi \in C_c^{\infty}(\Omega \times [0, T])$, where $\Lambda'(z) = \eta(z)z$ and $\Lambda''(z) \geq 0$.

Theorem 1 Let $\Omega \subset \mathbb{R}^3$ be a bounded domain of class $C^{2+\nu}$ for some $\nu > 0$ and $\eta(z) = |z|^{q-1}$. Suppose that the following conditions hold:

- (i) the pressure $p(\rho)$ is given by $p(\rho) = \rho^\gamma$ with the adiabatic exponent $\gamma > \frac{3}{2}$;
- (ii) the initial data satisfy

$$\begin{cases} \rho_0 \in L^\gamma(\Omega), \rho_0 \geq 0 \text{ on } \Omega, \\ \frac{|m_0|^2}{\rho_0} \in L^1(\Omega); \end{cases}$$

- (iii) the positive constants r and q satisfy the case that $\frac{12}{5} \leq r < 3$ and $q > \max\{\gamma, 9\}$, or the case that $r \geq 3$ and $q > 1$.

Then, the initial-boundary value problem (7)-(9) admits a finite energy weak solution (ρ, u) on $\Omega \times (0, T)$ for any given $T > 0$.

Theorem 2 Let $\Omega \subset \mathbb{R}^3$ be a bounded domain of class $C^{2+\nu}$ for some $\nu > 0$ and $\eta(z) = |z|^{q-1}$. Suppose that the following conditions hold:

(i) the pressure $p(\rho)$ is given by

$$\begin{cases} p'(s) \geq a_1 s^{\gamma-1} \text{ for all } s > 0, & p(s) \leq a_2 s^\gamma \text{ for all } s \geq 0, \\ p \in C[0, \infty) \cap C^1(0, \infty), & p(0) = 0 \end{cases} \quad (10)$$

with the adiabatic exponent $\gamma > \frac{3}{2}$;

(ii) the initial data satisfy

$$\begin{cases} \rho_0 \in L^\gamma(\Omega), \rho_0 \geq \underline{\rho} > 0 \text{ on } \Omega, \\ \frac{|m_0|^2}{\rho_0} \in L^1(\Omega); \end{cases}$$

(iii) the positive constants p and q satisfy the case that

$\frac{11}{5} \leq r < 3$ and $q > \max\{\gamma, 9\}$, or the case that $r \geq 3$ and $q > 1$.

Then, the initial-boundary value problem (7)-(9) admits a finite energy weak solution (ρ, u) on $\Omega \times (0, T)$ for any given $T > 0$.

Remark

(i) The solution constructed in Theorem 1 -2 admits that

$$\rho^\gamma \in L^{\frac{q+1}{q}}(\Omega \times (0, T)) \quad (\text{when } \frac{12}{5} \leq r < 3 \text{ and } q > \max\{\gamma, 9\}),$$

$$\text{or } \rho^\gamma \in L^{\frac{r+1}{r}}(\Omega \times (0, T)) \quad (\text{when } r \geq 3 \text{ and } q > 1),$$

$$\operatorname{div} u \in L^{q+1}(\Omega \times (0, T)) \text{ and } \nabla u \in L^r(\Omega \times (0, T)).$$

(ii) The solution constructed in Theorem 1 and Theorem 2 will satisfy the continuity equation in the sense of re-normalized solutions.

(iii) Our results also hold for the bulk viscosity coefficient $\eta(|\operatorname{div} u|) \sim |\operatorname{div} u|^{q-1}$, where the symbol \sim refers that there exist positive constants C_1 and C_2 such that

$$C_1 |\operatorname{div} u|^{q-1} \leq \eta(|\operatorname{div} u|) \leq C_2 |\operatorname{div} u|^{q-1}$$

and $\eta(z) + z\eta'(z) > 0$ holds for any $z > 0$.

Main difficulties and the countermeasure in proof of Theorems

(1) The initial density containing vacuum and strong degeneracy of the term $\operatorname{div}(|\mathbb{D}u|^{r-2}\mathbb{D}u)$ in momentum equations

Inspired by Jiang-Zhang-2001 and Chapter 7 in Feireisl-2004, we introduce an approximate problem

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho u) = \epsilon \Delta \rho, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla(p + \delta \rho^\beta) + \epsilon \nabla u \cdot \nabla \rho \\ \quad = \operatorname{div}((\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u + \eta(|\operatorname{div}u|)\operatorname{div}u \mathbb{I}) \end{cases} \quad (11)$$

with the initial-boundary conditions

$$\begin{cases} \nabla \rho \cdot n|_{\partial\Omega} = 0, & \rho|_{t=0} = \rho_{0,\delta}, \\ u|_{\partial\Omega} = 0, & \rho u|_{t=0} = m_{0,\delta}, \end{cases} \quad (12)$$

(2) The strong nonlinearity for the pressure term $p(\rho)$ and the term $\operatorname{div}(|\mathbb{D}u|^{r-2}\mathbb{D}u)$.

The difficulty comes from the nonlinear term

$$(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}}\mathbb{D}u + \eta(|\operatorname{div}u|)\operatorname{div}u$$

in the approximate problem.

Recall that $\eta(z) = |z|^{q-1}$, $\Lambda'(z) = \eta(z)z$ and $\Lambda''(z) \geq 0$, one can deduce that

$$\overline{\eta(\operatorname{div}u)\operatorname{div}u} = \eta(\operatorname{div}u)\operatorname{div}u.$$

So we need focus on the first term of the above nonlinear term.

Sketch of Theorem 1's proof

Step 1. Limit in the Galerkin approximation

The approximate problem (11)-(12) with fixed positive parameters ϵ and δ can be solved by means of a modified Faedo-Galerkin method.

Step 2. The vanishing limits of the artificial viscosity $\epsilon \rightarrow 0$.

The common difficulty in the Step 1 and the Step 2 :

The nonlinear term

$$(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u$$

in the approximate problem.

The key tool to deal with the nonlinear term above

Let $A_\epsilon(x, \xi)$ and $A(x, \xi)$ be Carathéodory vector functions.

$A_\epsilon(x, \xi), A(x, \xi) : \Omega \times \mathbb{R}^d \rightarrow \mathbb{R}^d$, where Ω is a bounded domains in \mathbb{R}^d . The Carathéodory property means continuity with respect to $\xi \in \mathbb{R}^d$ for a.e. $x \in \Omega$ and measurability with respect to x for any ξ . These vector functions are assumed to satisfy the minimal monotonicity and convergence conditions

$$(A_\epsilon(x, \xi) - A_\epsilon(x, \eta)) \cdot (\xi - \eta) \geq 0, \quad A_\epsilon(x, 0) \equiv 0$$
$$|A_\epsilon(x, \xi)| \leq c_0(|\xi|) < \infty, \quad \lim_{\epsilon \rightarrow 0} A_\epsilon(x, \xi) = A(x, \xi)$$

for a.e. $x \in \Omega$ and any $\xi \in \mathbb{R}^d$.

Lemma

Suppose that $v_\epsilon \rightharpoonup v$, $A_\epsilon(x, v_\epsilon) \rightharpoonup z$ in $L^1(\Omega)$. Let $K \subset \Omega$ be a measurable set such that $z \cdot v \in L^1(K)$. Then

$$\liminf_{\epsilon \rightarrow 0} \int_K A_\epsilon(x, v_\epsilon) \cdot v_\epsilon dx \geq \int_K z \cdot v dx$$

and, in the case of equality,

$$z|_K = A|_K, \quad A = A(x, v).$$

We employ the following weak formulation of the momentum equation in the approximate problem

$$\begin{aligned}
 & \left[\frac{1}{2} \int_{\Omega} \rho |u|^2 dx \right] \Big|_0^{\tau} - \left[\int_{\Omega} \rho u \cdot \varphi dx \right] \Big|_0^{\tau} \\
 & + \int_0^{\tau} \int_{\Omega} (\rho u \cdot \partial_t \varphi + \rho u \otimes u : \nabla \varphi) dx dt \\
 & + \int_0^{\tau} \int_{\Omega} (p(\rho) + \delta \rho^{\beta})(\operatorname{div} \varphi - \operatorname{div} u) dx dt - \int_0^{\tau} \int_{\Omega} \epsilon \nabla \rho \cdot \nabla u \cdot \varphi dx dt \\
 & + \int_0^{\tau} \int_{\Omega} \left(\overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} |\mathbb{D}u|^2} - \overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u : \mathbb{D}\varphi} \right) dx dt \\
 & \leq \int_0^{\tau} \int_{\Omega} [\Lambda(\operatorname{div} \varphi) - \Lambda(\operatorname{div} u)] dx dt \text{ for a.e. } \tau \in [0, T] \tag{13}
 \end{aligned}$$

The family of regularized Kernels

$$\eta_h(t) := \frac{1}{h} \mathbb{I}_{[-h,0]}(t) \text{ and } \eta_{-h}(t) := \frac{1}{h} \mathbb{I}_{[0,h]}(t) (h > 0),$$

together with the cut-off functions

$$\xi_\sigma \in C_c^\infty(0, \tau), \quad 0 \leq \xi \leq 1, \quad \xi_\sigma(t) = 1$$

whenever $t \in [\sigma, \tau - \sigma]$, $\sigma > 0$. Noticing that

$\eta_h * u = \frac{1}{h} \int_t^{t+h} u ds \in W^{1,r}(0, T; W_0^{1,r}(\Omega))$, we can take the quantities

$$\varphi_{h,\sigma} = \xi_\sigma \eta_{-h} * \eta_h * (\xi_\sigma u) \quad (\sigma, h > 0)$$

as test functions in (13).

By careful calculation, we can arrive at

$$\int_0^\tau \int_\Omega \left(\overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} |\mathbb{D}u|^2} - \overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u : \mathbb{D}u} \right) dxdt \leq 0,$$

based on the fact that

$$\begin{aligned} \lim_{\sigma \rightarrow 0} \lim_{h \rightarrow 0} \int_0^\tau \int_\Omega (\Lambda(\operatorname{div} \varphi_{h,\sigma}) - \Lambda(\operatorname{div} u)) dxdt &= 0, \\ \left[\int_\Omega \rho u \cdot \varphi_{h,\sigma} dx \right]_0^\tau &= 0 \text{ (for all } \sigma, h > 0), \end{aligned}$$

So together with Fatou's lemma,

$$\lim_{\sigma \rightarrow 0} \lim_{h \rightarrow 0} \int_0^\tau \int_{\Omega} \left(\overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} |\mathbb{D}u|^2} - \overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u : \mathbb{D}\varphi_{h,\sigma}} \right) dxdt \geq 0.$$

it ensures that

$$\overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u} = (\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u$$

and

$$\overline{(\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} |\mathbb{D}u|^2} = (\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} |\mathbb{D}u|^2.$$

Step 3. The artificial pressure coefficient $\delta \rightarrow 0$.

3.1 The density estimates.

Lemma

There exists a positive constant C , independence of δ , such that

$$\int_0^T \int_{\Omega} (\rho_{\delta}^{\frac{q+1}{q}\gamma} + \delta \rho_{\delta}^{\beta+\frac{\gamma}{q}}) dx dt \leq C,$$

holds for the case that $\frac{11}{5} \leq r < 3$ and $q > \max\{\gamma, 9\}$, and

$$\int_0^T \int_{\Omega} (\rho_{\delta}^{\frac{r}{r-1}\gamma} + \delta \rho_{\delta}^{\beta+\frac{\gamma}{r-1}}) dx dt \leq C,$$

holds for the case that $r \geq 3$ and $q > 1$.

3.2 The amplitude of oscillations.

For the cut-off operators introduced in Feireisl-2004 and Jiang-Zhang-2001, we consider a family of functions

$$T_k(z) = kT\left(\frac{z}{k}\right) \text{ for } z \in \mathbb{R}, k = 1, 2, \dots \quad (14)$$

where $T \in C^\infty(\mathbb{R})$ is chosen so that

$$T(z) = z \text{ for } z \leq 1, T(z) = 2 \text{ for } z \geq 3, T \text{ concave.}$$

Lemma

There exists a positive constant C , independence of k , such that

$$\limsup_{\delta \rightarrow 0} \|T_k(\rho_\delta) - T_k(\rho)\|_{L^{\frac{q+1}{q}\gamma}(\Omega \times (0, T))} \leq C$$

holds for the case that $\frac{12}{5} \leq r < 3$ and $q > \max\{\gamma, 9\}$,

$$\limsup_{\delta \rightarrow 0} \|T_k(\rho_\delta) - T_k(\rho)\|_{L^{\gamma+1}(\Omega \times (0, T))} \leq C$$

holds for the case that $r \geq 3$ and $q > 1$.

Remark. The limit functions ρ and u satisfy the continuity equation (4)₁ in the sense of renormalized solutions.

3.3 The momentum equation.

The first key point is to prove $\overline{\rho^\gamma} = \rho^\gamma$. The following integrability properties of the limit functions ρ and u , play an important role, which are stated as

$$\rho^\gamma \in L^{\frac{q+1}{q}}(\Omega \times (0, T)) \left(\frac{12}{5} \leq r < 3 \text{ and } q > \max\{\gamma, 9\} \right),$$

$$\text{or } \rho^\gamma \in L^{\frac{r}{r-1}}(\Omega \times (0, T)) \left(r \geq 3 \text{ and } q > 1 \right),$$

$$\operatorname{div} u \in L^{q+1}(\Omega \times (0, T)) \text{ and } \nabla u \in L^r(\Omega \times (0, T)),$$

$$\rho u^2 \in L^{\frac{r}{r-1}}(\Omega \times (0, T)).$$

The second key equality $\overline{|\mathbb{D}u|^r} = |\mathbb{D}u|^r$ is obtained by applying the technique in the following inequality

$$\begin{aligned} & \left[\frac{1}{2} \int_{\Omega} \rho |u|^2 dx \right] \Big|_0^{\tau} - \left[\int_{\Omega} \rho u \cdot \varphi dx \right] \Big|_0^{\tau} \\ & + \int_0^{\tau} \int_{\Omega} (\rho u \cdot \partial_t \varphi + \rho u \otimes u : \nabla \varphi) dx dt \\ & + \int_0^{\tau} \int_{\Omega} \rho^\gamma (\operatorname{div} \varphi - \operatorname{div} u) dx dt + \int_0^{\tau} \int_{\Omega} \left(\overline{|\mathbb{D}u|^r} - \overline{|\mathbb{D}u|^{r-2} \mathbb{D}u} : \mathbb{D} \varphi \right) dx dt \\ & \leq \int_0^{\tau} \int_{\Omega} (\Lambda(\operatorname{div} \varphi) - \Lambda(\operatorname{div} u)) dx dt \text{ for a.e. } \tau \in [0, T] \end{aligned} \quad (15)$$

In Theorem 2, the pressure $p(\rho)$ is given by

$$\begin{cases} p'(s) \geq a_1 s^{\gamma-1} \text{ for all } s > 0, & p(s) \leq a_2 s^\gamma \text{ for all } s \geq 0, \\ p \in C[0, \infty) \cap C^1(0, \infty), & p(0) = 0 \end{cases}$$

with the adiabatic exponent $\gamma > \frac{3}{2}$; and the initial data satisfy

$$\begin{cases} \rho_0 \in L^\gamma(\Omega), \rho_0 \geq \underline{\rho} > 0 \text{ on } \Omega, \\ \frac{|m_0|^2}{\rho_0} \in L^1(\Omega). \end{cases}$$

The approximate problem is still adopted as

$$\left\{ \begin{array}{l} \partial_t \rho + \operatorname{div}(\rho u) = \epsilon \Delta \rho, \\ \partial_t(\rho u) + \operatorname{div}(\rho u \otimes u) + \nabla(p + \delta \rho^\beta) + \epsilon \nabla u \cdot \nabla \rho \\ \quad = \operatorname{div}((\delta + |\mathbb{D}u|^2)^{\frac{r-2}{2}} \mathbb{D}u + \eta(|\operatorname{div}u|)\operatorname{div}u \mathbb{I}) \end{array} \right.$$

with the initial-boundary conditions

$$\left\{ \begin{array}{l} \nabla \rho \cdot n|_{\partial\Omega} = 0, \quad \rho|_{t=0} = \rho_{0,\delta}, \\ u|_{\partial\Omega} = 0, \quad \rho u|_{t=0} = m_{0,\delta}, \end{array} \right.$$

The difference between proof of Theorem 2 and Theorem 1 is the pressure term.

The limit in the Galerkin approximation and the vanishing limits of the artificial viscosity $\epsilon \rightarrow 0$ can be settled by the similar way in proof of Theorem 1.

In the artificial pressure coefficient $\delta \rightarrow 0$, one can arrive at

$$\int_0^\tau \int_\Omega (\overline{p(\rho)} \operatorname{div} u - \overline{p(\rho) \operatorname{div} u}) dx dt \leq 0 \text{ for a.a. } \tau \in [0, T].$$

To deal with $\overline{\rho P(\rho)} - \rho P(\rho)$, the convexity of the function $zP(z)$ with $P(z) = \int_1^z \frac{p(s)}{s^2} ds$ and the initial density without vacuum play an important role.

Since the initial density is without vacuum, the convexity of the function $zP(z)$ implies that there exists a certain $\alpha > 0$ such that

$$\int_\Omega [\overline{\rho P(\rho)} - \rho P(\rho)] dx \geq \alpha \limsup_{\delta \rightarrow 0} \int_\Omega |\rho_\delta - \rho|^2 dx.$$

The constant $\alpha > 0$ in above inequality depends on the positive lower bound of the initial density This is different way to deal with the initial density being without vacuum.

Thank you for your attention!